

Arbitrary Lagrangian Euler codes for non-ideal MHD

Warwick (Physics) - **Tony Arber**, K. Bennett, T. Goffrey, C. Brady D. Barlow, A. Rees

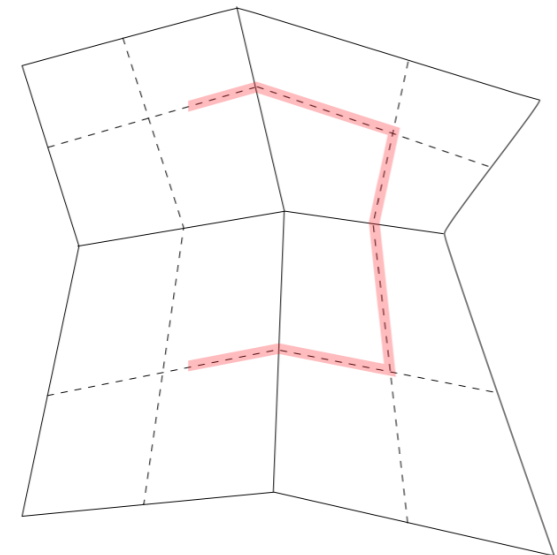
Warwick (Computer Science) - S. Jarvis

Imperial - J. Chittenden, S. Rose, R. Kingham, K. McGlinchey

York - C. Ridgers, G. Pert, M. Read

RAL - R. Scott, H. Schmidt

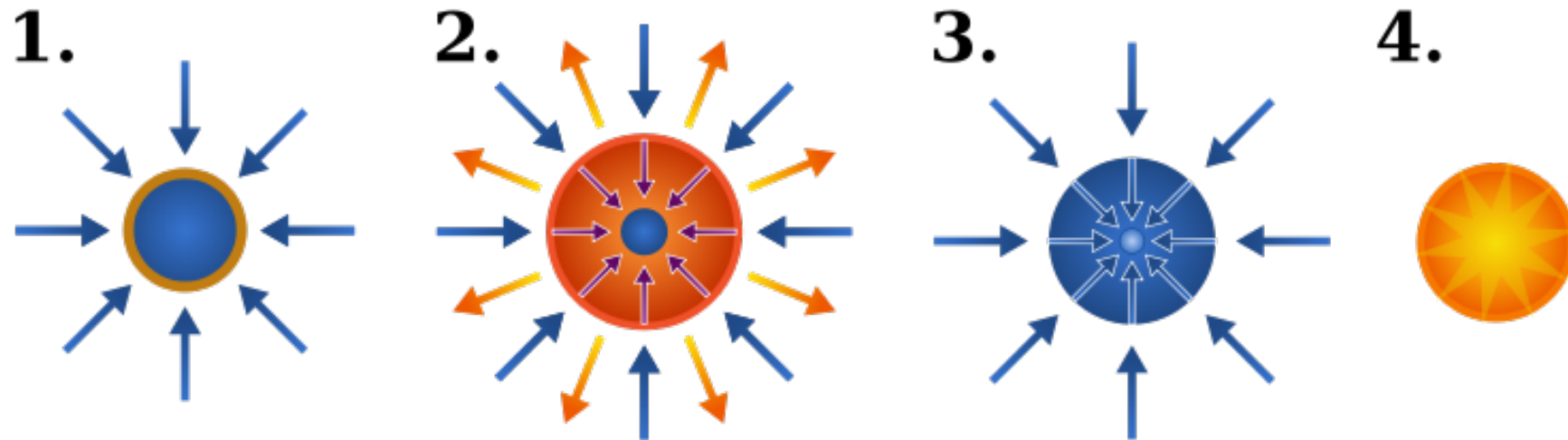
AWE - B. Williams, R. Smedley-Stevenson



Overview

- What is the problem?
- Basics of laser-driven fusion
- Why this leads to ALE schemes
- Basic ALE algorithm
- Non-ideal MHD terms
- Some examples
- Status of the code development

Laser-fusion in a nutshell



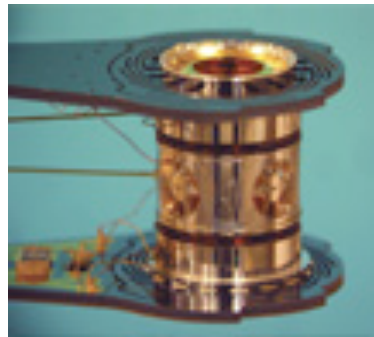
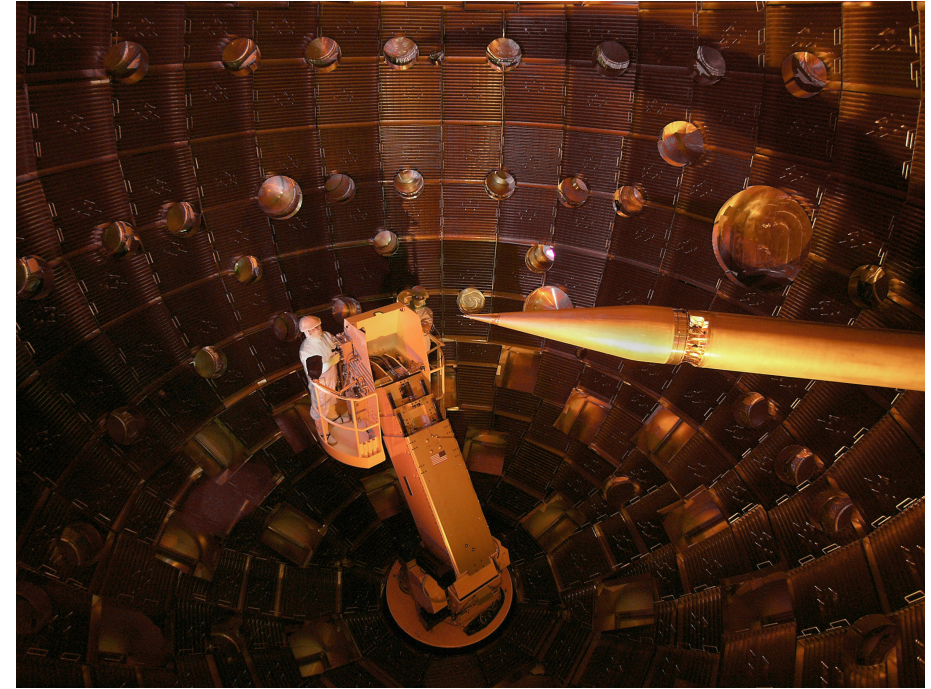
To achieve a gain of ~ 10 need...

- Compress D-T fuel to ~ 1000 solid density
- Ignite fuel at $\sim 10^7$ K
- Requires implosion speed of $\sim 350 \text{ km s}^{-1}$ (about Mach 10)
- Drive time $\sim 20 \text{ ns}$
- Laser energy $\sim 1.8 \text{ MJ}$ and peak power 500 TW ($\sim 5 \times 10^5$ Sizewell B)
- Peak ablation pressure $\sim 130 \text{ Mbar}$
- Peak ignition pressure $\sim 10^5 \text{ Mbar}$ with burn, i.e. 10^{11} atmospheric
- Acceleration $\sim 10^{13} \text{ m s}^{-2}$ about 10^{12} g

NIF was designed and built to create ignition conditions

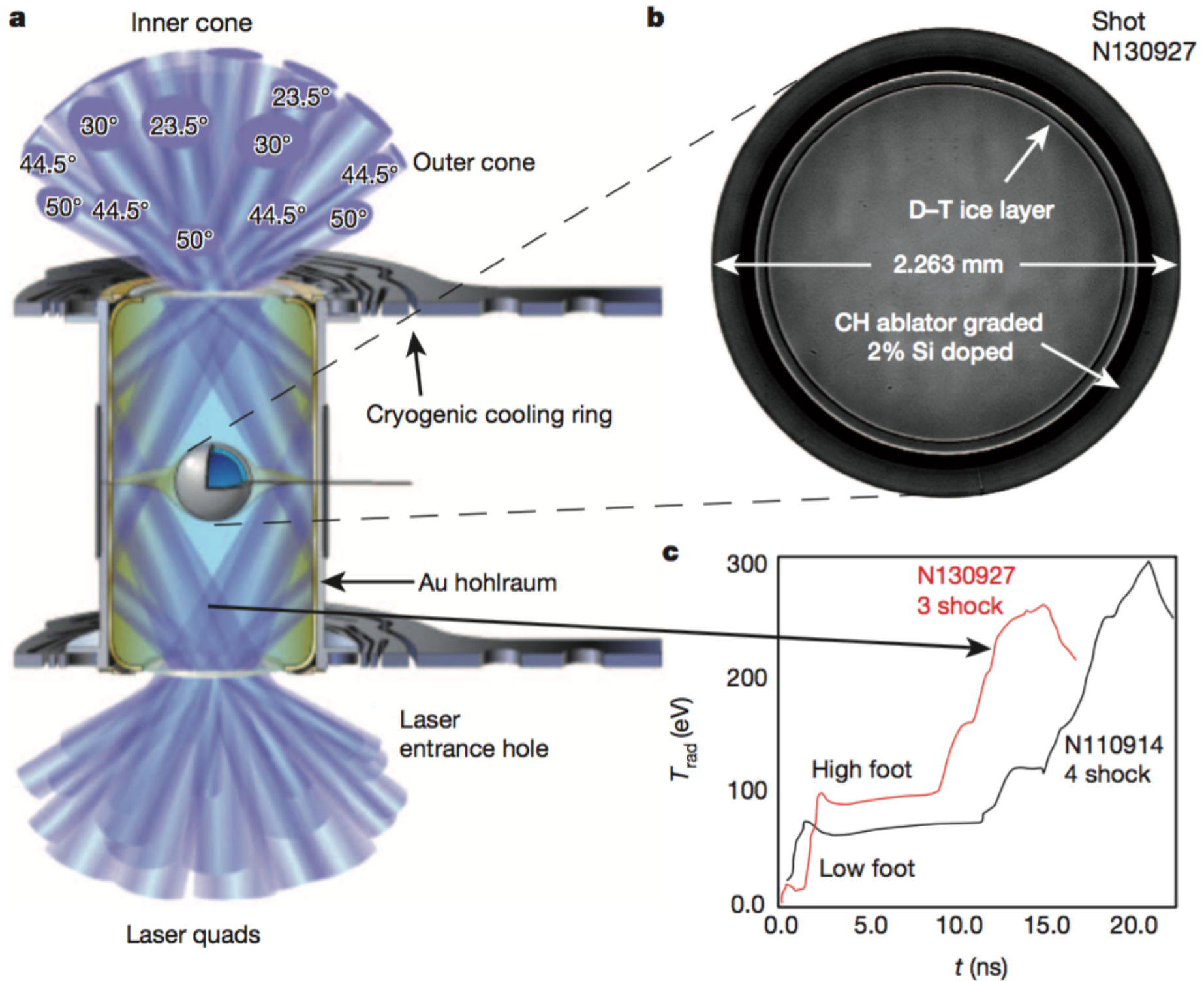
- 192 Beams
- Frequency tripled Nd glass
- Energy 1.8 MJ
- Power 500 TW
- Wavelength 351 nm

National Ignition Facility (NIF)

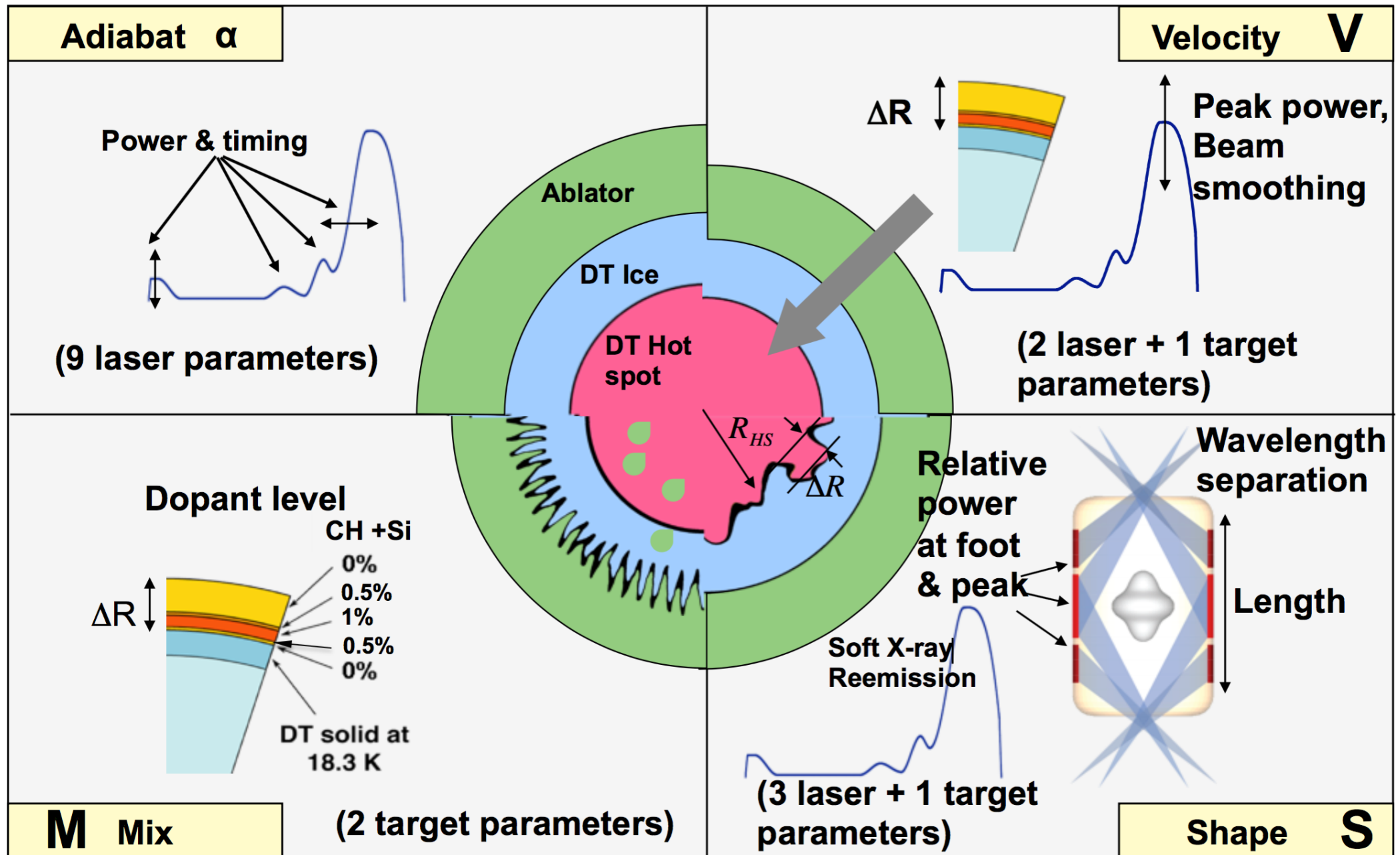


Lawrence Livermore National Laboratory (LLNL)

Few MJ laser energy to 100 MJ burn



$$\text{Fusion success} = f(a, v, m, s)$$



Code specification

A target point design must...

- Handle converging and coalescing shocks at $\sim$ Mach 10
- Handle tabulated EOS, NLTE and burn
- Preserve symmetry
- Prevent numerical mixing of materials
- Maintain accuracy for 30 x length contraction

Odin is an Arbitrary-Lagrangian-Eulerian code

- Lagrangian mesh - grid moves with fluid
- Second-order accurate with shock viscosity (Kurapetenko)
- Not in conservative form - compatible energy update (Caramana)
- Area-weighted r-z geometry for symmetry
- Include MHD as well as Euler solver
- Remap/rezone to relaxed grid if Lagrangian grid too distorted

Lagrangian Equations

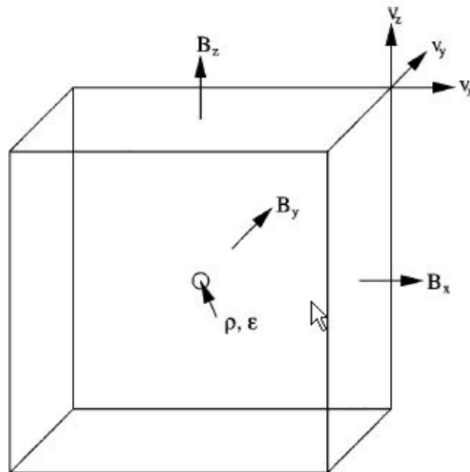
$$\frac{D\rho}{Dt} = -\rho \nabla \cdot \mathbf{v}$$

$$\frac{D\epsilon}{Dt} = -\frac{P}{\rho} \nabla \cdot \mathbf{v}$$

$$\frac{D\mathbf{v}}{Dt} = -\frac{1}{\rho} \nabla \cdot P + \frac{1}{\rho} \mathbf{j} \times \mathbf{B}$$

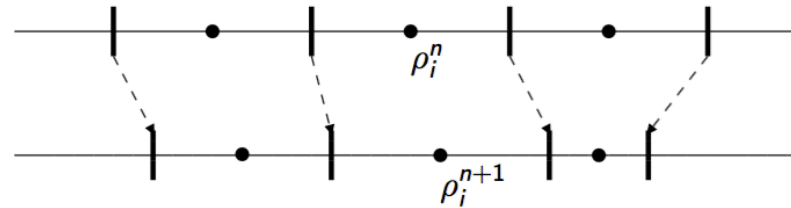
$$\frac{D}{Dt} \left(\frac{\mathbf{B}}{\rho} \right) = \frac{\mathbf{B}}{\rho} \cdot \nabla \mathbf{v}$$

$$\epsilon = \frac{P}{\rho(\gamma - 1)}$$



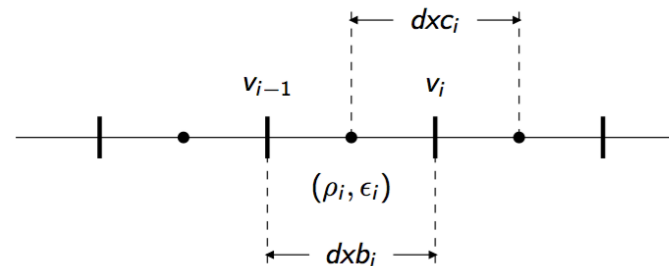
Lagrangian Grids

Lagrangian grid, i.e. $\frac{D}{Dt}$, updated variables move with the fluid.



Staggered Grid

- Variables ($\rho, \epsilon, \mathbf{v}$) not defined at the same grid location
- Define v as the velocity of cell boundaries
- ρ as cell averaged density defined at cell centre
- $\rho_i dx b_i$ is the mass in cell i



Momentum Equation

$$\int_{\Omega(t)} \rho \frac{D\vec{u}}{Dt} dV = - \int_{\Omega(t)} \nabla P dV.$$

$$M = \int_{\Omega(t)} \rho dV$$

$$\bar{f} = \frac{1}{V} \int_{\Omega(t)} f dV.$$

$$M \frac{D\tilde{\vec{u}}}{Dt} = - \int_{\partial\Omega(t)} P d\vec{S}.$$

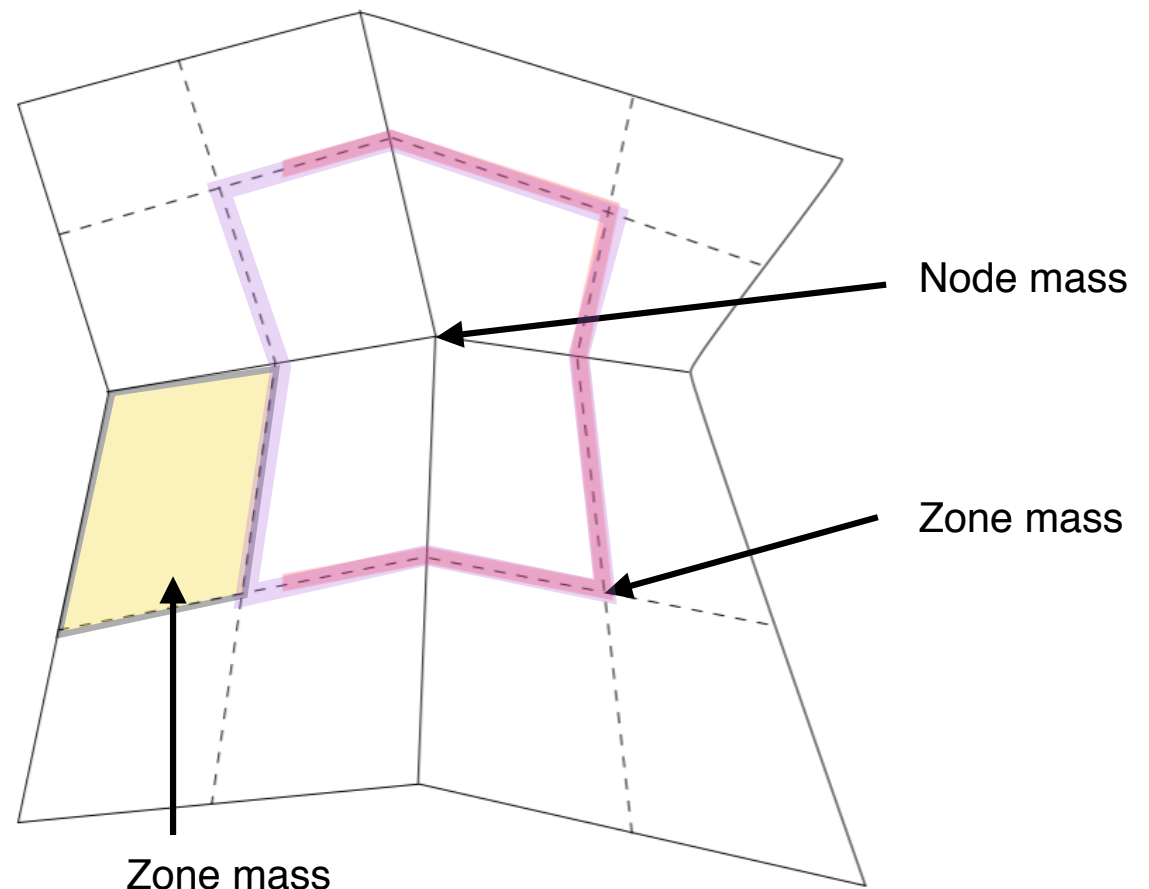
$$\frac{D}{Dt} M = 0$$

$$\tilde{f} = \frac{1}{M} \int_{\Omega(t)} f \rho dV,$$

Mass in cell/zone conserved

Momentum needs nodal mass

Assume corner masses are constant - the median mesh is Lagrangian



Compatible energy update

$$M^p \frac{Dv_x}{Dt} = \sum_{i=1}^4 f_{x,i}.$$

M^z mass in cell/zone

M^p mass in nodal volume about velocity

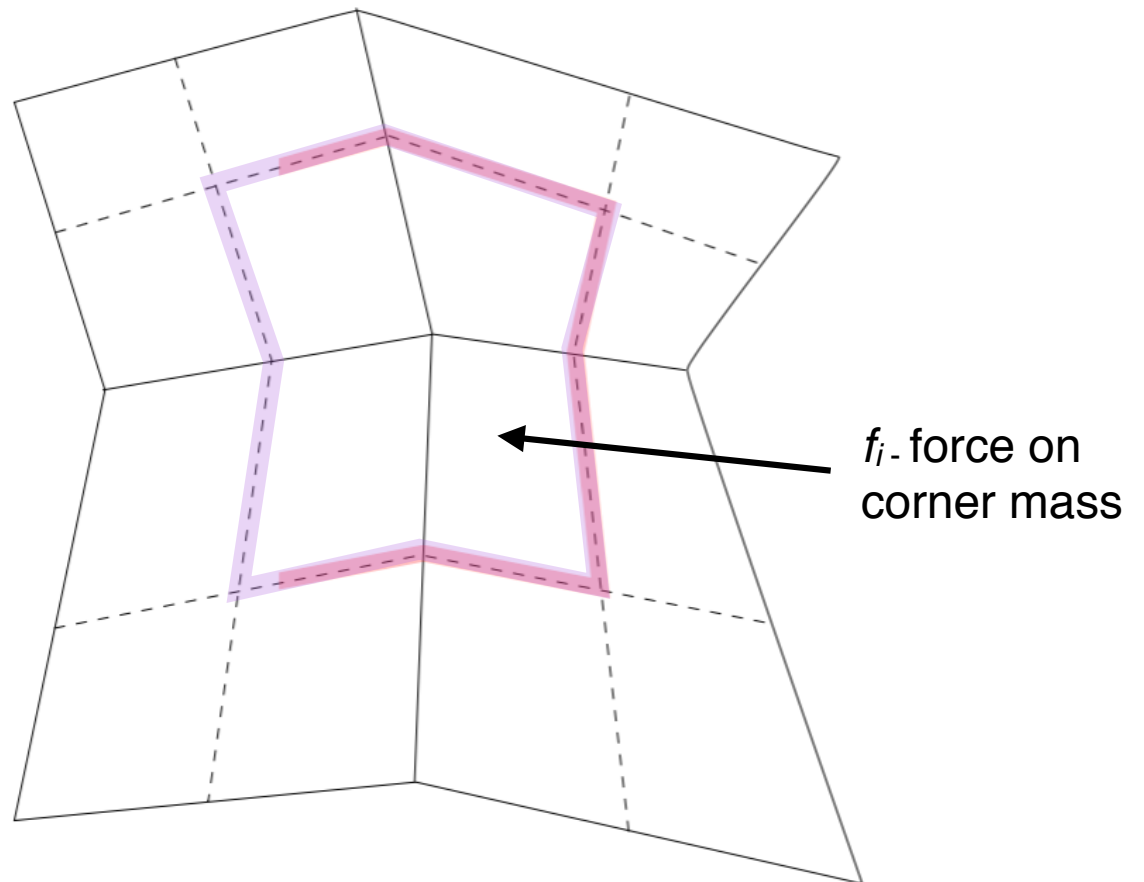
$$M^z \frac{De_i}{Dt} = - \sum_{i=1}^4 \vec{f}_i \cdot \vec{v}_i,$$

Provided same force is used in both updates energy is exactly conserved.

Requires a scheme to find nodal mass from zonal mass

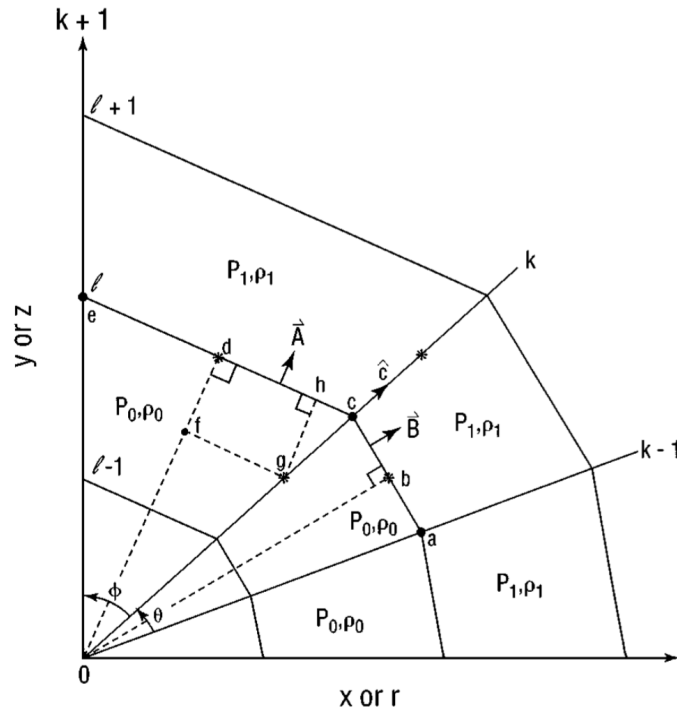
In x-y simply use areas of sub-zonal mesh

Corner mass conserved in Lagrangian step



r-z Area Weighting

Control volume averaging in r-z



$$M^p \frac{Du_p}{Dt} = - \int P d\mathbf{S} + \hat{\mathbf{r}} \int \frac{P}{r} dV$$

Radial weighting in $d\mathbf{S}$ unlikely to be balanced by volume term in code.

Approach based on this method leads to loss of symmetry

Problem removed if $\int P r dr dz \simeq r_g \int P dr dz$

$$M^p \frac{D\mathbf{u}}{Dt} = -r_g \mathbf{F}_P$$

Re-factor calculations of nodal mass from volume mass using

$$M^p = r_g \sum_z \rho_z A_z$$

Edge Viscosity

Full scheme from Caramana et al. JCP (1998)

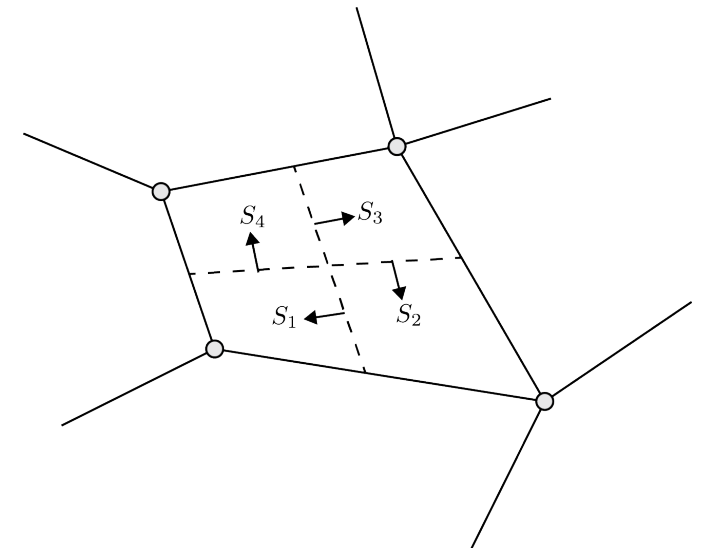
Only apply on edge compression

Limited away from shocks

$$\mathbf{f}_i = \rho_i \left\{ \frac{\gamma + 1}{4} \Delta v_i + \left(\left(\frac{\gamma + 1}{4} \right)^2 \Delta v_i^2 + c_s^2 \right)^{1/2} \right\} (\Delta \hat{\mathbf{v}}_i \cdot \mathbf{S}_i) \Delta \mathbf{v}_i (1 - \psi_i)$$

Shock jump from Lagrangian from Kuropatenko, 1967

For MHD usually replace sound speed with fast speed



1D test - Sod's problem

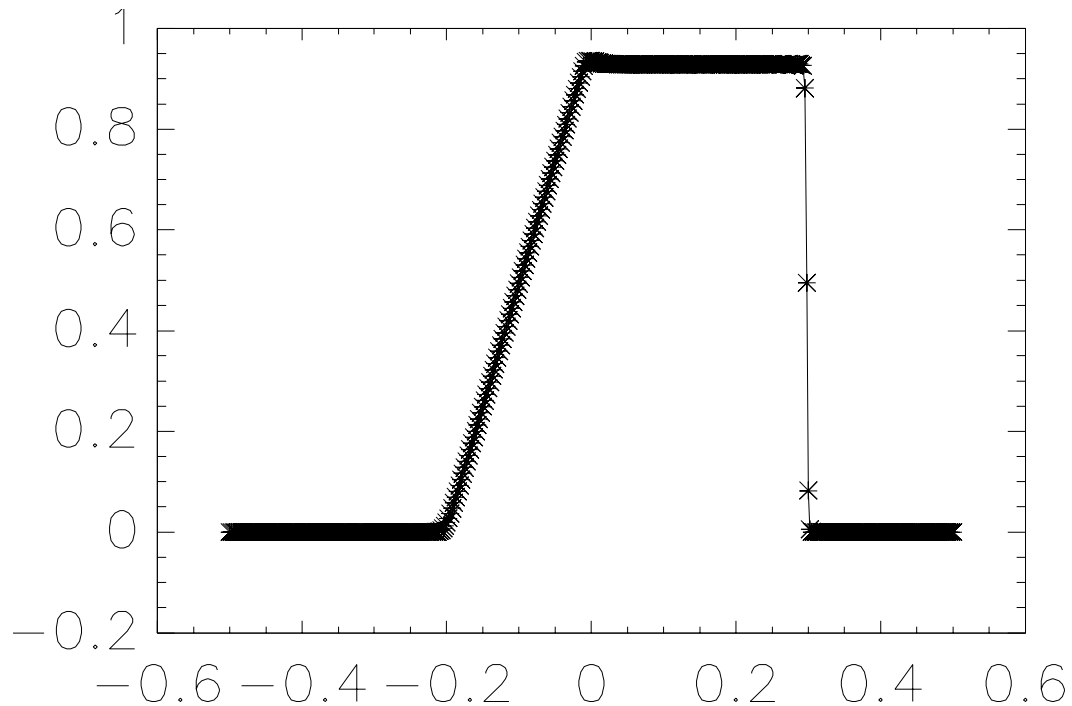
Sod considered a one-dimensional tube of unit length $0 \leq x \leq 1$ and the following initial conditions at $t = 0$:

$$\rho(x, 0) = \begin{cases} 1.0 & \text{for } x \leq \frac{1}{2} \\ 0.125 & \text{for } x > \frac{1}{2} \end{cases},$$

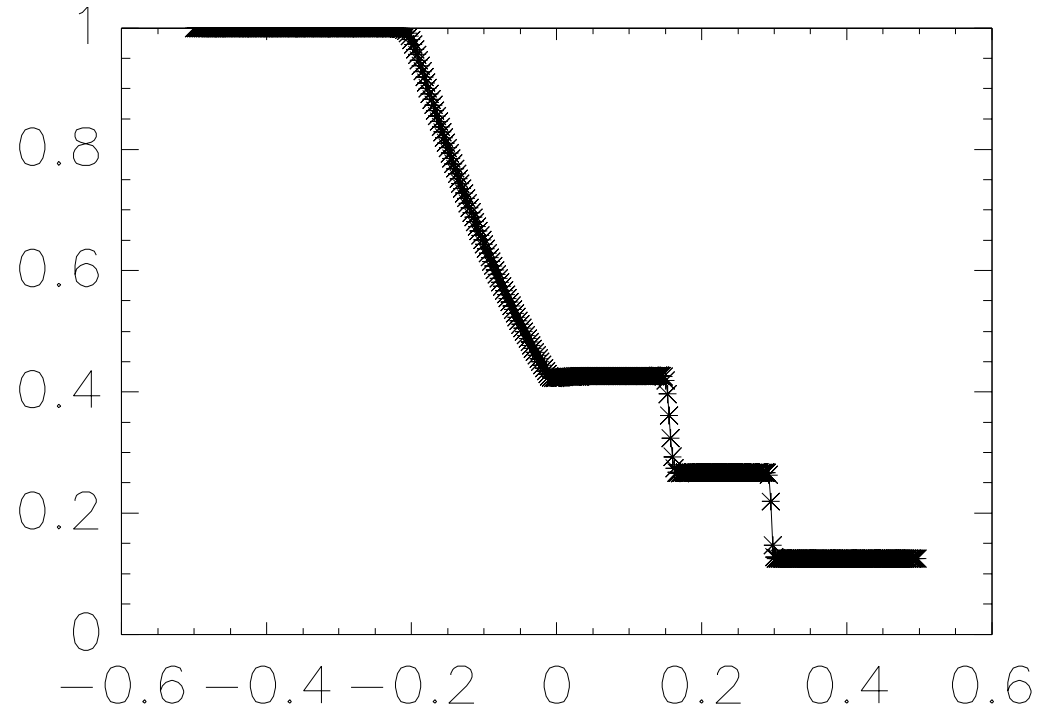
$$p(x, 0) = \begin{cases} 1.0 & \text{for } x \leq \frac{1}{2} \\ 0.1 & \text{for } x > \frac{1}{2} \end{cases},$$

$$u(x, 0) = 0.$$

Velocity



Density



Eulerian grid

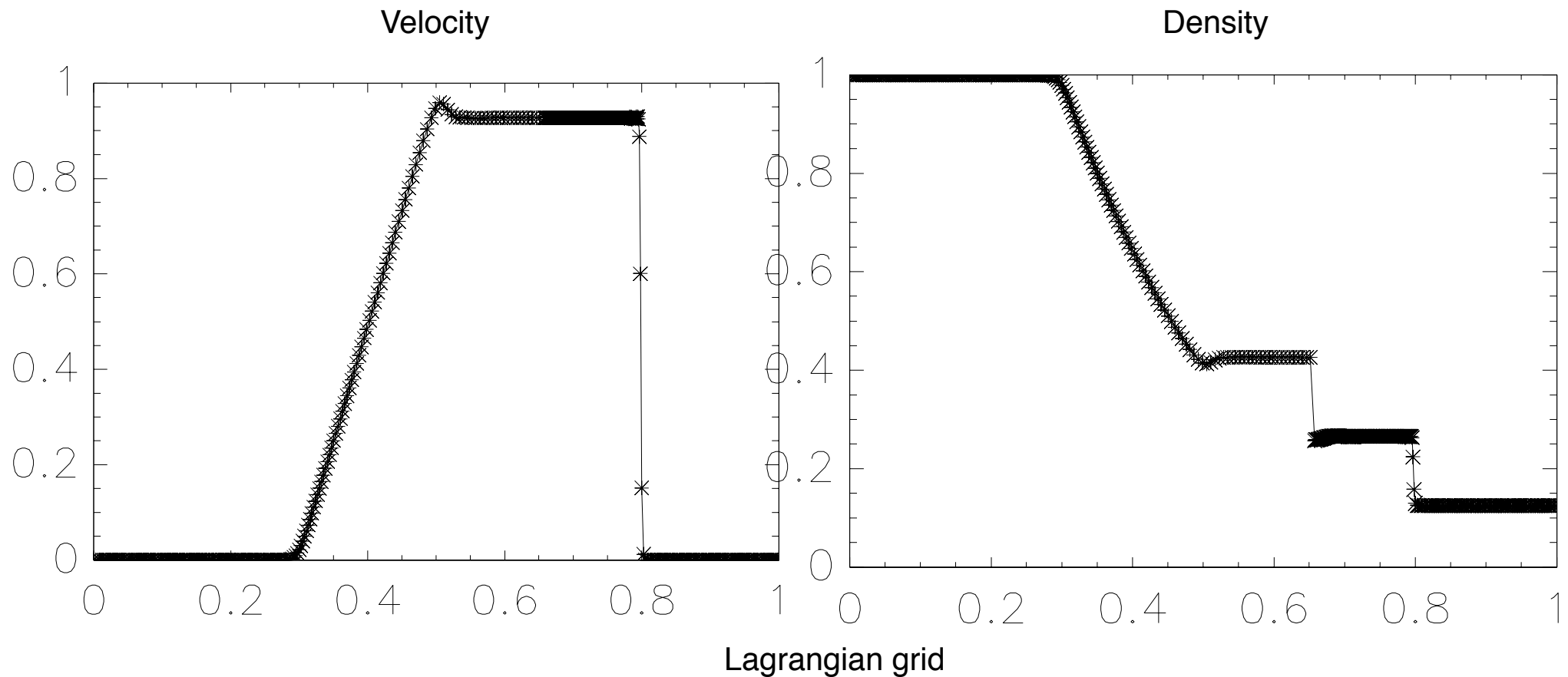
1D test - Sod's problem

Sod considered a one-dimensional tube of unit length $0 \leq x \leq 1$ and the following initial conditions at $t = 0$:

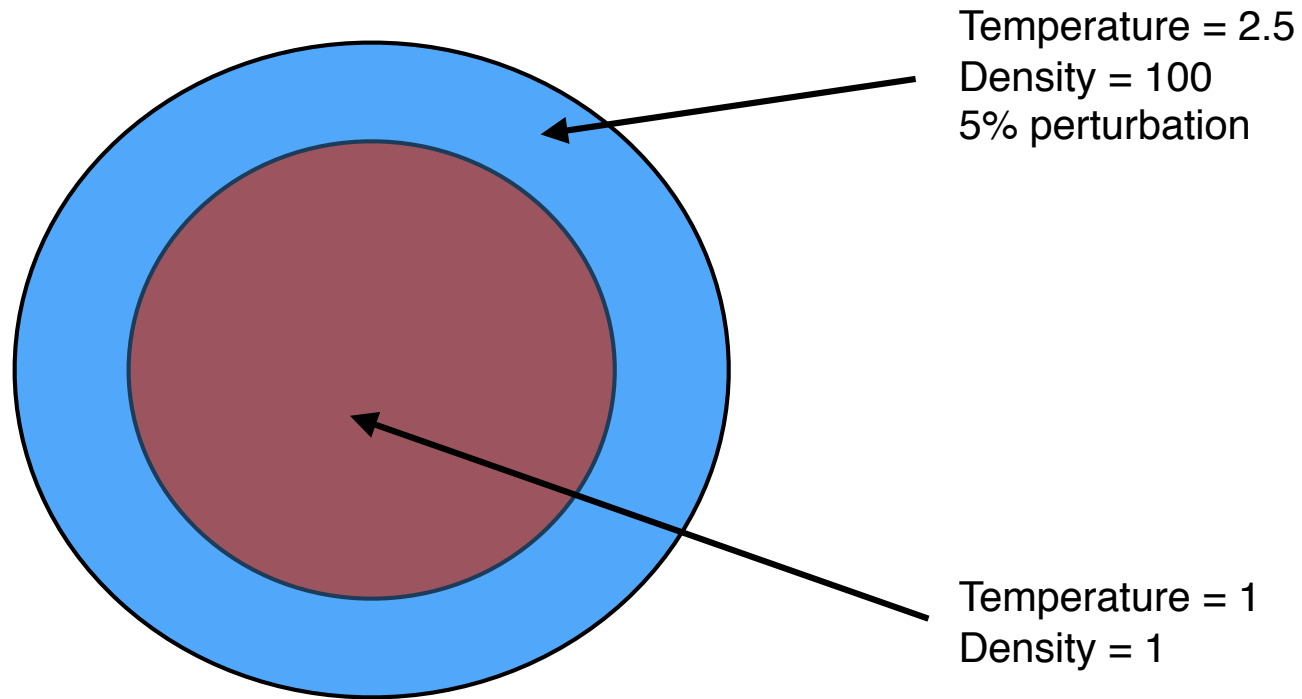
$$\rho(x, 0) = \begin{cases} 1.0 & \text{for } x \leq \frac{1}{2} \\ 0.125 & \text{for } x > \frac{1}{2} \end{cases},$$

$$p(x, 0) = \begin{cases} 1.0 & \text{for } x \leq \frac{1}{2} \\ 0.1 & \text{for } x > \frac{1}{2} \end{cases},$$

$$u(x, 0) = 0.$$

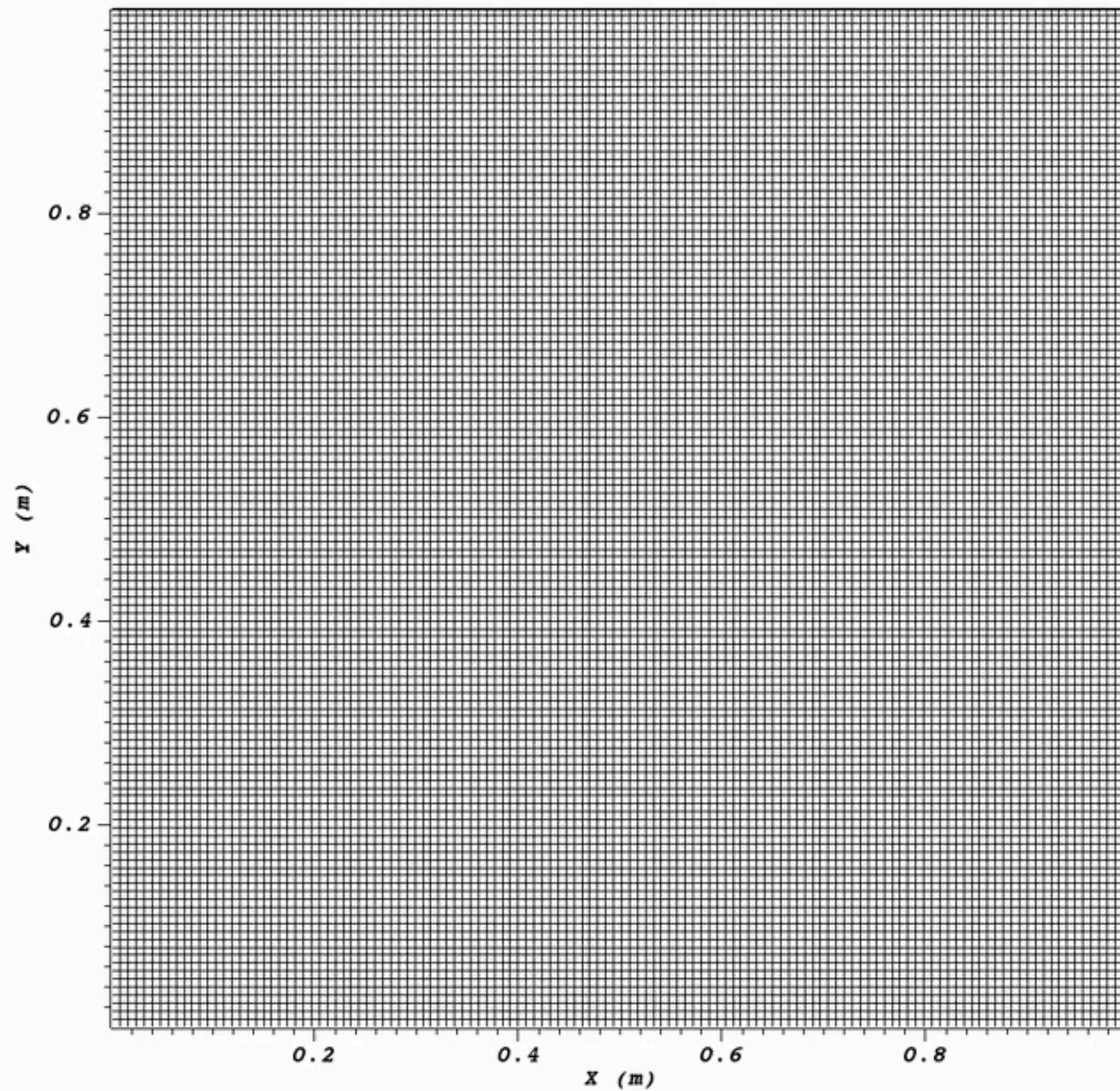


Spherical shell test

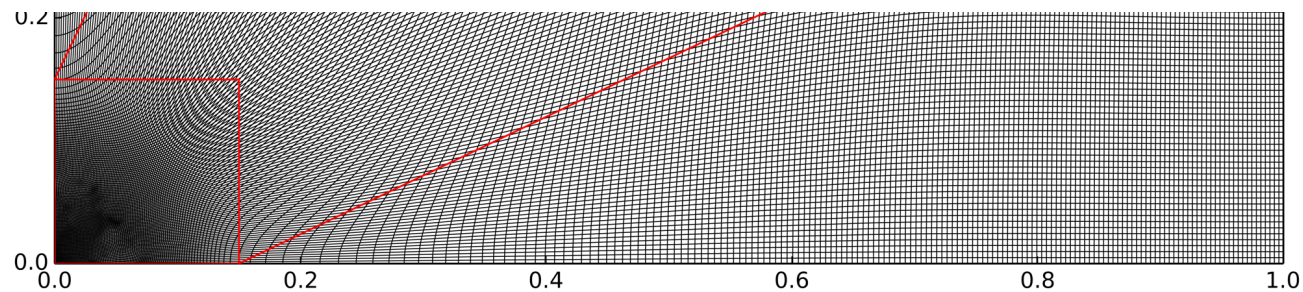
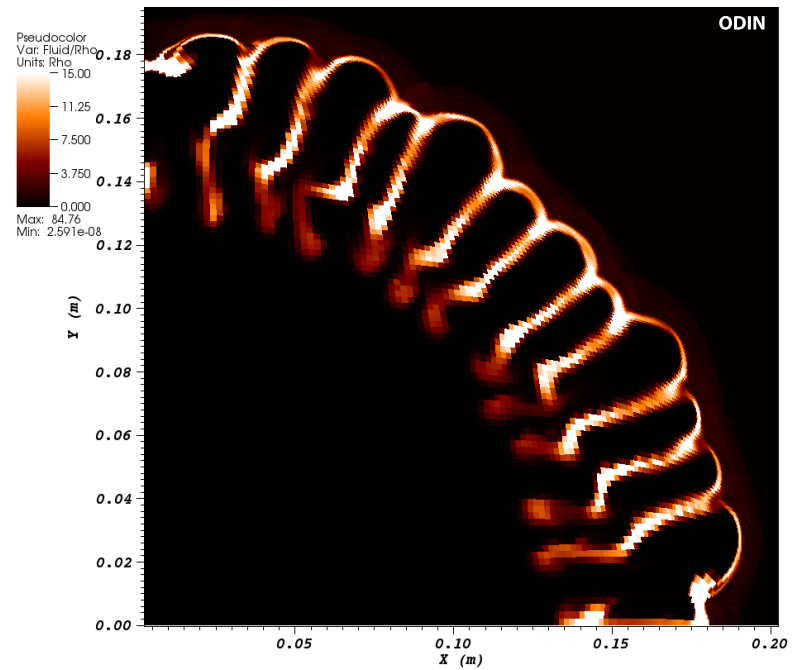
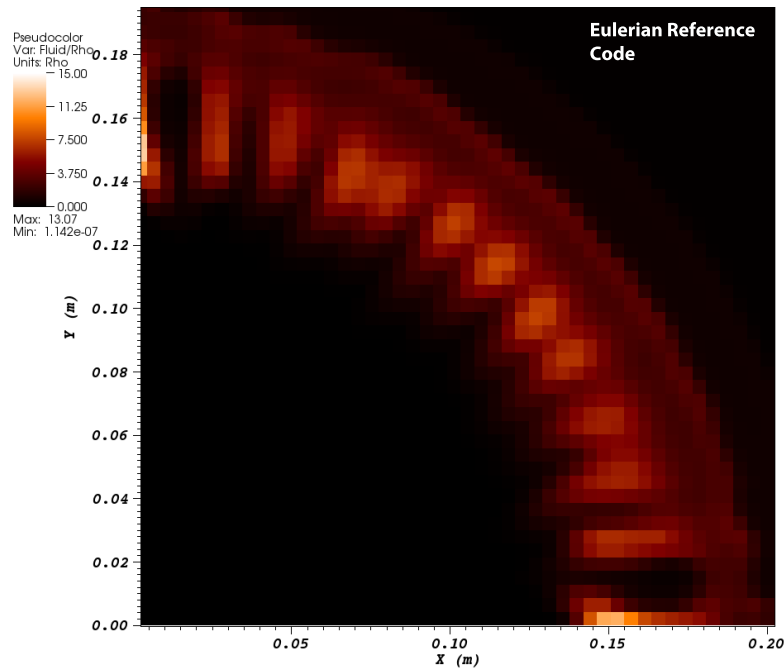
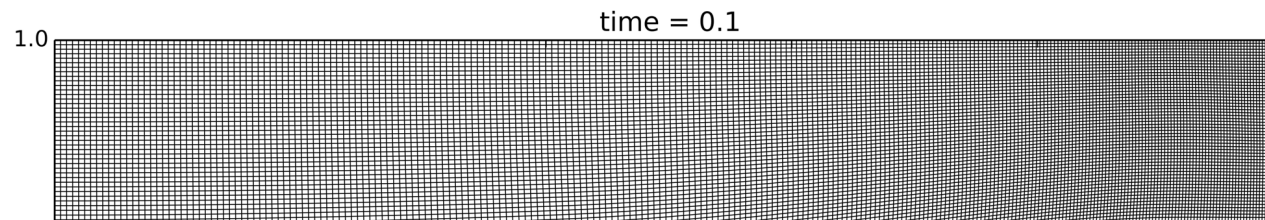


Includes remapping to relaxed grid (Winslow) until core collapse then locked grid

Spherical compression test



Spherical compression test



Lagrangian B-field update

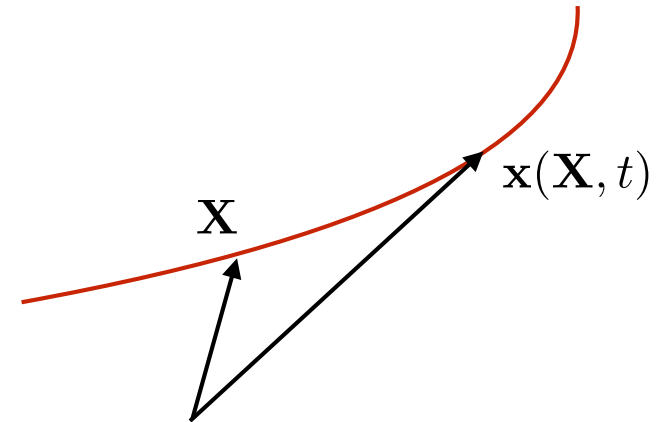
- Adapted from Craig & Sneyd, Astrophysical J., **311**, 1986
- B-field staggered to cell faces to preserve $\text{div.B}=0$ by constrained transport (Evans & Hawley) so really only know fluxes through surfaces, not vector B-field on surface

$$\mathbf{x}(\mathbf{X}, 0) = \mathbf{X}$$

$$\frac{B_i}{\rho} = \frac{\partial x_i}{\partial X_\alpha} \frac{B_i^0}{\rho_0}$$

$$\frac{\rho_0}{\rho} = \frac{\partial(x_1, x_2, x_3)}{\partial(X_1, X_2, X_3)} = \Delta_0$$

$$B_i = \frac{\partial x_i}{\partial X_\alpha} \frac{B_\alpha^0}{\Delta_0}$$



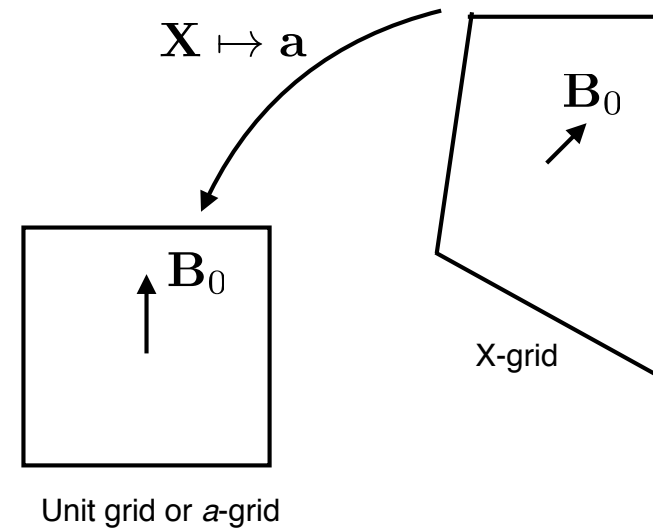
Use Cauchy solution to update cell-centred B-field using but initial X-grid may not be uniform

The pre-initial B-field

- If initial grid not coordinate aligned above scheme inconvenient
- Transform initial conditions back on to unit grid, the *a*-grid

$$B_i = \frac{\partial x_i}{\partial a_\alpha} \frac{\bar{B}_\alpha^0}{\Delta}$$

$$\bar{B}_i = B_\alpha^0 \frac{\partial a_i}{\partial X_\alpha} \frac{\partial(X_1, X_2, X_3)}{\partial(a_1, a_2, a_3)}$$



Orszag-Tang Vortex

Problem Definition

$$\rho = 1.0 \quad p = \frac{5}{3}$$

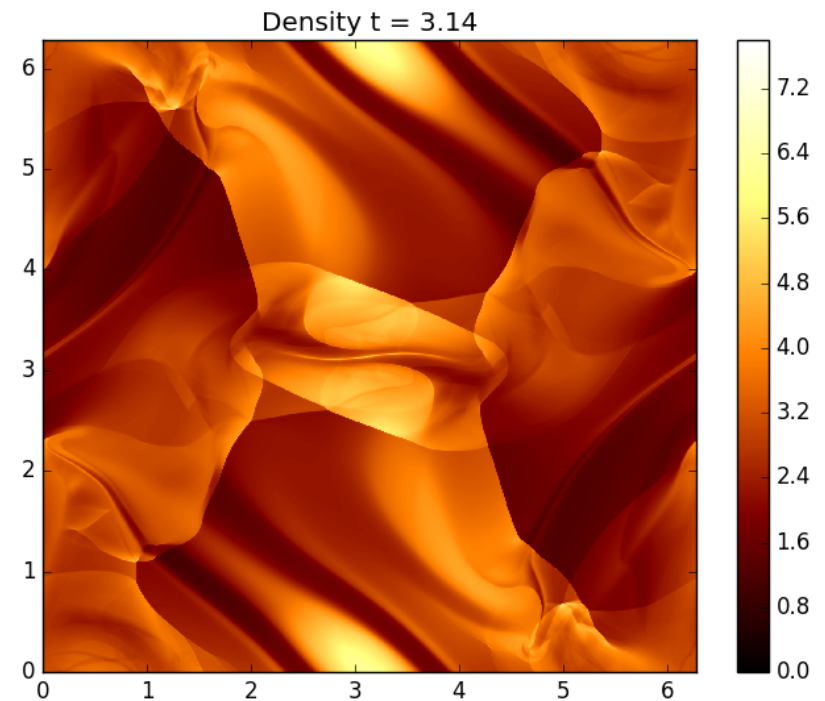
$$v_x = -\sin y$$

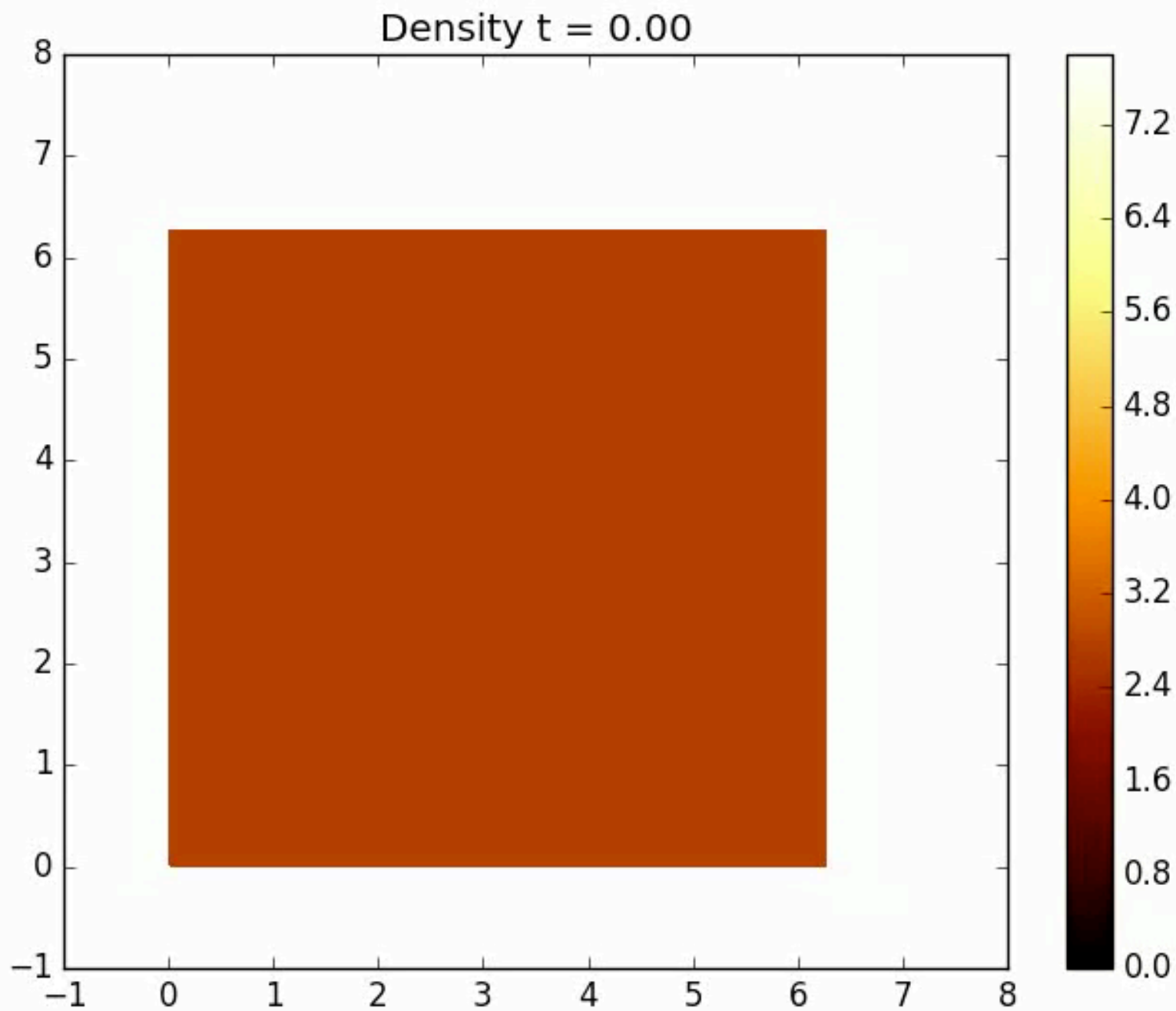
$$v_y = \sin x$$

$$B_x = -\sin y$$

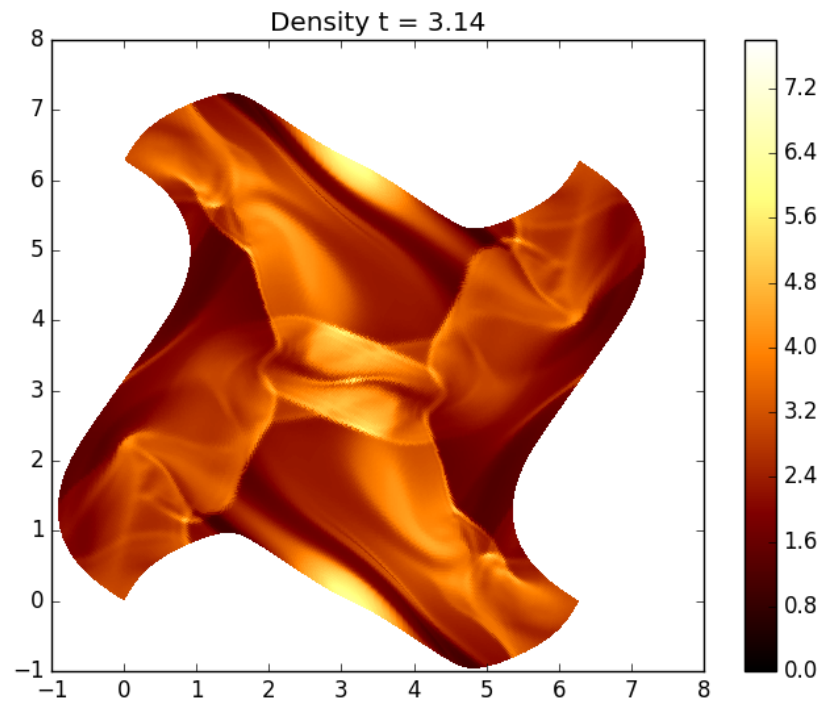
$$B_y = \sin 2x$$

Run Lagrangian Mode until
 $t=1.0$. Then lock grid, and run
Eulerian until $t=3.14$



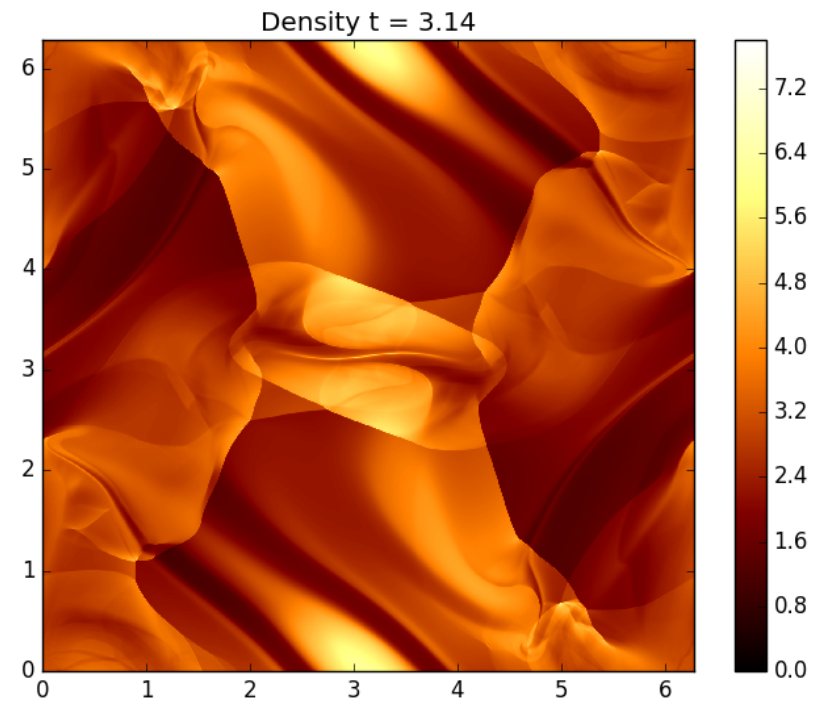


Orszag-Tang



Density at $t=3.14$ for ALE Orszag-Tang vortex.

Odin with 256^2 grid



Density at $t=3.14$ for 1600^2 LARE2D calculation.

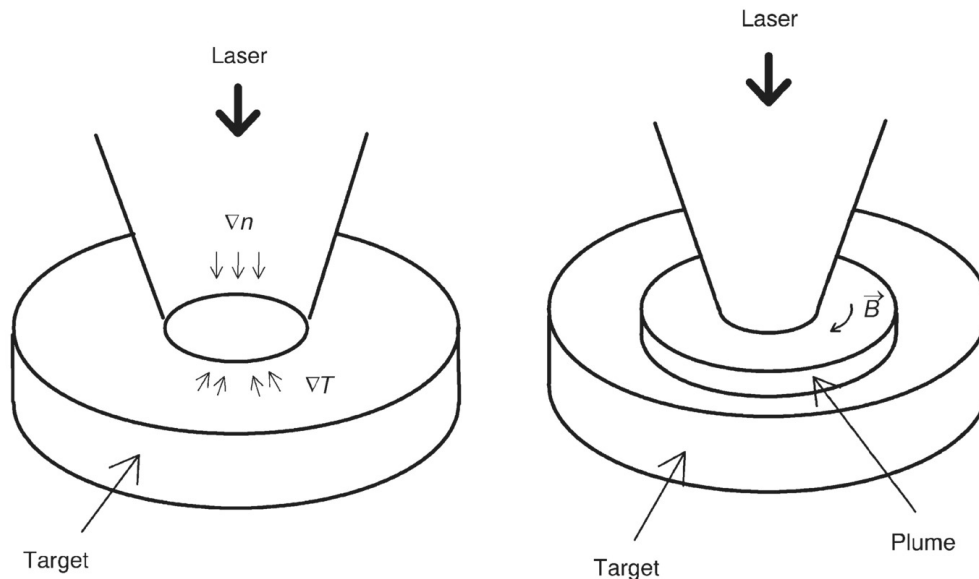
Biermann battery field generation

Pressure term in generalised Ohm's Law

$$\mathbf{E} + \mathbf{v} \times \mathbf{B} = \eta \mathbf{j} - \frac{1}{en_e} \nabla P_e$$

Combines with Faraday's law to give

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times \left(\frac{1}{en_e} \nabla P_e \right) = - \frac{\nabla n_e \times \nabla k_B T_e}{en_e}$$



¹ C.K. Li *et al.*, Phys. Rev. Lett **102** (2009)

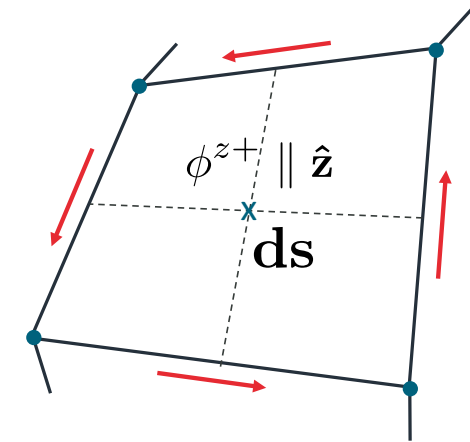
² G. Gregori *et al.*, Nature **481** (2012)

³ L. Biermann, Z. Naturforsch **5** (1950)

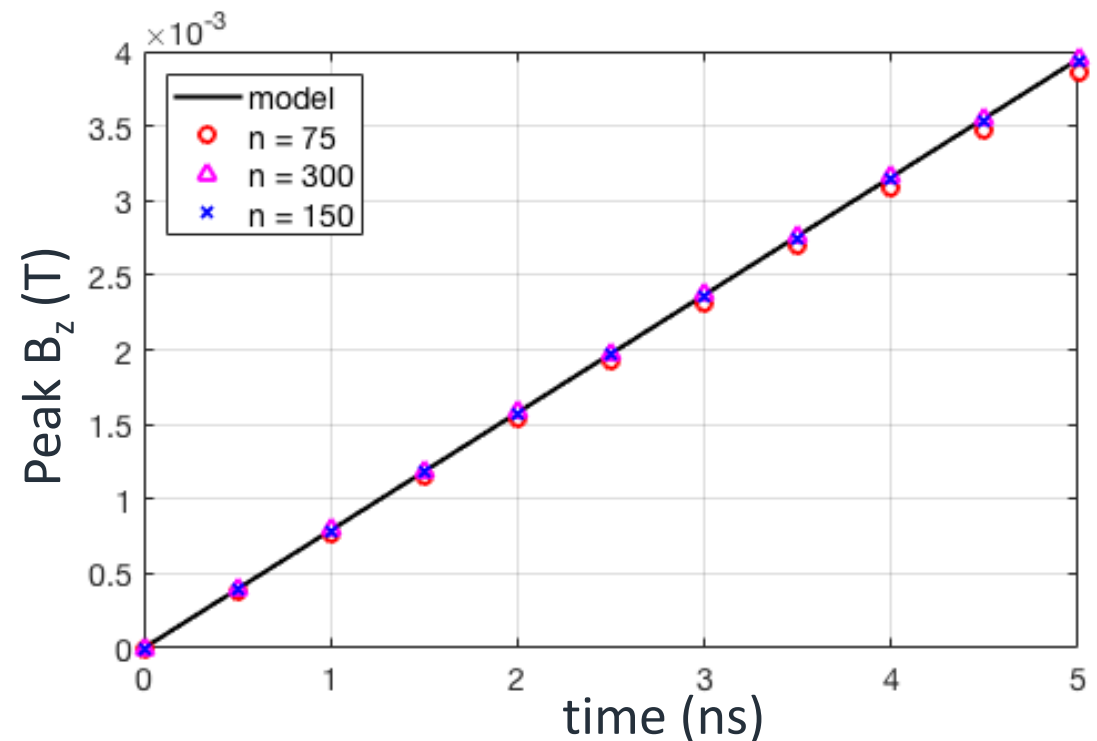
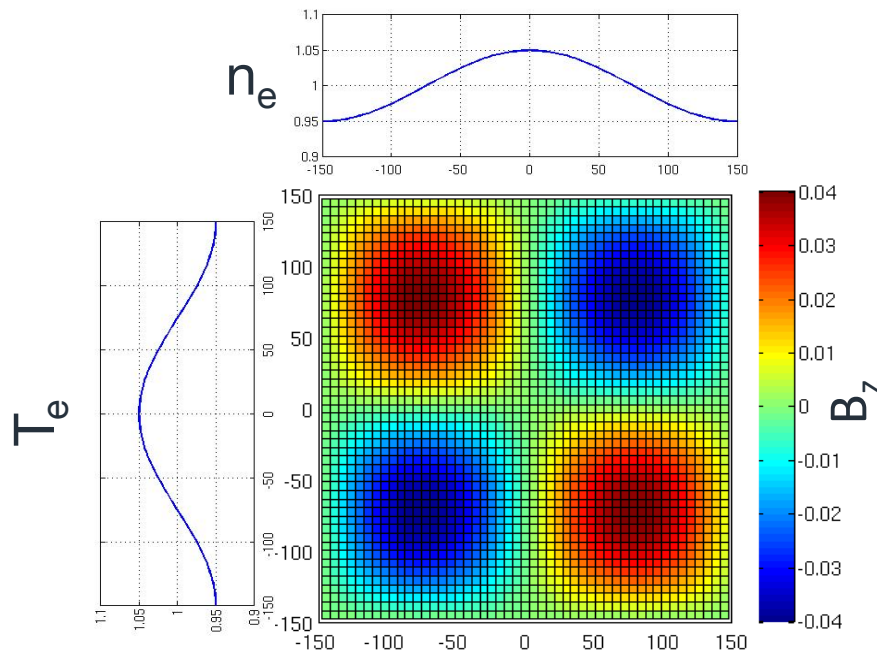
$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times \left(\frac{k_b T_e}{e} \nabla \ln n_e \right)$$

Biermann battery - implementation

- B-fields in Odin defined as fluxes $\perp$ to cell faces
- Field generation in z-direction only
- Update total cell fluxes via line integrals



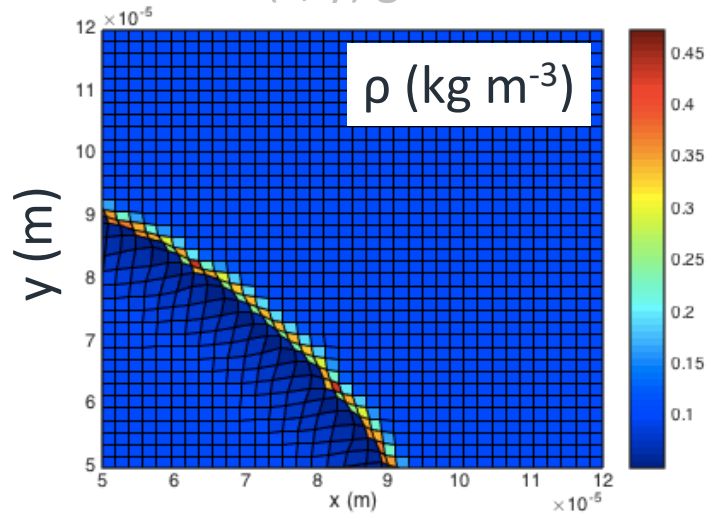
$$\frac{\partial}{\partial t} \int_S \mathbf{B} \cdot d\mathbf{s} = \oint_C \left(\frac{k_B T_e}{e} \nabla \ln n_e \right) \cdot d\mathbf{l}$$



Biermann battery – catastrophe

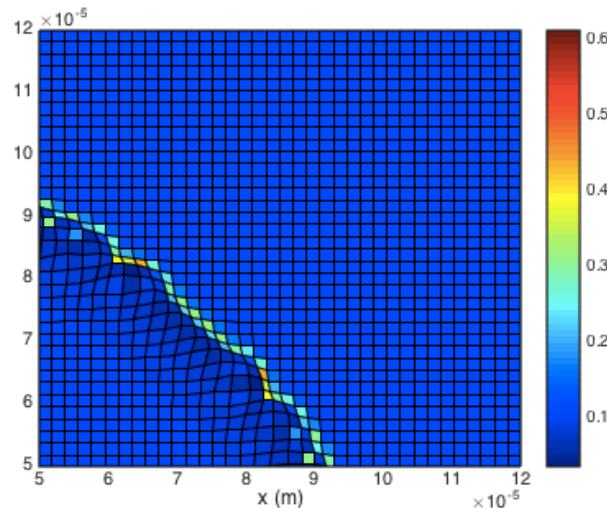
Biermann : OFF

(x, y) grid



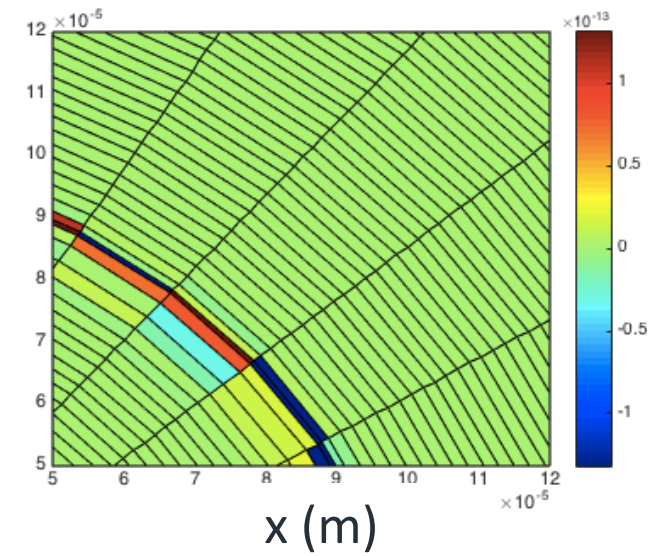
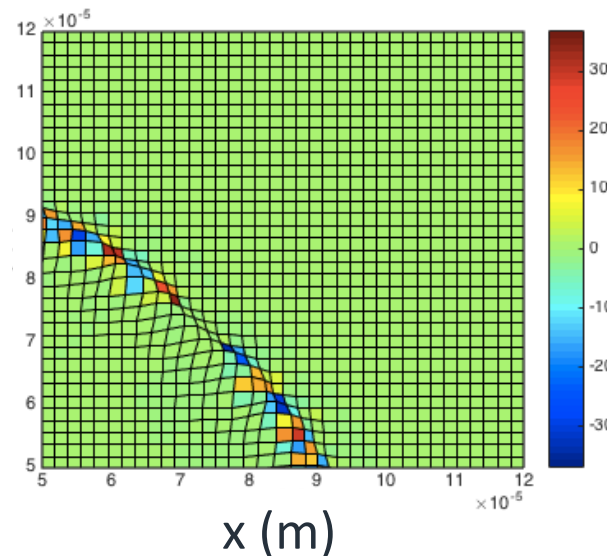
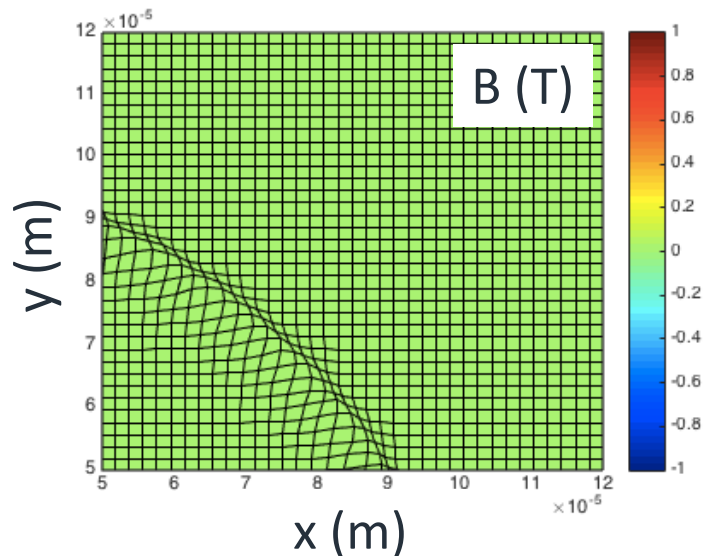
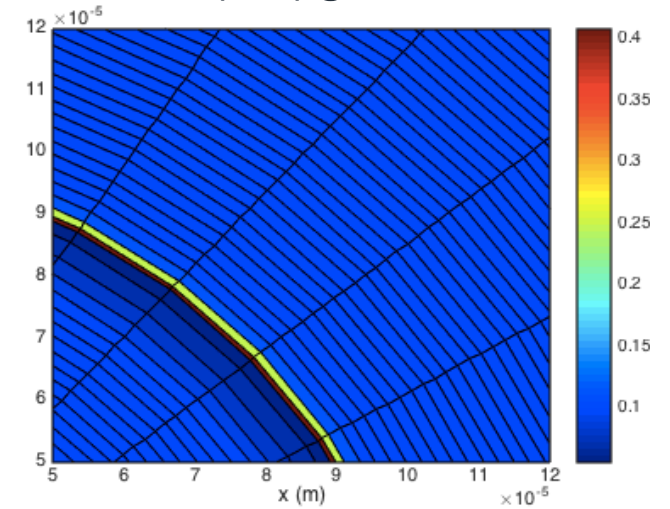
Biermann : ON

(x, y) grid



Biermann : ON

(r, θ) grid



Maximum $B \approx 40$ T

Maximum $B \approx 10^{-13}$ T

Thermal conduction with B-fields

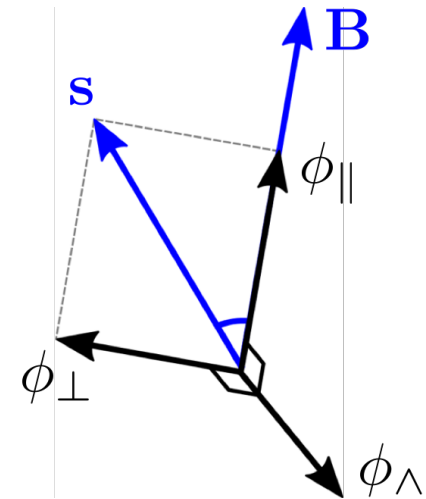
- Temperature governed by diffusion equation

$$\rho \frac{\partial U}{\partial t} = -\nabla \cdot \mathbf{q}$$

- Anisotropic heat-flow (in presence of B-field)

$$\kappa = f(\omega\tau)$$

$$\mathbf{q} = -\underline{\underline{\kappa}} \cdot \nabla T$$



$$\mathbf{q} = \underbrace{-\kappa_{\parallel} \mathbf{b} (\mathbf{b} \cdot \nabla T)}_{\mathbf{q}_{\parallel}} - \underbrace{\kappa_{\perp} (\mathbf{b} \times [\nabla T \times \mathbf{b}])}_{\mathbf{q}_{\perp}} - \underbrace{\kappa_{\Lambda} \mathbf{b} \times \nabla T}_{\mathbf{q}_{\Lambda}}$$

$\mathbf{q}_{\parallel}$

Parallel

$\mathbf{q}_{\perp}$

Perpendicular

$\mathbf{q}_{\Lambda}$

Righi-Leduc

¹ E.M. Epperlein & M.G. Haines, Phys. Fluids **29** (1986)

² S.I. Braginskii, Rev. Plas. Phys. **1** (1965)

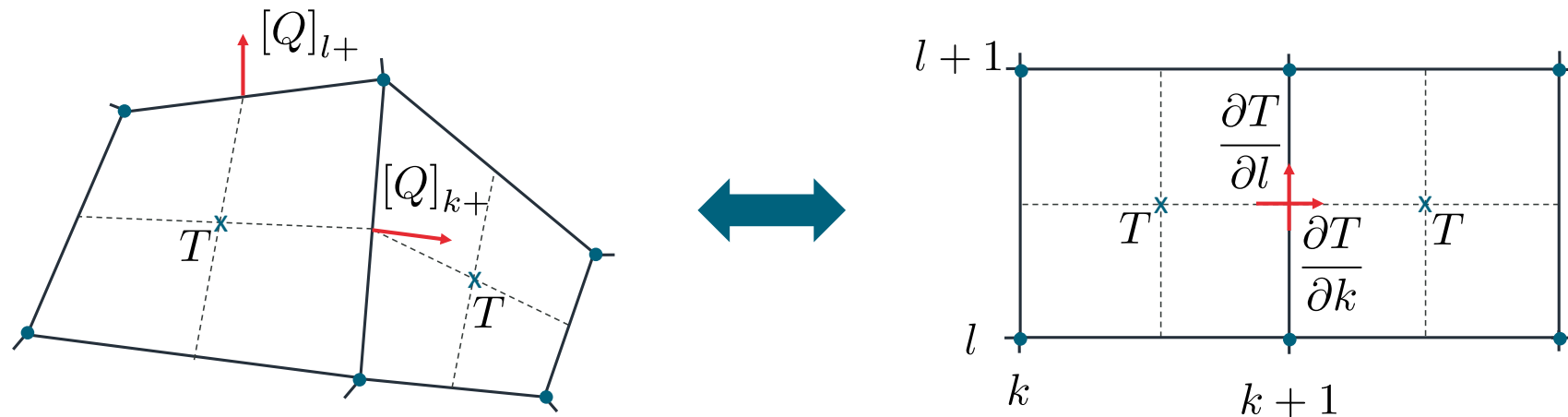
³ C.A. Walsh *et al.*, Phys. Rev. Lett. **118** (2017)

Isotropic thermal conduction in Odin

- Take control volume integral + divergence theorem

$$\frac{\partial}{\partial t} \int_V \rho U dV = - \oint_S \mathbf{q} \cdot d\mathbf{S}$$

- Implement gradients on index grid due to distorted mesh



Total heat-fluxes

$$\left\{ \begin{array}{l} [Q]_{k+} = -\frac{\kappa_{\perp}}{J} \left\{ \left(\frac{\partial T}{\partial k} \right) |\mathbf{r}_l|^2 - \left(\frac{\partial T}{\partial l} \right) \mathbf{r}_k \cdot \mathbf{r}_l \right\} \\ [Q]_{l+} = -\frac{\kappa_{\perp}}{J} \left\{ \left(\frac{\partial T}{\partial l} \right) |\mathbf{r}_k|^2 - \left(\frac{\partial T}{\partial k} \right) \mathbf{r}_k \cdot \mathbf{r}_l \right\} \end{array} \right.$$

¹ G.J. Pert, J. Comp. Phys. **42** (1981)

Anisotropic TC on the ALE grid

- Anisotropic heat-flow derivation based on coordinate transformation approach used by Pert ¹
- Recall $\mathbf{q} = -\kappa \nabla T$ for isotropic heat-flow:

$$[Q]_{k+} = -\frac{\kappa_{\perp}}{J} \left\{ \left(\frac{\partial T}{\partial k} \right) |\mathbf{r}_l|^2 - \left(\frac{\partial T}{\partial l} \right) \mathbf{r}_k \cdot \mathbf{r}_l \right\}$$

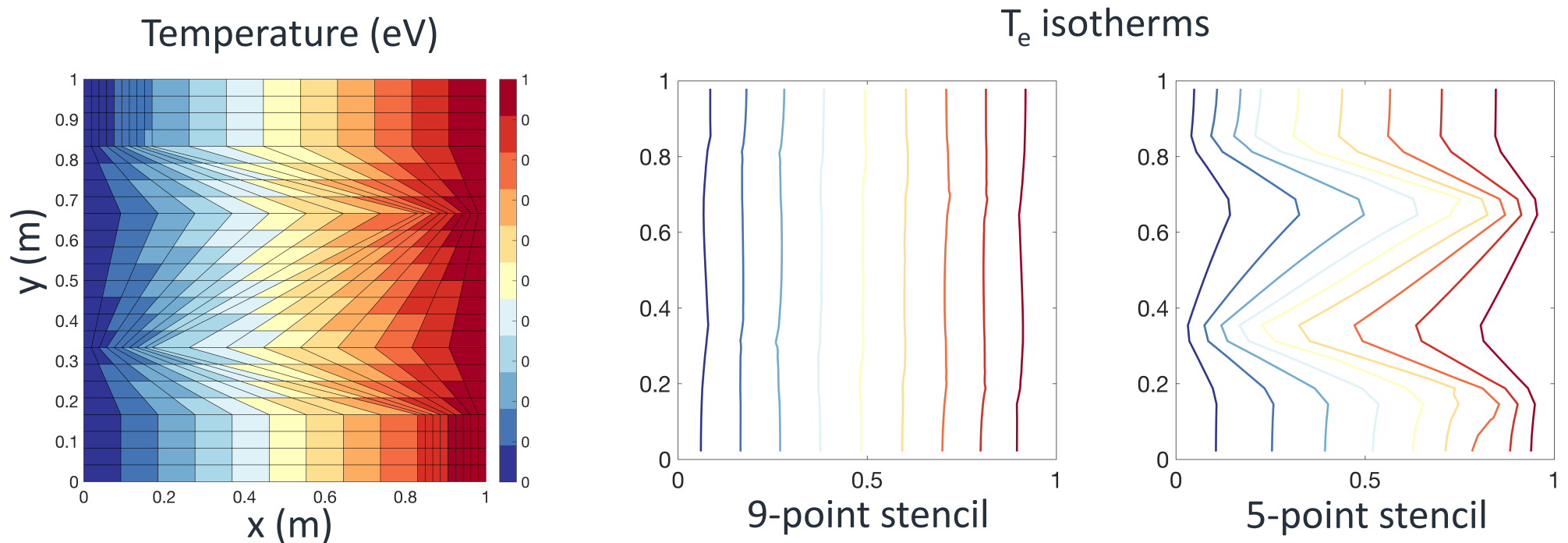
- Anisotropic TC yields $\mathbf{q}_{\parallel}$, $\mathbf{q}_{\perp}$, $\mathbf{q}_{\wedge}$ components

$$\left\{ \begin{array}{l} [Q_{\parallel}]_{k+} = -\frac{\kappa_{\parallel}}{J} \left\{ \left(\frac{\partial T}{\partial k} \right) |\mathbf{b} \times \mathbf{r}_l|^2 - \left(\frac{\partial T}{\partial l} \right) [(\mathbf{b} \times \mathbf{r}_l) \cdot (\mathbf{b} \times \mathbf{r}_k)] \right\} \\ [Q_{\perp}]_{k+} = -\frac{\kappa_{\perp}}{J} \left\{ \left(\frac{\partial T}{\partial k} \right) [|\mathbf{r}_l|^2 - |\mathbf{b} \times \mathbf{r}_l|^2] - \left(\frac{\partial T}{\partial l} \right) [\mathbf{r}_k \cdot \mathbf{r}_l - (\mathbf{b} \times \mathbf{r}_l) \cdot (\mathbf{b} \times \mathbf{r}_k)] \right\} \\ [Q_{\wedge}]_{k+} = +\frac{\kappa_{\wedge}}{J} b_z J \left(\frac{\partial T}{\partial l} \right) \end{array} \right.$$

¹ G.J. Pert, J. Comp. Phys. **42** (1981)

Conduction testing – Kershaw grid

- Test heat-flow on the Kershaw ¹ grid - strongly distorted
- Expect linear T_e gradient in x-direction



- Standard ‘5-point’ spatial stencil leaves strong grid imprint
- Full (‘9-point’) stencil required to produce correct isotherms

¹ D. Kershaw, J. Comp. Phys. **39** (1981)

Conduction testing – Parrish & Stone test

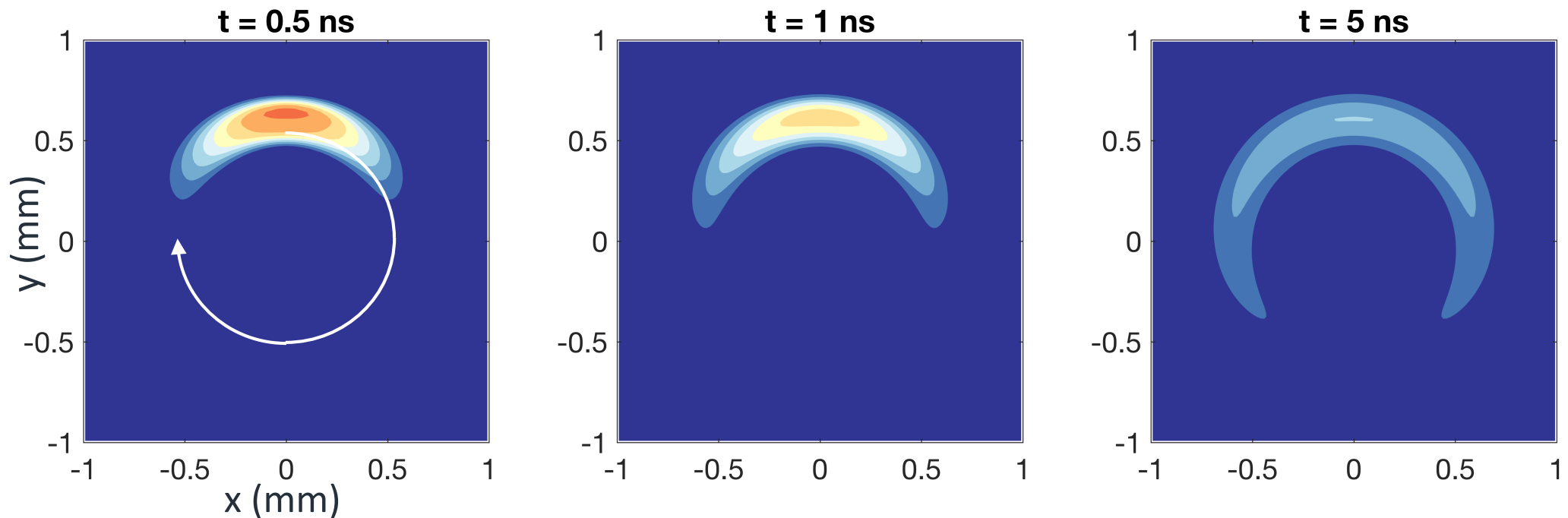
- Heat-pulse annulus in circular B-field profile

$$T(r, \theta) \begin{cases} T^* & \text{when } (0.5 \leq r \leq 0.7), \left(\frac{11\pi}{12} \leq \theta \leq \frac{13\pi}{12} \right) \\ T_0 & \text{else} \end{cases}$$

$$B_0 = 100 T$$

$$T_0 = 100 eV$$

$$T^* = 120 eV$$



- Super time-stepping² stages limited to ~ 25

¹ I. Parrish & J. Stone, *Astro. J.* **633** (2005)

² C.D. Meyer, *Mon. Not. R. Astro. Soc.* 422 (2012)

Extended MHD effects

- Odin core code uses ideal MHD
- Generalised Ohm's law

$$en_e (\mathbf{E} + \boxed{\mathbf{C} \times \mathbf{B}}) = -\nabla P_e + \mathbf{j} \times \mathbf{B} + \boxed{\frac{m_e}{e\tau} \underline{\underline{\alpha}}^c \cdot \mathbf{j}} - \boxed{n_e \underline{\underline{\beta}}^c \cdot \nabla T_e}$$

frozen-in flow resistivity thermoelectric

- Scalar resistive diffusion

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times [\eta \mathbf{j}]$$

- Nernst advection – B-fields advect with electron heat-flow

$$\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \left(\frac{\beta_{\wedge}}{e|B|} \nabla T_e \times \mathbf{B} \right) = \nabla \times (\mathbf{v}_N \times \mathbf{B})$$

⁶ E.M. Epperlein & M.G. Haines, J. Phys. D **17** (1984)

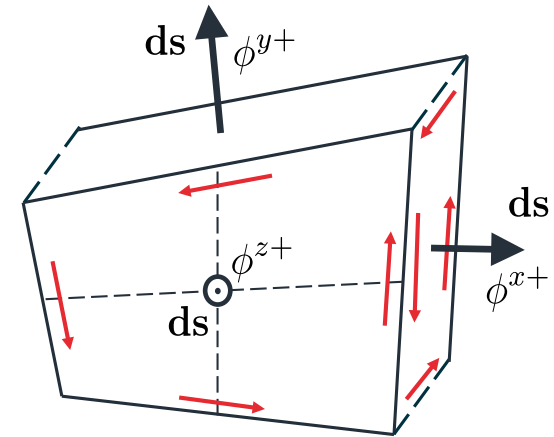
⁷ S.I. Braginskii., Rev. Plas. Phys. **1** (1965)

Scalar resistive diffusion testing

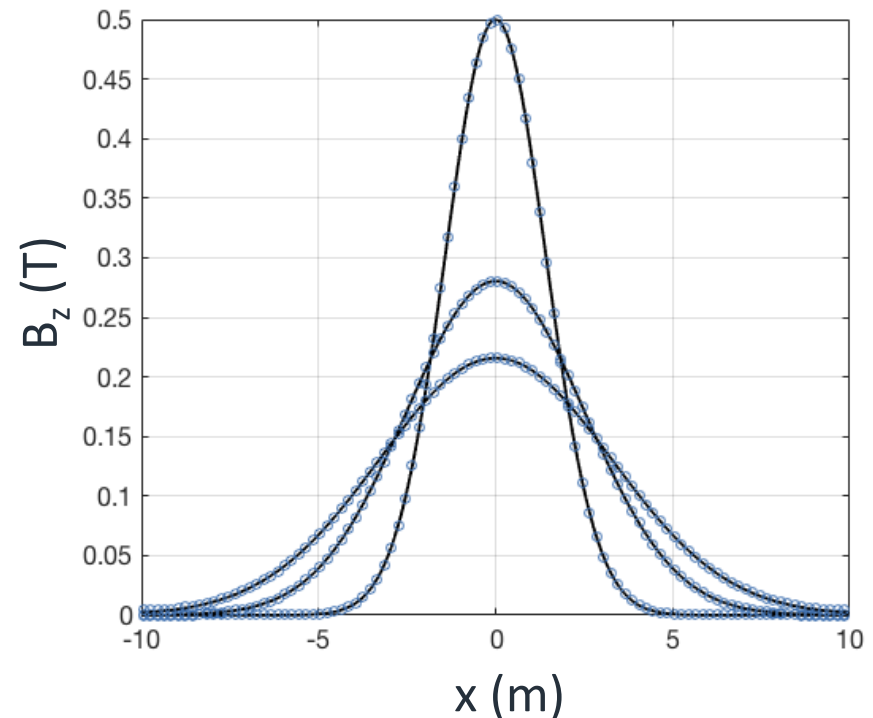
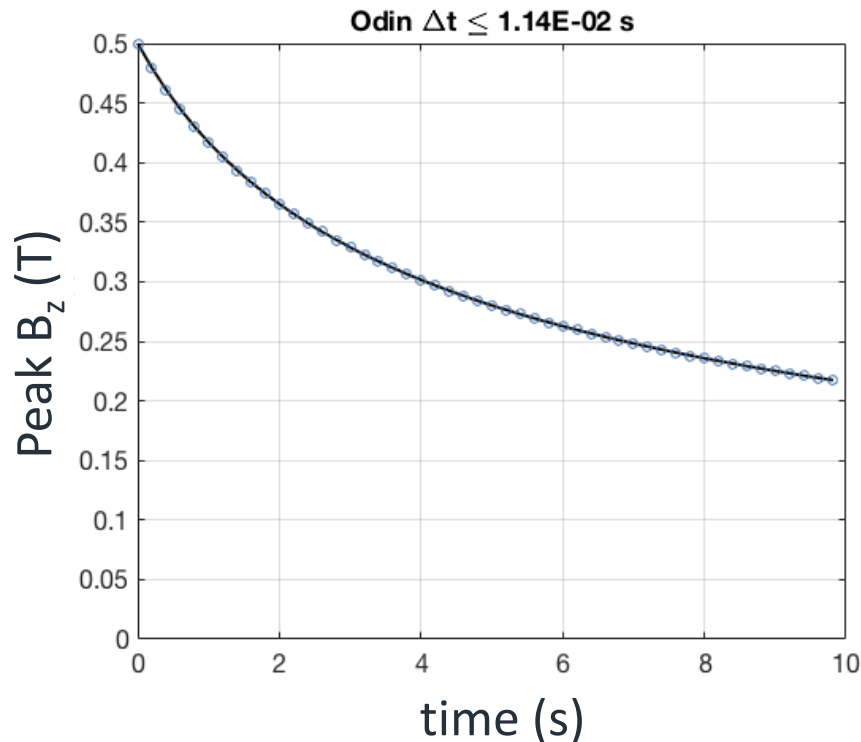
- Calculate B-field fluxes

$$\frac{\partial}{\partial t} \int_S \mathbf{B} \cdot d\mathbf{s} = -\frac{m_e}{e^2} \oint_C \left(\frac{\alpha_{\perp}^c}{\tau n_e} \mathbf{j} \right) \cdot d\mathbf{l}$$

$$\mathbf{j} = \frac{\nabla \times \mathbf{B}}{\mu_0}$$



- Test: decay of a Gaussian B-field perturbation



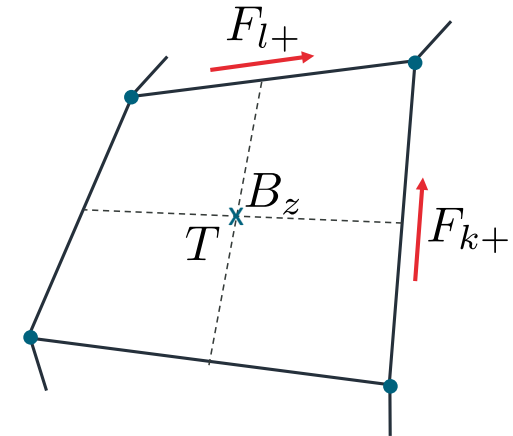
Nernst advection implementation

- B-field fluxes by surface integral

$$\frac{\partial}{\partial t} \int \mathbf{B} \cdot d\mathbf{S} = -\frac{1}{e} \oint \left(\beta_{\wedge} \nabla T \times \hat{\mathbf{b}} \right) \cdot d\mathbf{l}$$

$$\frac{\partial}{\partial t} \phi_z = -\frac{1}{e} \{ F_{K+} - F_{L+} - F_{K-} + F_{L-} \}$$

$$\begin{cases} F_{K+} = \int_{K+ \text{ edge}} \beta_{\wedge} \nabla T \times \hat{\mathbf{b}} \cdot d\mathbf{l} \\ F_{L+} = \int_{L+ \text{ edge}} \beta_{\wedge} \nabla T \times \hat{\mathbf{b}} \cdot d\mathbf{l} \end{cases}$$



- Use 9-point stencil as with heat-flow calculation

$$F_{K+} = \frac{\beta_{\wedge} b_z}{J} \left(\mathbf{r}_K \cdot \mathbf{r}_L \frac{\partial T}{\partial L} - \mathbf{r}_L \cdot \mathbf{r}_L \frac{\partial T}{\partial K} \right)$$

$$F_{L+} = \frac{\beta_{\wedge} b_z}{J} \left(\mathbf{r}_K \cdot \mathbf{r}_K \frac{\partial T}{\partial L} - \mathbf{r}_K \cdot \mathbf{r}_L \frac{\partial T}{\partial K} \right)$$

Current status of Odin

- Ideal MHD Lagrangian step with arbitrary remap to smoothed grid (ALE-MHD)
- x-y or r-z 2D geometry
- Laser-ray tracing package
- Anisotropic thermal conduction for long mean-free-path
- Multi-group radiation transport
- Multi-material interface reconstruction on remapping
- Arbitrary EOS currently SESEME or FEOS
- Non-ideal MHD includes
 - Biermann battery term
 - Resistivity
 - Nernst field advection

Aim is for full simulations of laser-driven fusion experiments by the end of 2018 and then released as a 'service' from mid-2019

Thank you for listening