

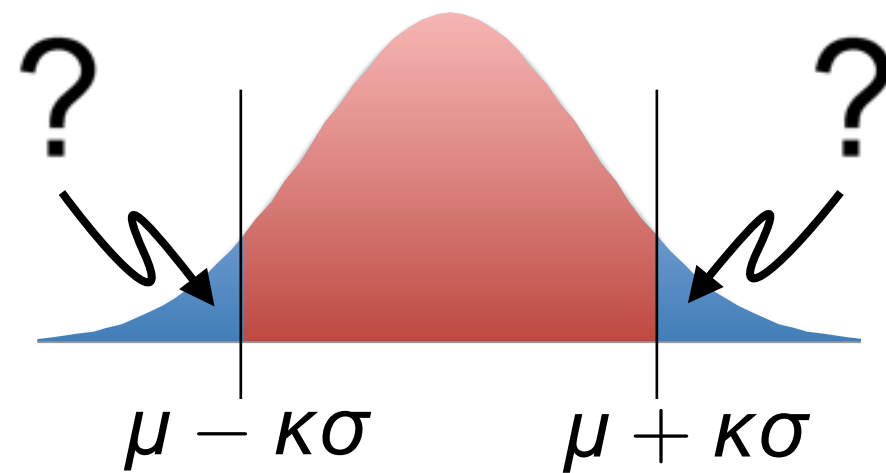
Generalized Gauss Inequalities via Semidefinite Programming

Bart Van Parys,¹ Paul Goulart,¹ Daniel Kuhn²

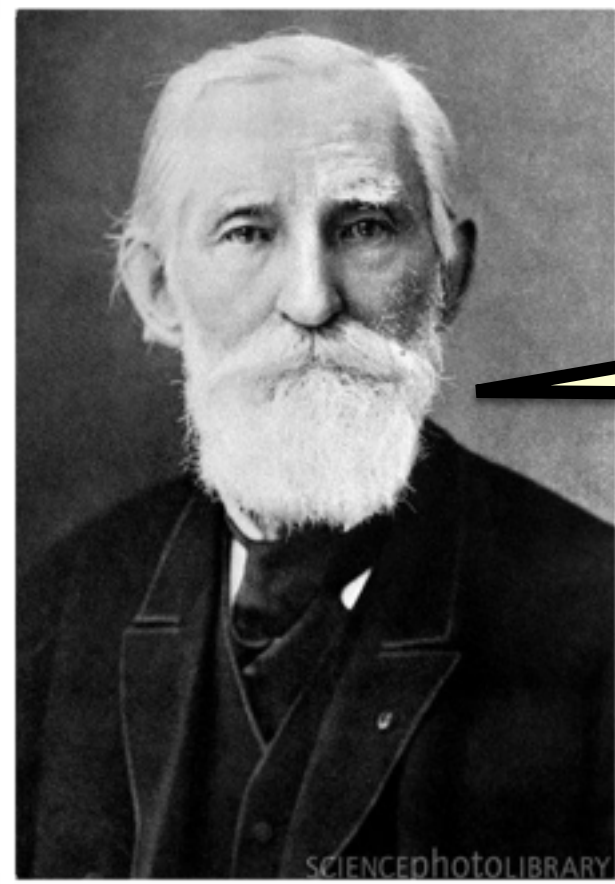
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Eidgenössische Technische Hochschule Zürich (ETHZ)

²Risk Analytics and Optimization Chair
École Polytechnique Fédérale de Lausanne (EPFL)

Bounding Univariate Tail Probabilities



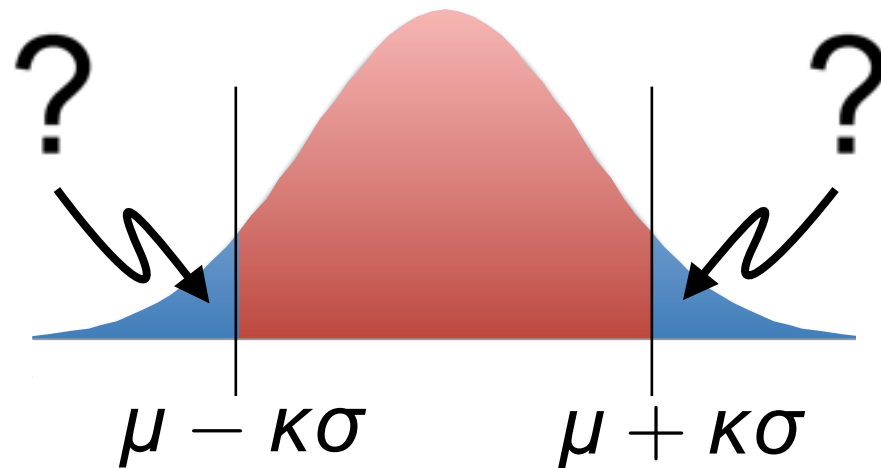
Bounding Univariate Tail Probabilities



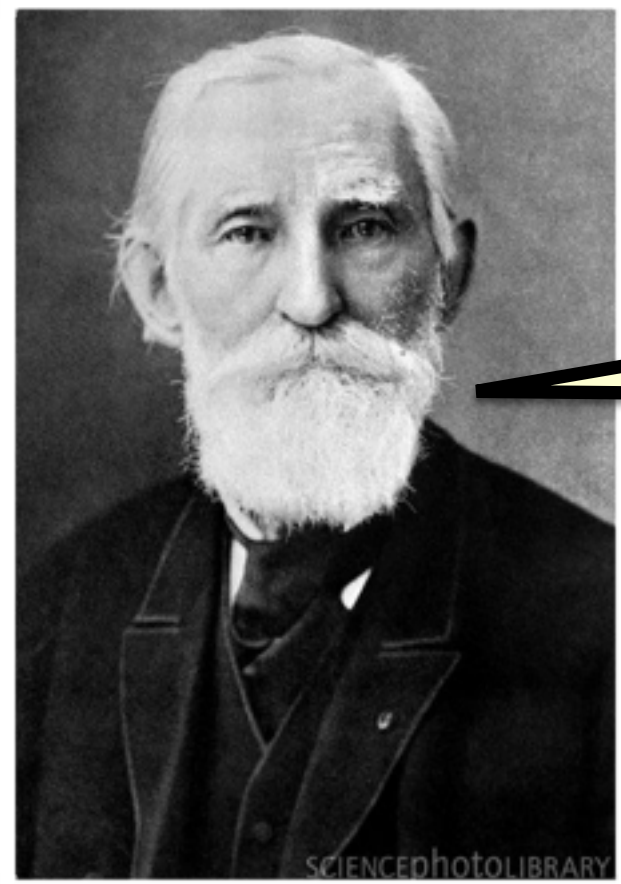
Pafnuty Chebyshev
(1821–1894)

Chebyshev (1867): For $\xi \sim (\mu, \sigma)$

$$\mathbb{P}(|\xi - \mu| \geq k\sigma) \leq \frac{1}{k^2} \quad (k \geq 1)$$



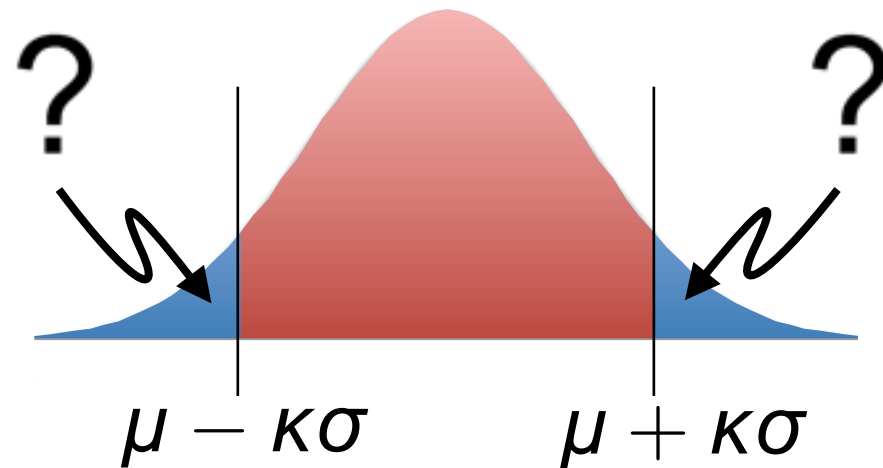
Bounding Univariate Tail Probabilities



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Carl Friedrich Gauss
(1777–1855)

Gauss (1823): For $\xi \sim (\mu, \sigma)$ **unimodal**

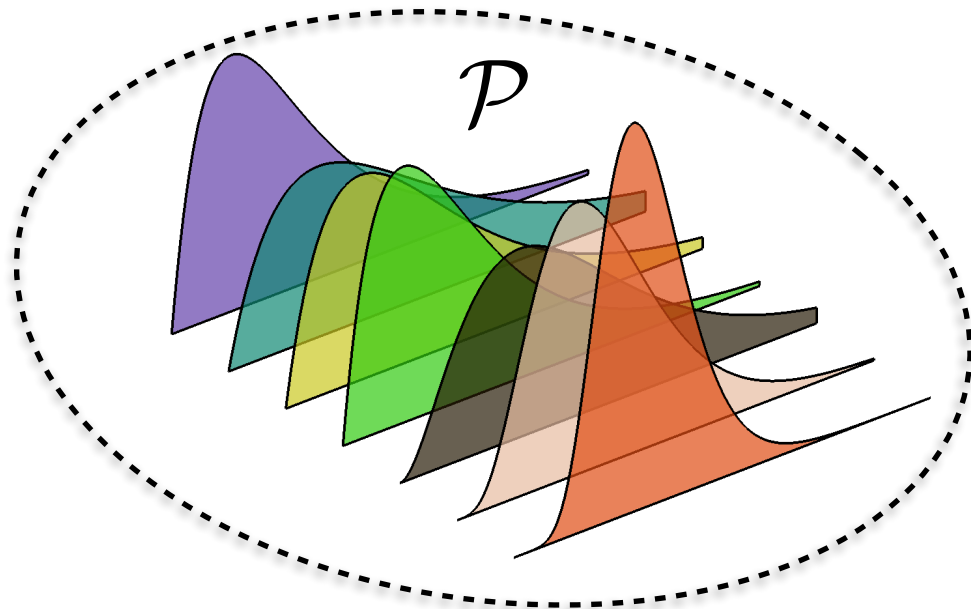
$$\mathbb{P}(|\xi - \mu| \geq k\sigma) \leq \frac{4}{9k^2} \quad \left(k \geq \frac{2}{\sqrt{3}}\right)$$

Optimization Perspective

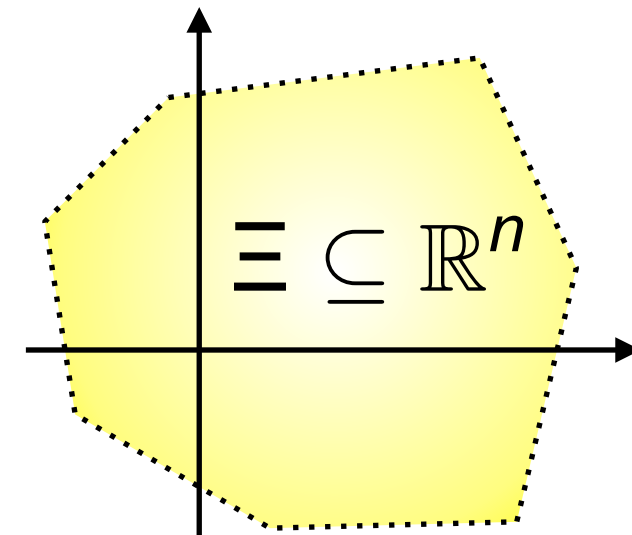
Worst-case probability problems:

$$\sup_{\mathbb{P} \in \mathcal{P}} \mathbb{P}(\xi \notin \Xi) = ?$$

ambiguity set



open polyhedron



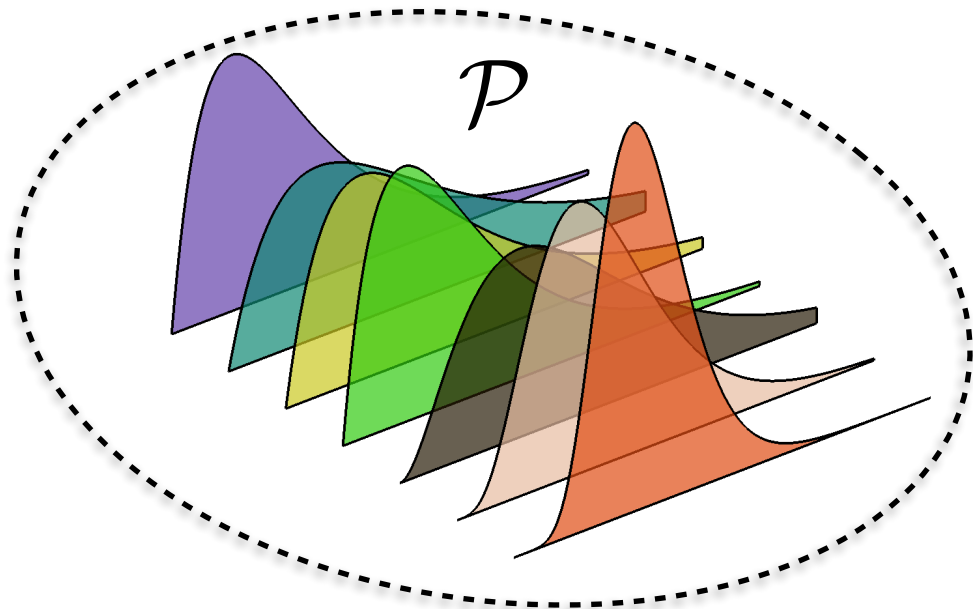
$$\Xi = \{ \xi : a_i^\top \xi < b_i \ \forall i = 1, \dots, k \}$$

Optimization Perspective

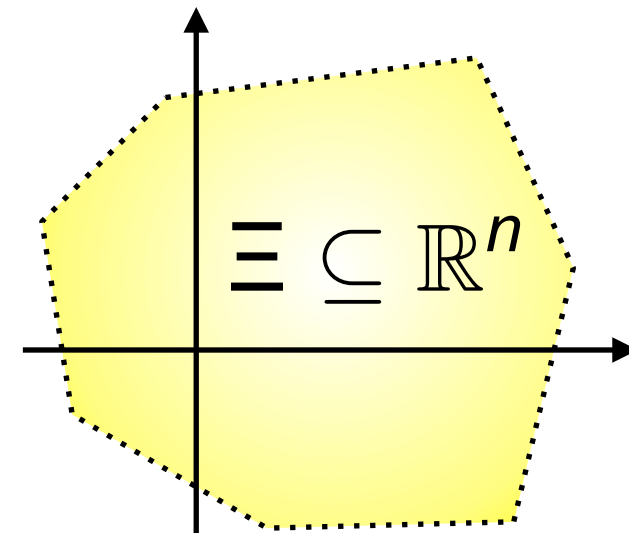
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$$\Xi = \{ \xi : a_i^\top \xi < b_i \ \forall i = 1, \dots, k \}$$

Chebyshev: \mathcal{P} = set of all distributions with mean μ and variance σ^2

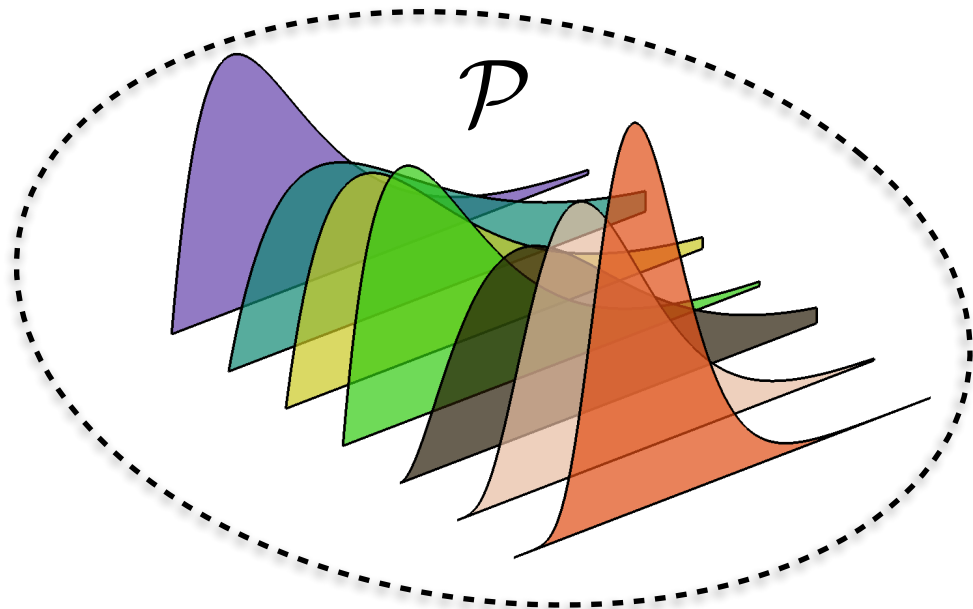
$$\Xi = \{ \xi : \mu - k\sigma < \xi < \mu + k\sigma \}$$

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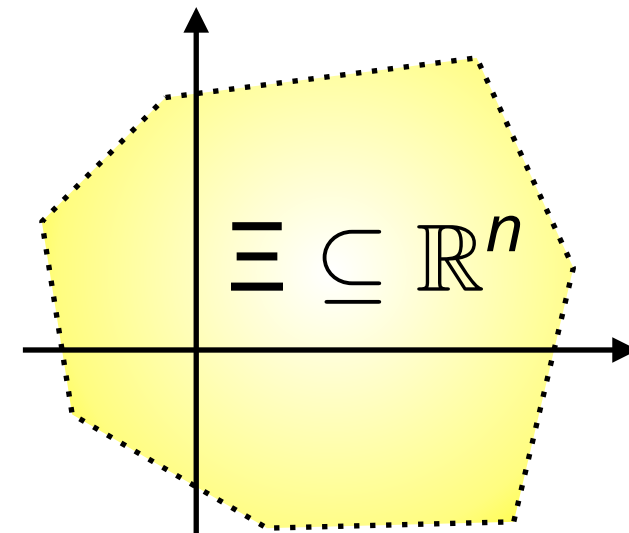
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open polyhedron



$$\Xi = \{ \xi : a_i^\top \xi < b_i \ \forall i = 1, \dots, k \}$$

Gauss: \mathcal{P} = set of all unimodal distributions with mean μ and variance σ^2
 $\Xi = \{ \xi : \mu - k\sigma < \xi < \mu + k\sigma \}$

Multivariate Chebyshev Bound

$$\mathcal{P}(\boldsymbol{\mu}, \boldsymbol{S}) = \left\{ \mathbb{P} : \mathbb{E}_{\mathbb{P}}(\boldsymbol{\xi}) = \boldsymbol{\mu}, \mathbb{E}_{\mathbb{P}}(\boldsymbol{\xi}\boldsymbol{\xi}^{\top}) = \boldsymbol{S} \right\}$$

Multivariate Chebyshev Bound

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Vandenberghe, Boyd, Comanor (2007):

$$\begin{aligned} \sup_{\mathbb{P} \in \mathcal{P}(\boldsymbol{\mu}, \mathbf{S})} \mathbb{P}(\boldsymbol{\xi} \notin \Xi) &= \max \sum_{i=1}^k \lambda_i \\ \text{s.t. } & \mathbf{a}_i^{\top} \mathbf{z}_i \geq b_i \lambda_i \quad \forall i = 1, \dots, k \\ & \sum_{i=1}^k \begin{pmatrix} \mathbf{z}_i & \mathbf{z}_i \\ \mathbf{z}_i^{\top} & \lambda_i \end{pmatrix} \preceq \begin{pmatrix} \mathbf{S} & \boldsymbol{\mu} \\ \boldsymbol{\mu}^{\top} & 1 \end{pmatrix} \\ & \begin{pmatrix} \mathbf{z}_i & \mathbf{z}_i \\ \mathbf{z}_i^{\top} & \lambda_i \end{pmatrix} \succeq 0 \quad \forall i = 1, \dots, k \end{aligned}$$

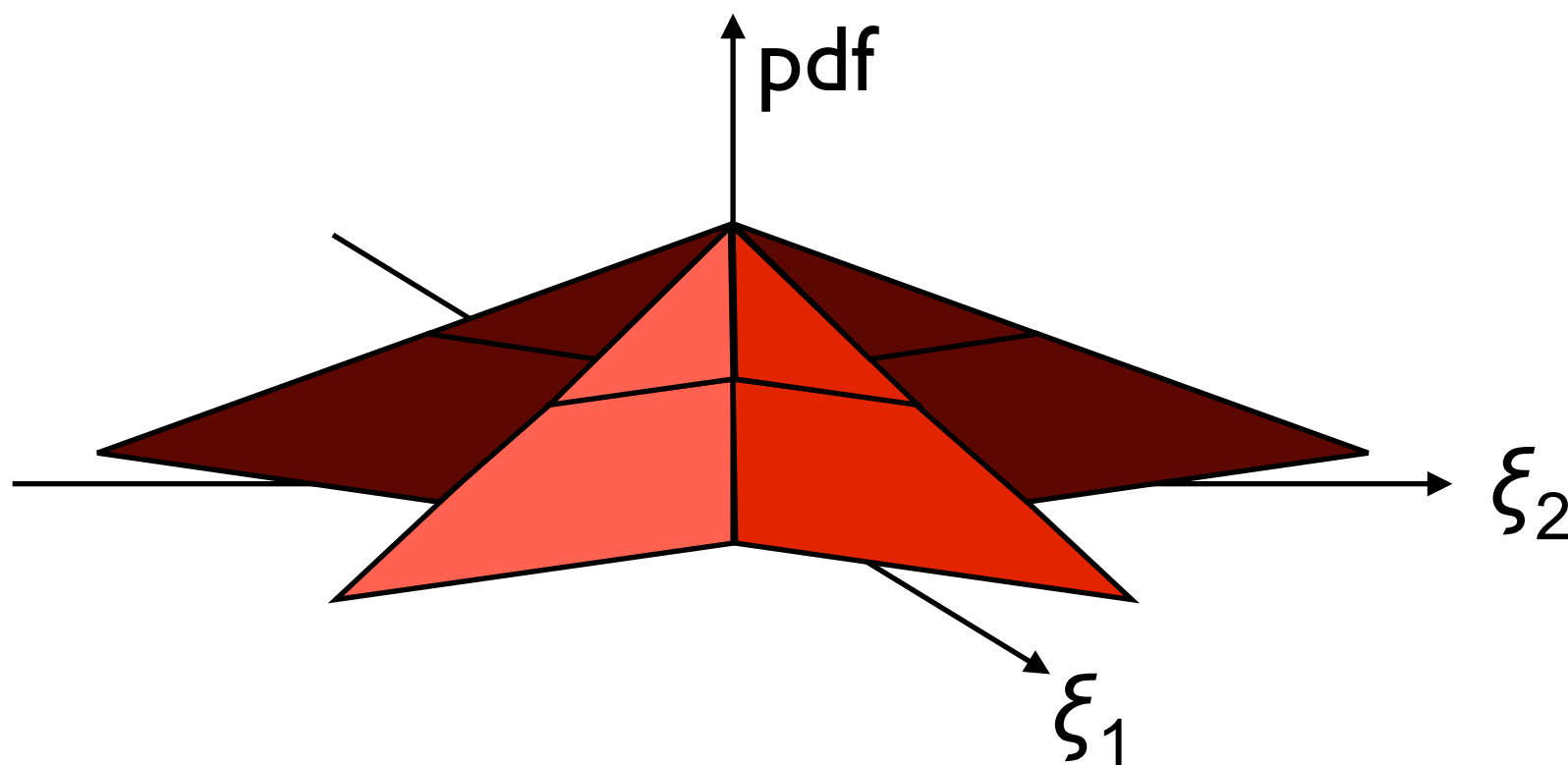
Multivariate Gauss Bound

$$\mathcal{P}_\star(\mu, S) = \{ \mathbb{P} \text{ star-unimodal} : \mathbb{E}_{\mathbb{P}}(\xi) = \mu, \mathbb{E}_{\mathbb{P}}(\xi\xi^\top) = S \}$$

Multivariate Gauss Bound

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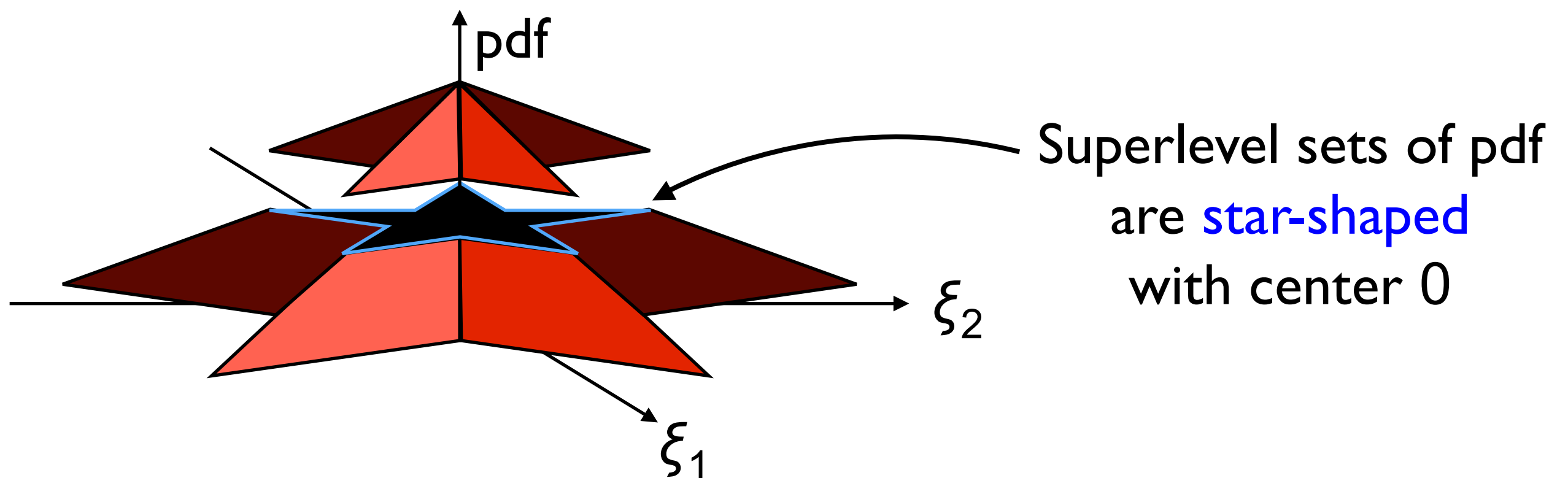
Definition: If \mathbb{P} has a continuous pdf f , then \mathbb{P} is star-unimodal if $f(t\xi)$ is non-increasing in $t > 0$ for all $\xi \neq 0$.



Multivariate Gauss Bound

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Van Parys, Goulart, K. (2014):

$$\begin{aligned} \sup_{\mathbb{P} \in \mathcal{P}_\star(\mu, S)} \mathbb{P}(\xi \notin \Xi) &= \max \sum_{i=1}^k \lambda_i - \tau_i \\ \text{s.t. } & \mathbf{a}^\top \mathbf{z}_i \geq 0, \tau_i \geq 0 \quad \forall i = 1, \dots, k \\ & \tau_i (\mathbf{a}_i^\top \mathbf{z}_i)^n \geq \lambda_i^{n+1} b_i^n \quad \forall i = 1, \dots, k \\ & \sum_{i=1}^k \begin{pmatrix} \mathbf{z}_i & \mathbf{z}_i \\ \mathbf{z}_i^\top & \lambda_i \end{pmatrix} \preceq \begin{pmatrix} \frac{n+2}{n} S & \frac{n+1}{n} \mu \\ \frac{n+1}{n} \mu^\top & 1 \end{pmatrix} \\ & \begin{pmatrix} \mathbf{z}_i & \mathbf{z}_i \\ \mathbf{z}_i^\top & \lambda_i \end{pmatrix} \succeq 0 \quad \forall i = 1, \dots, k \end{aligned}$$

State-of-the-Art: The Duality Method

- Worst-case probability problem is an **infinite-dimensional LP**;
- Dual LP is a **semi-infinite LP/robust optimization problem**;
- Dual can often be reformulated as a **tractable conic program**:
 - * Bertsimas & Popescu (2005): SOS techniques
 - * Popescu (2005): SOS techniques and Choquet theory;
 - * Boyd, Vandenberghe & Comanor (2007): \mathcal{S} -lemma;
 - * Delage & Ye (2010): Ellipsoid method;
 - * Zymler, K. & Rustem (2013): Farkas lemma and \mathcal{S} -lemma;
 - * etc.

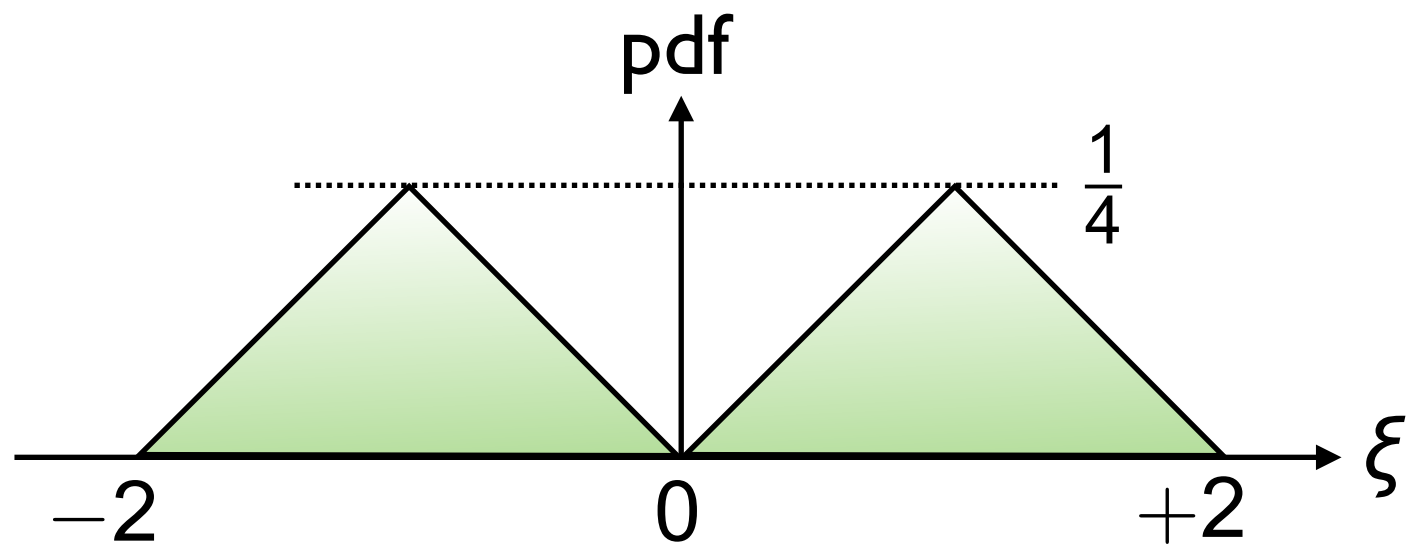
- Different Degrees of Unimodality
- Choquet Representations
 - The Set of All Distributions
 - The Set of Star-unimodal Distributions
 - The Set of α -Unimodal Distributions
- Generalized Probability Bounds
 - Feasibility Conditions
 - Structure of Extremal Distributions
 - SDP Reformulation
- Extensions

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Different Degrees of Unimodality

Definition: If \mathbb{P} has a continuous pdf f , then \mathbb{P} is α -unimodal if $t^{n-\alpha}f(t\xi)$ is non-increasing in $t > 0$ for all $\xi \neq 0$.

Example: $n = 1, \alpha = 2$

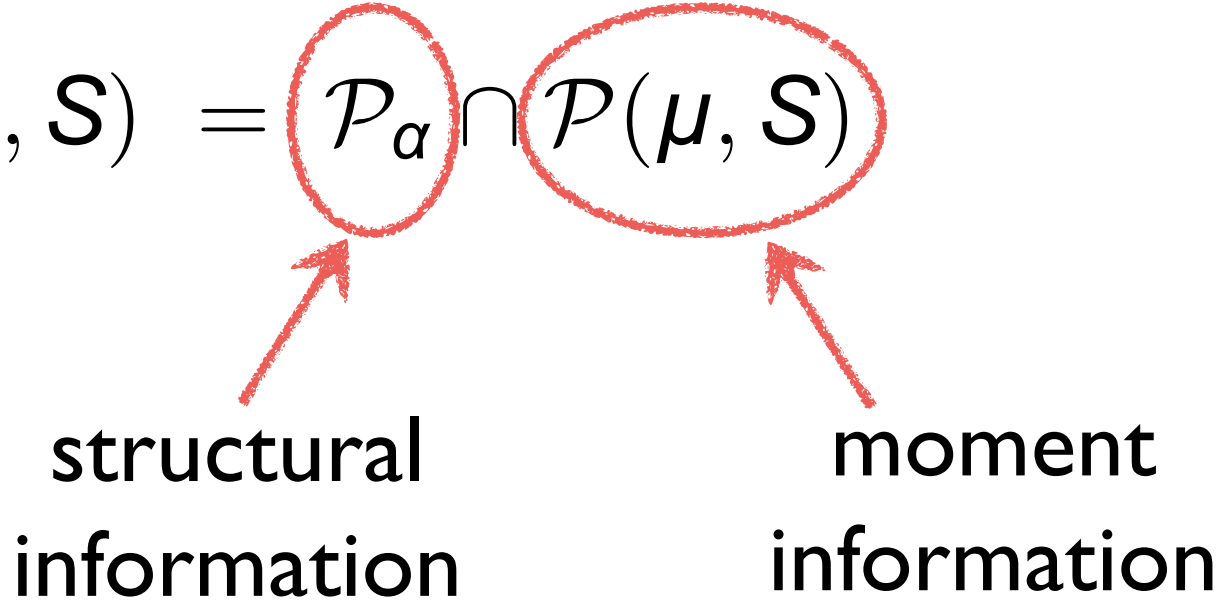


Definition: \mathcal{P}_α = weak closure of the set of all α -unimodal distributions.

α -Unimodal Probability Bounds

Goal: Compute $\sup_{\mathbb{P} \in \mathcal{P}_\alpha(\mu, S)} \mathbb{P}(\xi \notin \Xi)$

Ambiguity set: $\mathcal{P}_\alpha(\mu, S) = \mathcal{P}_\alpha \cap \mathcal{P}(\mu, S)$



The diagram illustrates the ambiguity set $\mathcal{P}_\alpha(\mu, S)$ as the intersection of two sets: \mathcal{P}_α and $\mathcal{P}(\mu, S)$. Both sets are circled in red. A red arrow points from the text "structural information" to the circle around \mathcal{P}_α . Another red arrow points from the text "moment information" to the circle around $\mathcal{P}(\mu, S)$.

structural
information

moment
information

α -Unimodal Probability Bounds

Goal: Compute $\sup_{\mathbb{P} \in \mathcal{P}_\alpha(\mu, S)} \mathbb{P}(\xi \notin \Xi)$

Ambiguity set: $\mathcal{P}_\alpha(\mu, S) = \mathcal{P}_\alpha \cap \mathcal{P}(\mu, S)$

Special cases: $\text{cl}(\cup_{\alpha=1}^{\infty} \mathcal{P}_\alpha) = \mathcal{P}_\infty = \text{set of all distributions}$
 \implies Generalized Chebyshev bounds

$\mathcal{P}_n = \text{set of all star-unimodal distributions}$
 \implies Generalized Gauss bounds

☒ **Different Degrees of Unimodality**

☐ Choquet Representations

- ☐ The Set of All Distributions

- ☐ The Set of Star-unimodal Distributions

- ☐ The Set of α -Unimodal Distributions

☐ Generalized Probability Bounds

- ☐ Feasibility Conditions

- ☐ Structure of Extremal Distributions

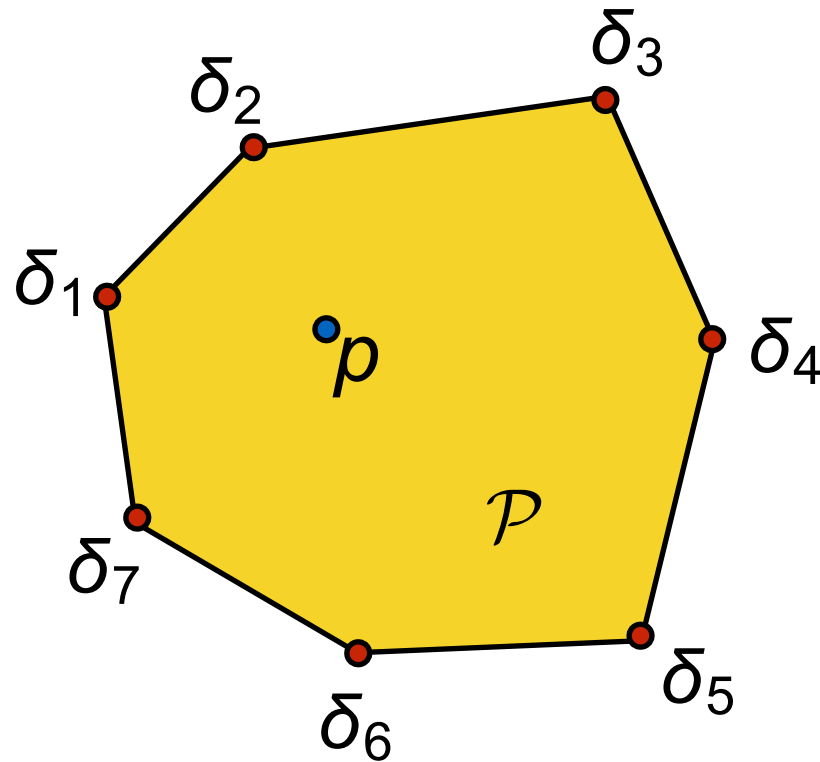
- ☐ SDP Reformulation

☐ Extensions

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Choquet Representations

Minkowski: Every point in a compact convex set $\mathcal{P} \subset \mathbb{R}^n$ is the mean of a distribution on $\text{ex}\mathcal{P}$.

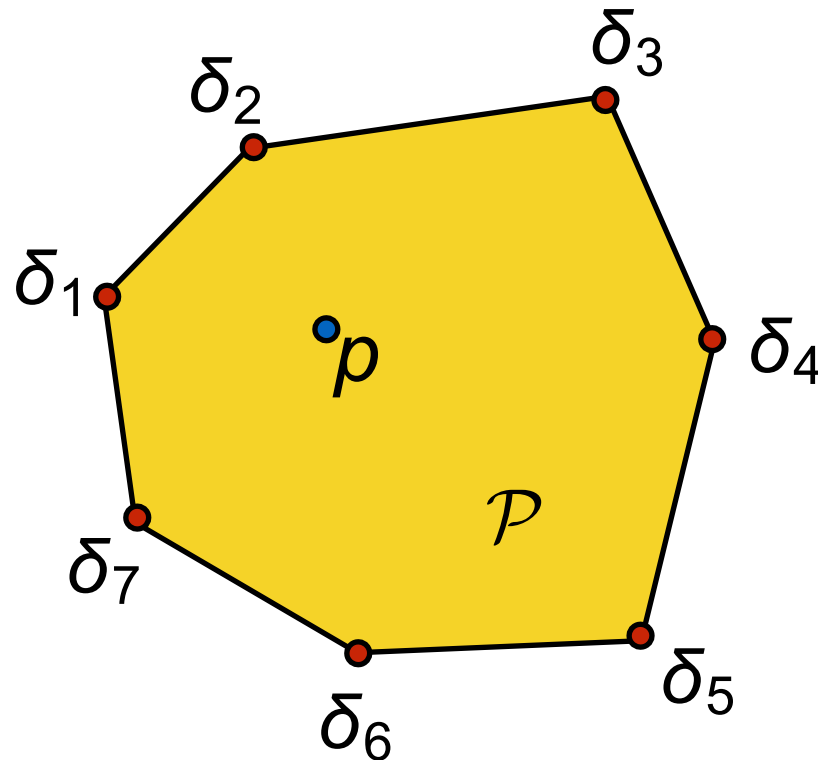


$$p = \sum_i m_i \delta_i$$

probability
distribution on $\text{ex } \mathcal{P}$

Choquet Representations

Minkowski: Every point in a compact convex set $\mathcal{P} \subset \mathbb{R}^n$ is the mean of a distribution on $\text{ex}\mathcal{P}$.



$$p = \sum_i m_i \delta_i$$

probability distribution on $\text{ex } \mathcal{P}$

A red arrow points from the text "probability distribution on $\text{ex } \mathcal{P}$ " to the coefficient m_i in the equation above.

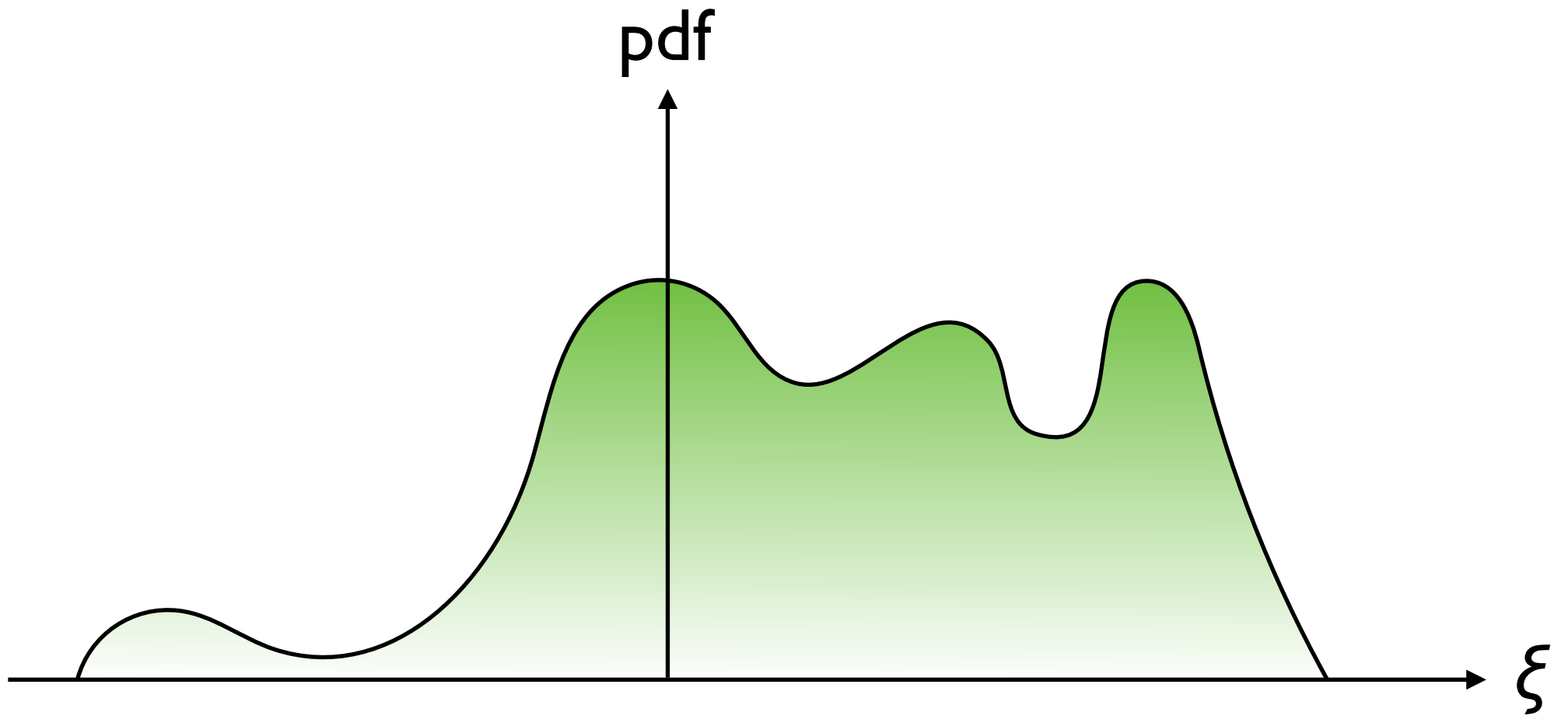
A convex set \mathcal{P} of distributions admits a **Choquet representation** if $\forall \mathbb{P} \in \mathcal{P}$ there is a distribution m on $\text{ex } \mathcal{P}$ with:

$$\mathbb{P}(\cdot) = \int_{\text{ex } \mathcal{P}} \delta(\cdot) m(d\delta) \quad \text{mixture distribution}$$

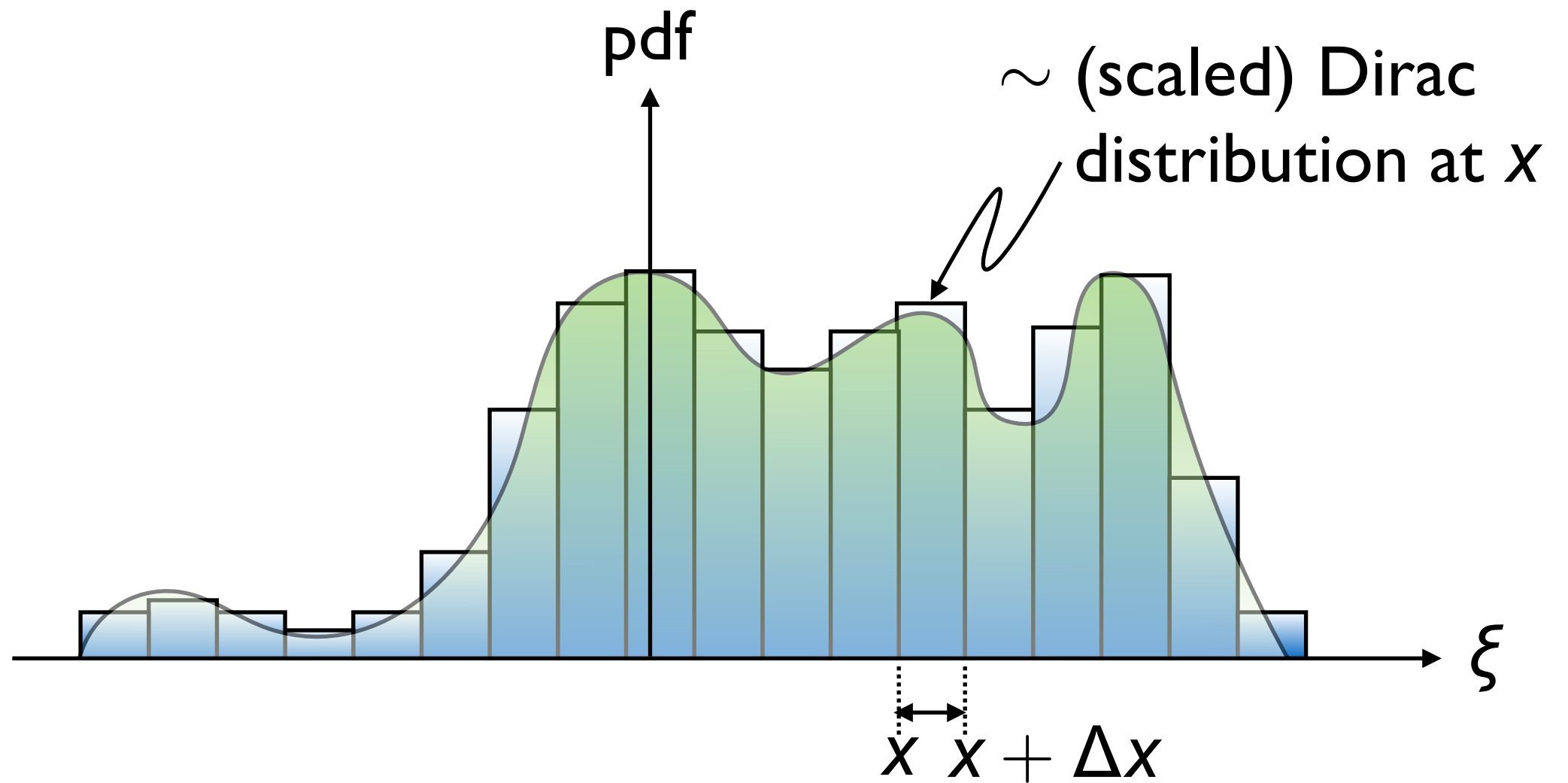
A red curved arrow points from the text "mixture distribution" to the measure $m(d\delta)$ in the integral above.

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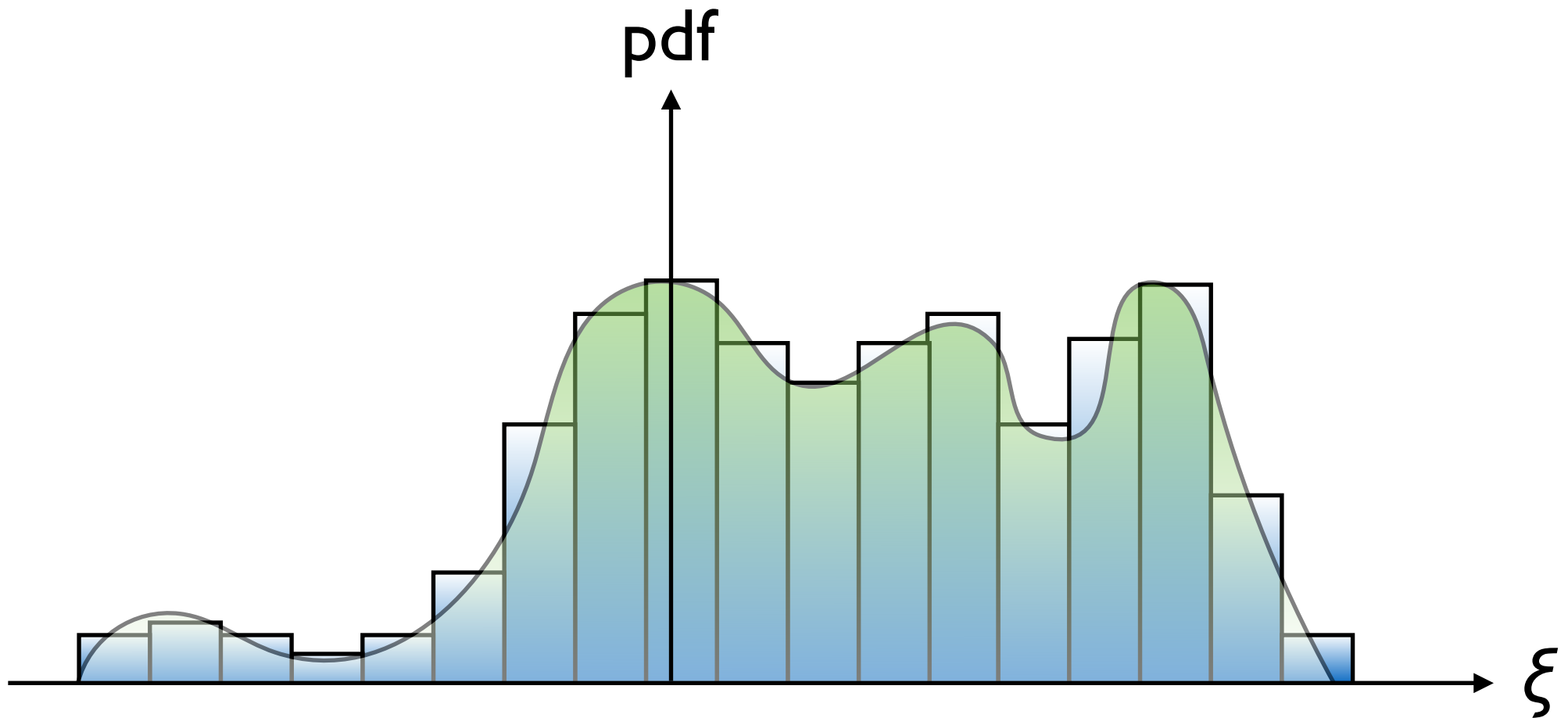
The Set of all Distributions



The Set of all Distributions



The Set of all Distributions



$$\mathbb{P}(\cdot) = \int_{\mathbb{R}^n} \delta_x(\cdot) \mathbb{P}(\mathrm{d}\mathbf{x})$$

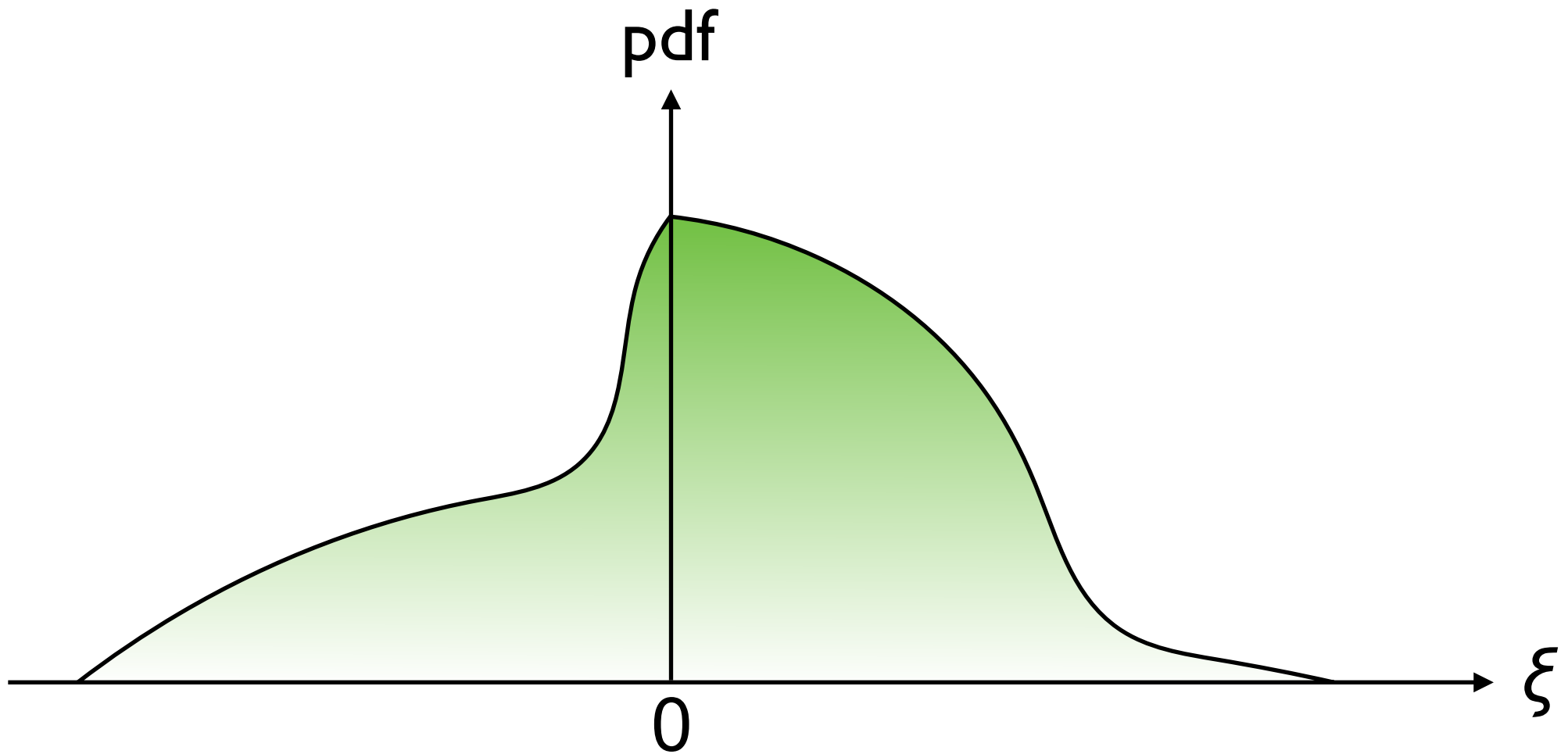
Dirac distribution at x

mixture distribution $m \equiv \mathbb{P}$

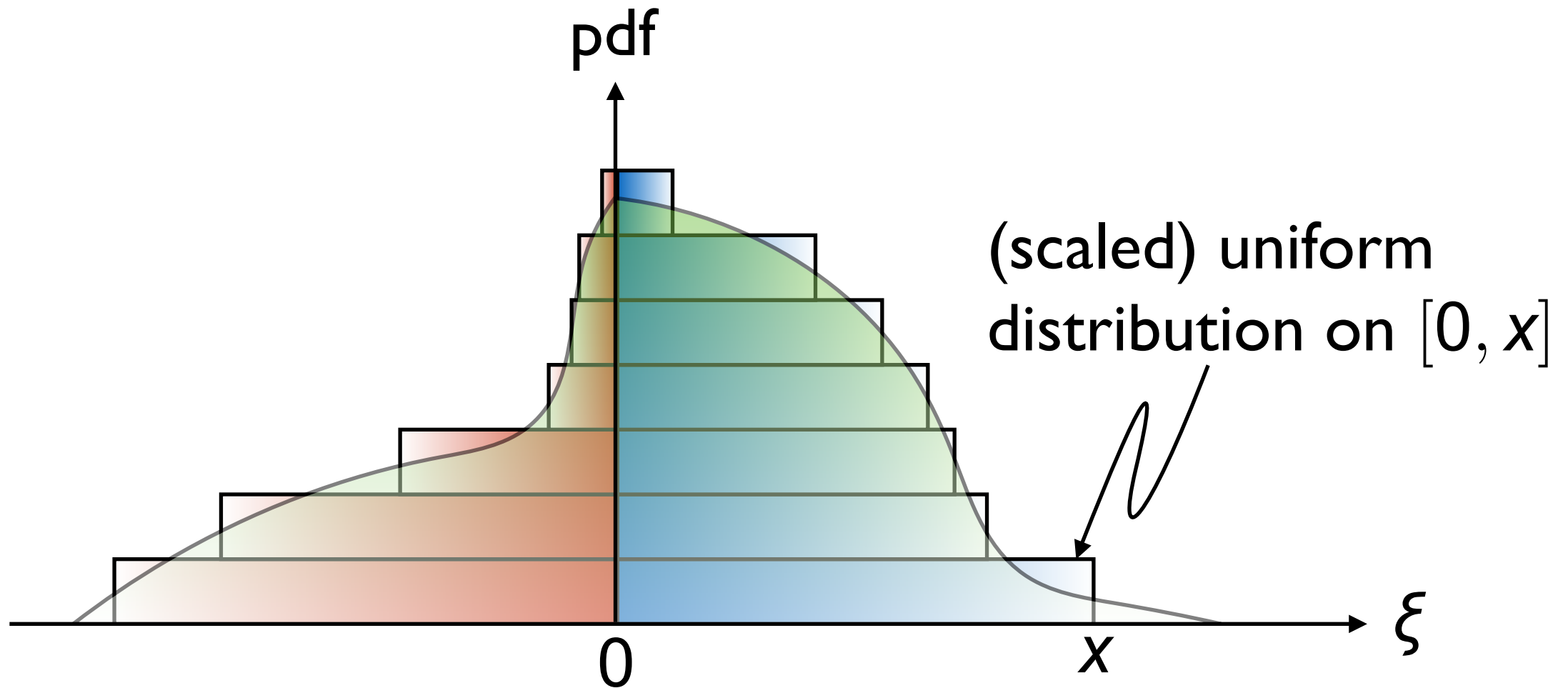
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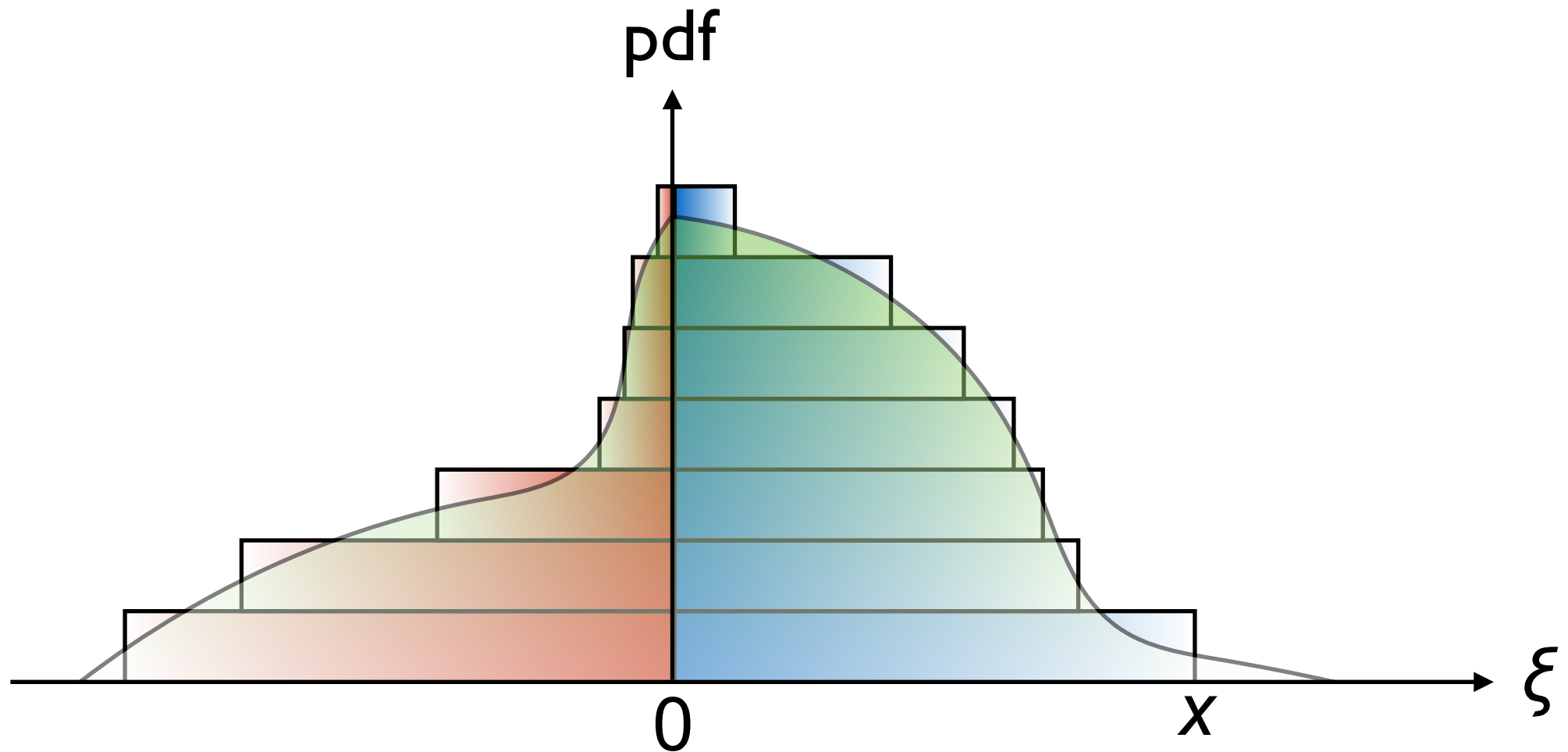
Unimodal Univariate Distributions



Unimodal Univariate Distributions



Unimodal Univariate Distributions

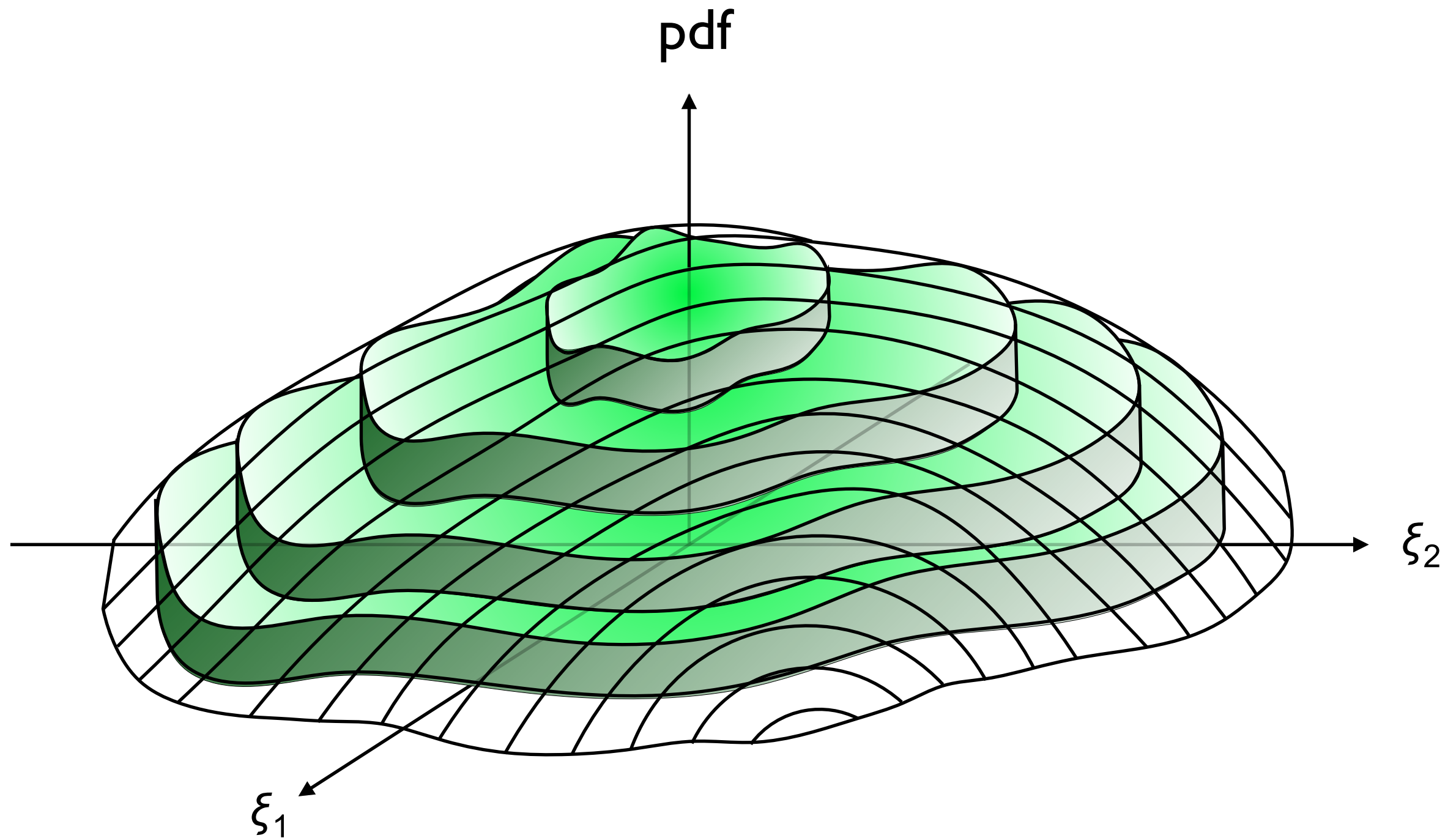


Khinchine (1938):
$$\mathbb{P}(\cdot) = \int_{-\infty}^{+\infty} \delta_{[0,x]}^1(\cdot) m(dx)$$

$\delta_{[0,x]}^1(\cdot)$ uniform distribution on $[0, x]$

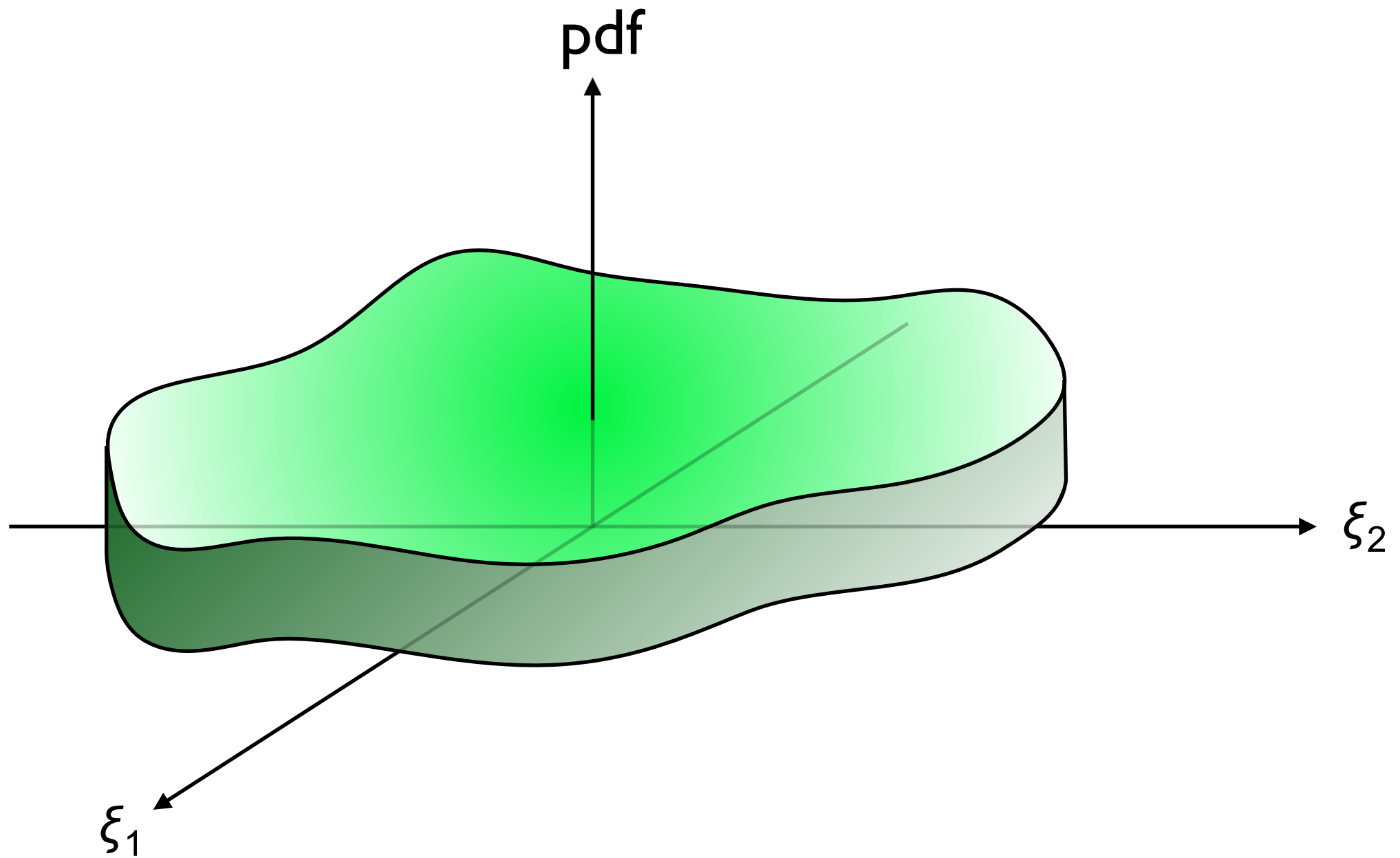
$m(dx)$ mixture distribution

Unimodal Bivariate Distributions

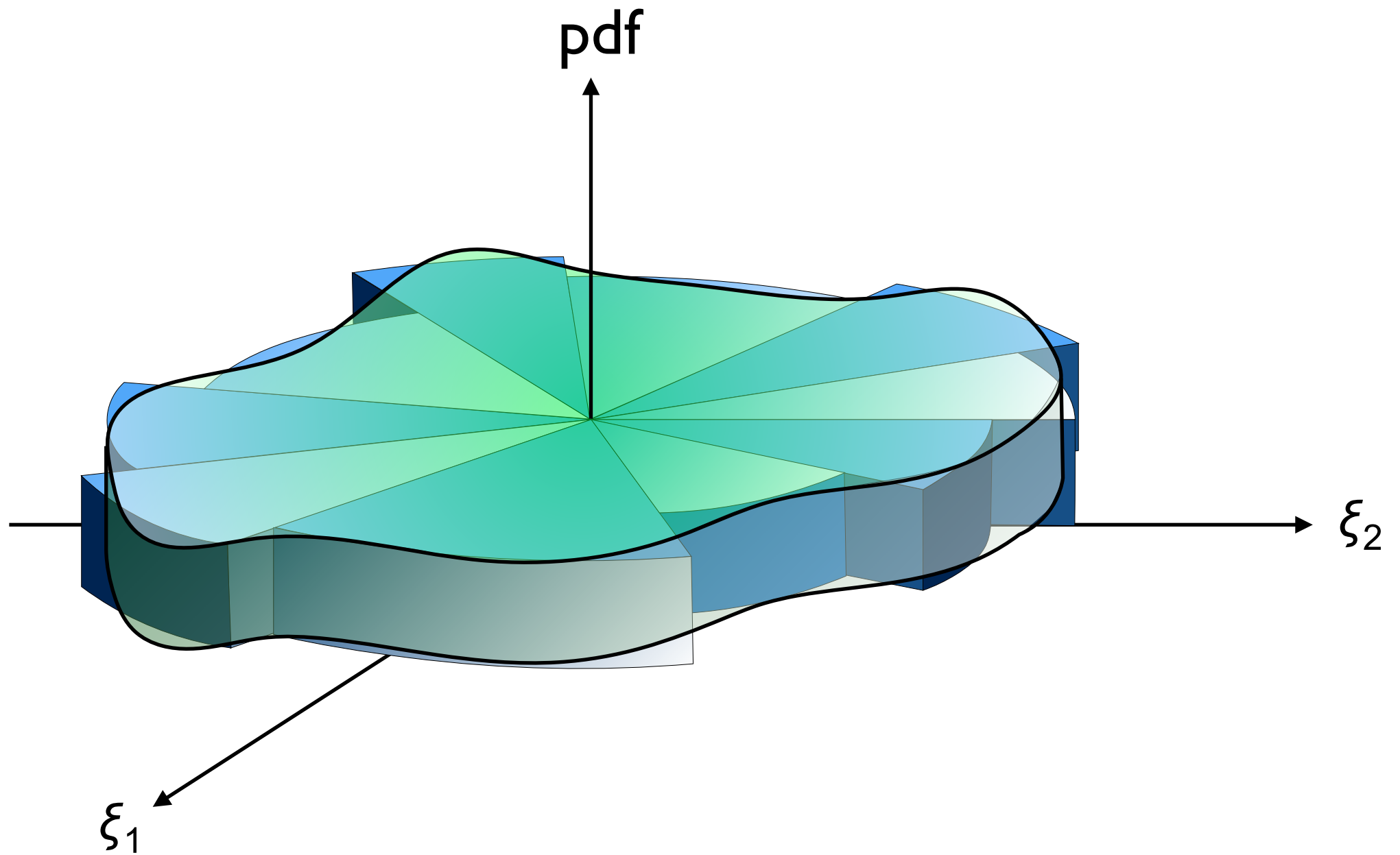


Multivariate unimodal distributions can be decomposed into **uniform distributions on star-shaped sets**.

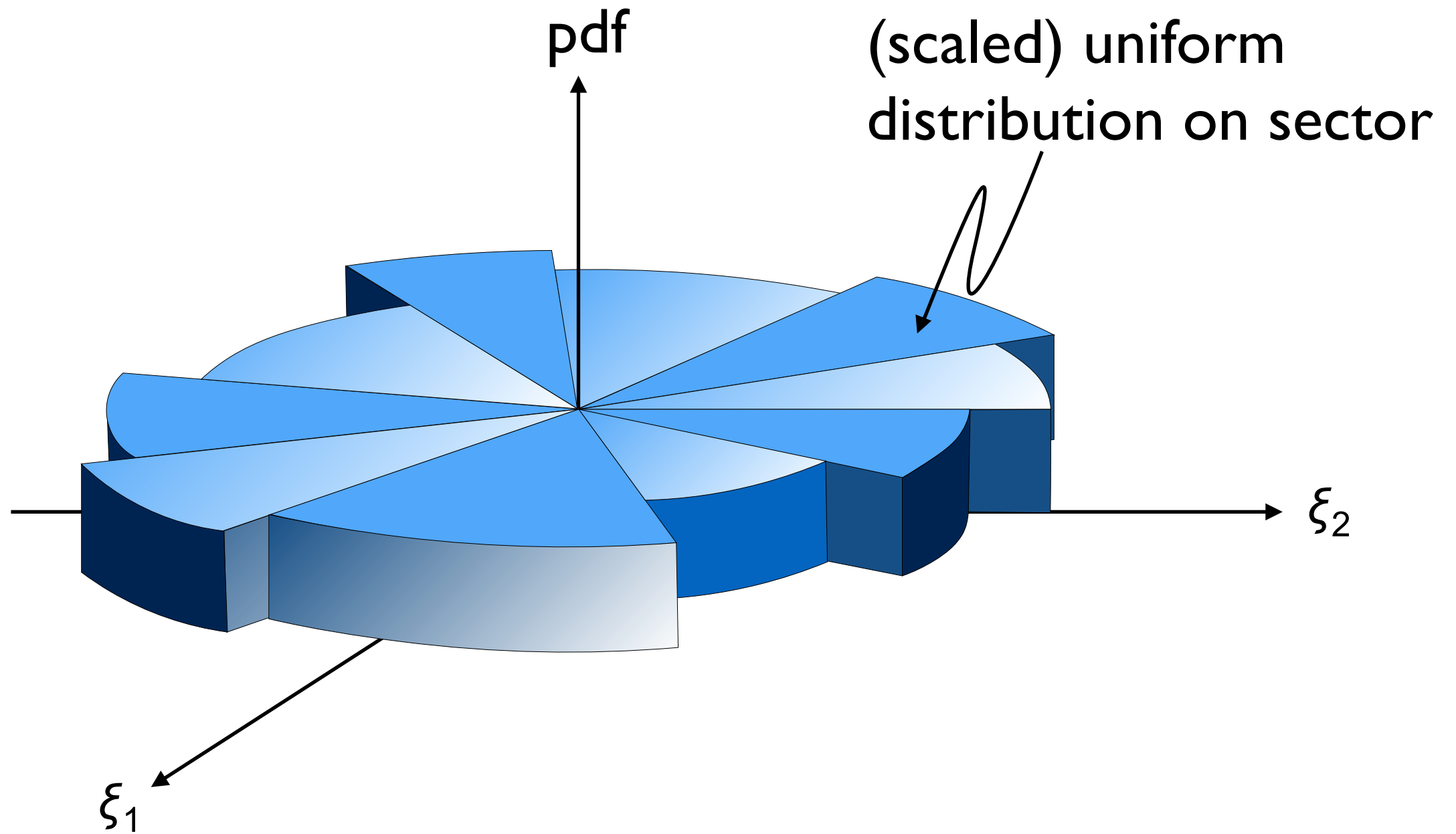
Uniform Distributions on Star-shaped Sets



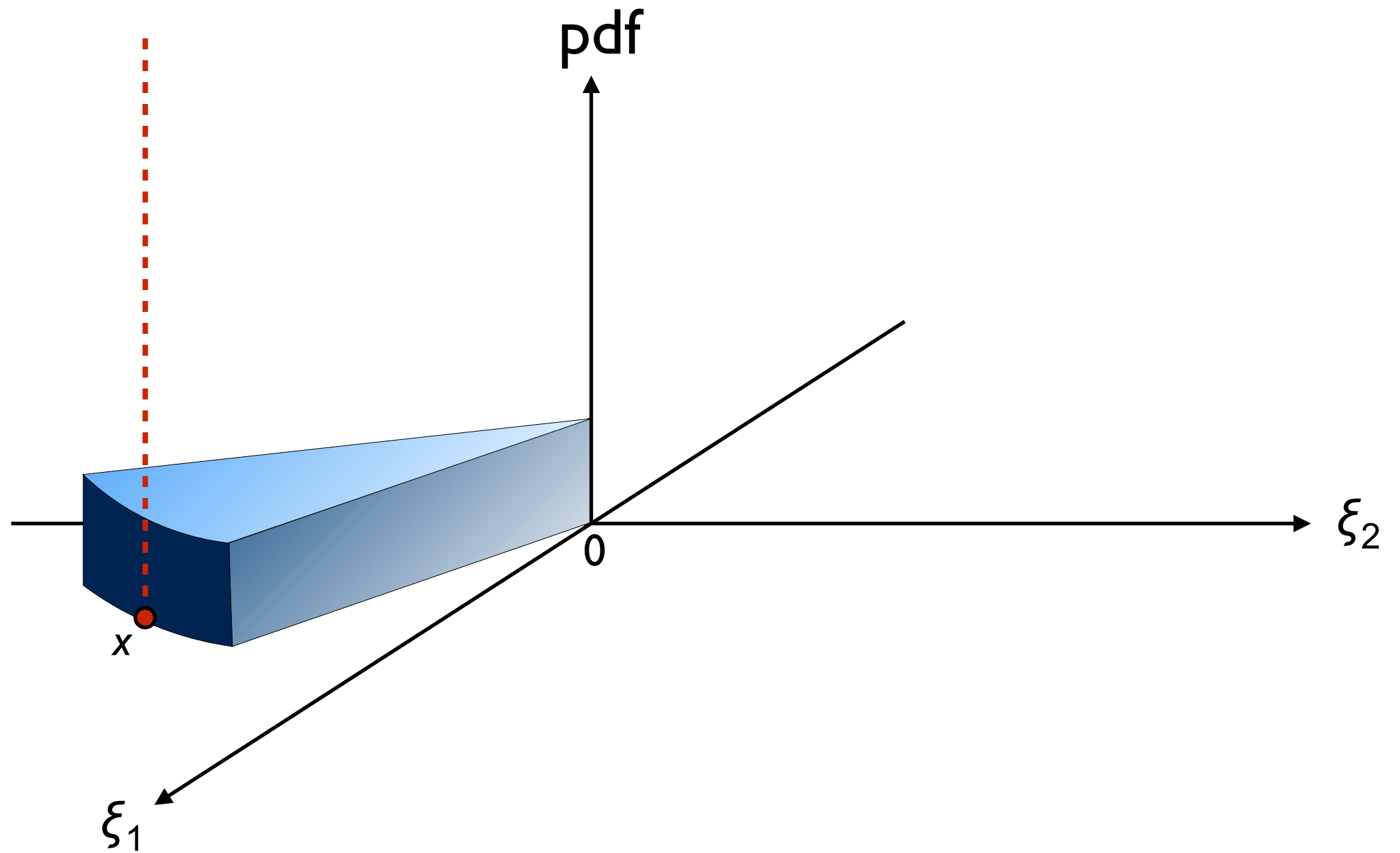
Uniform Distributions on Star-shaped Sets



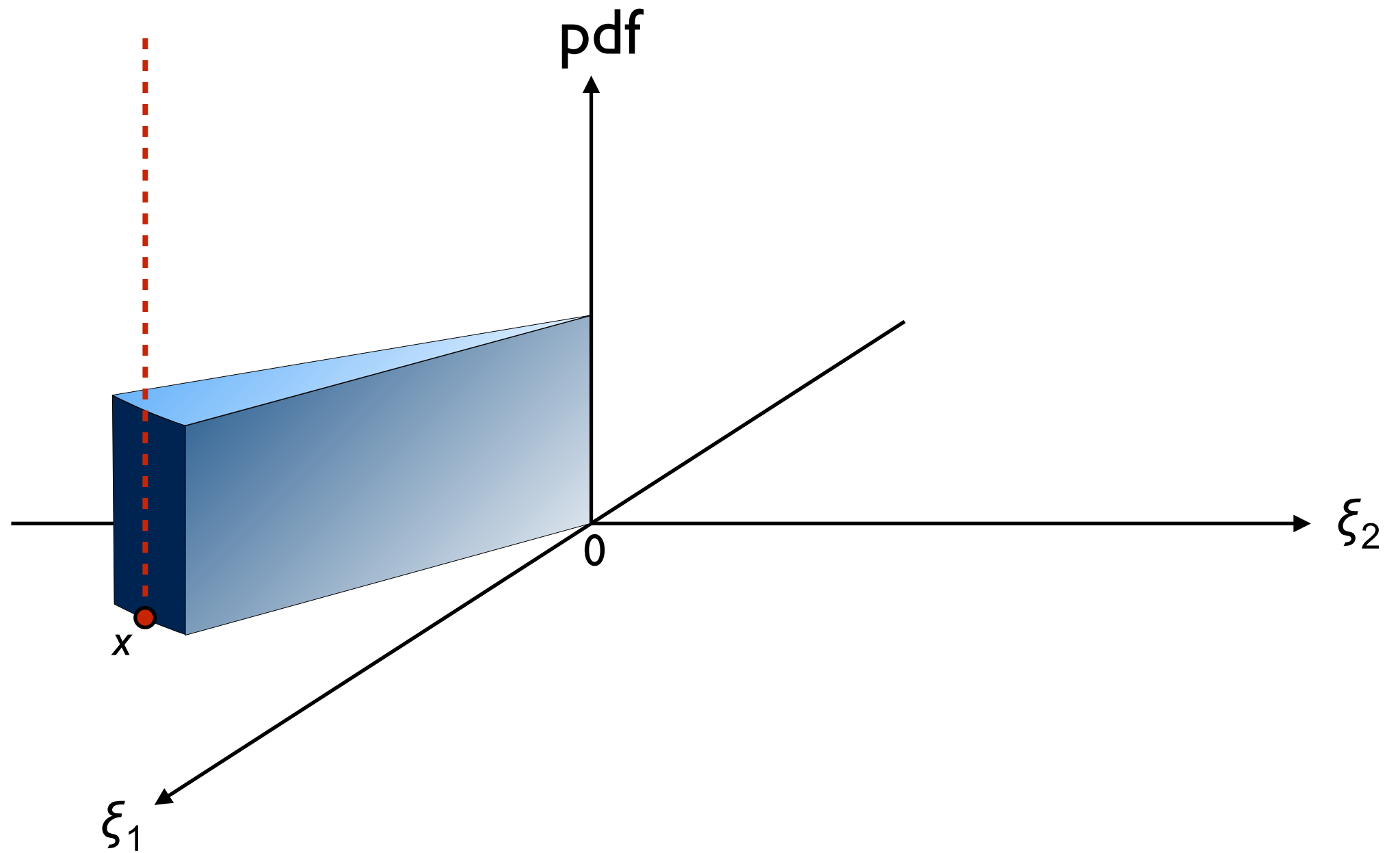
Uniform Distributions on Star-shaped Sets



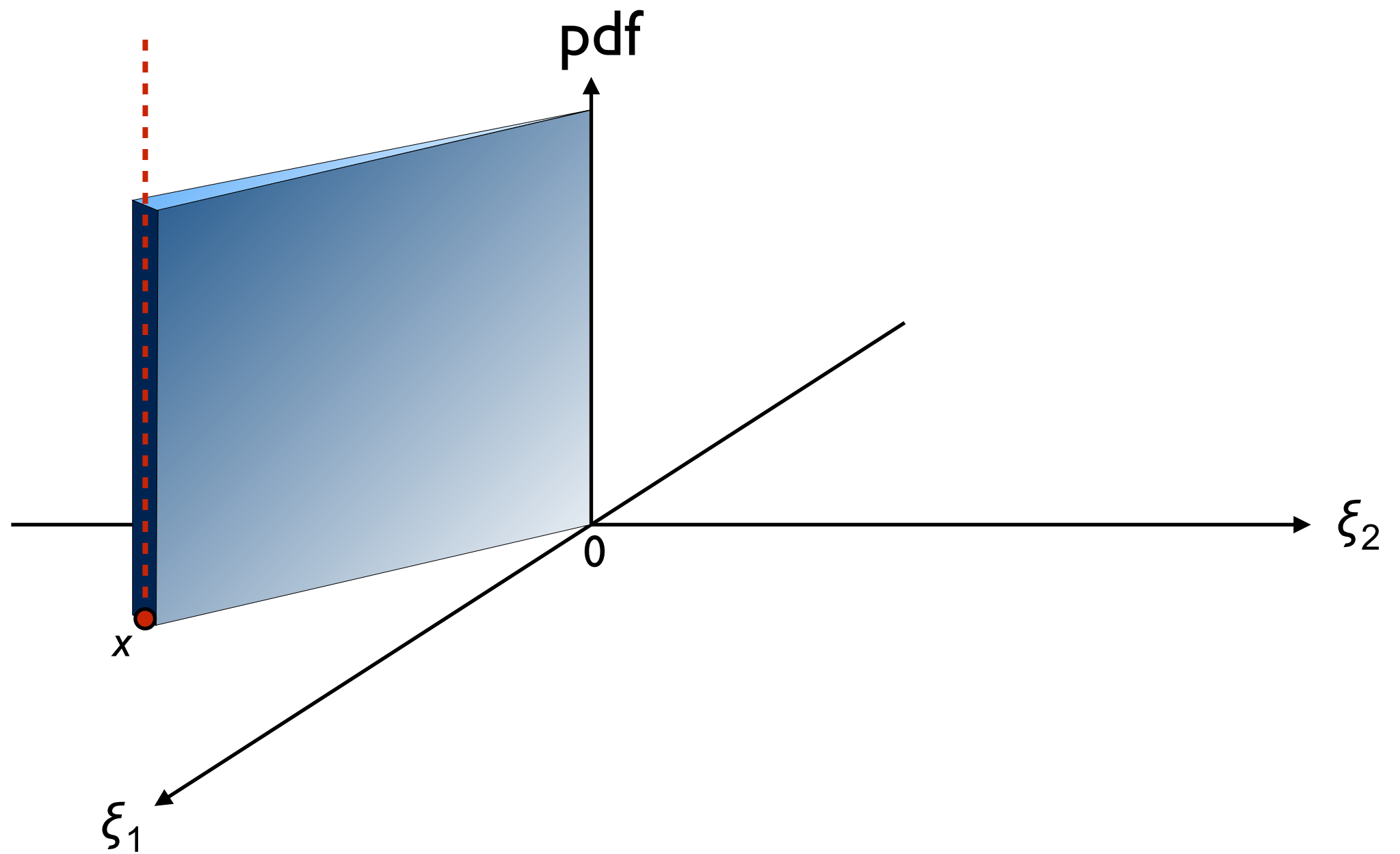
Radial Unimodal Distributions



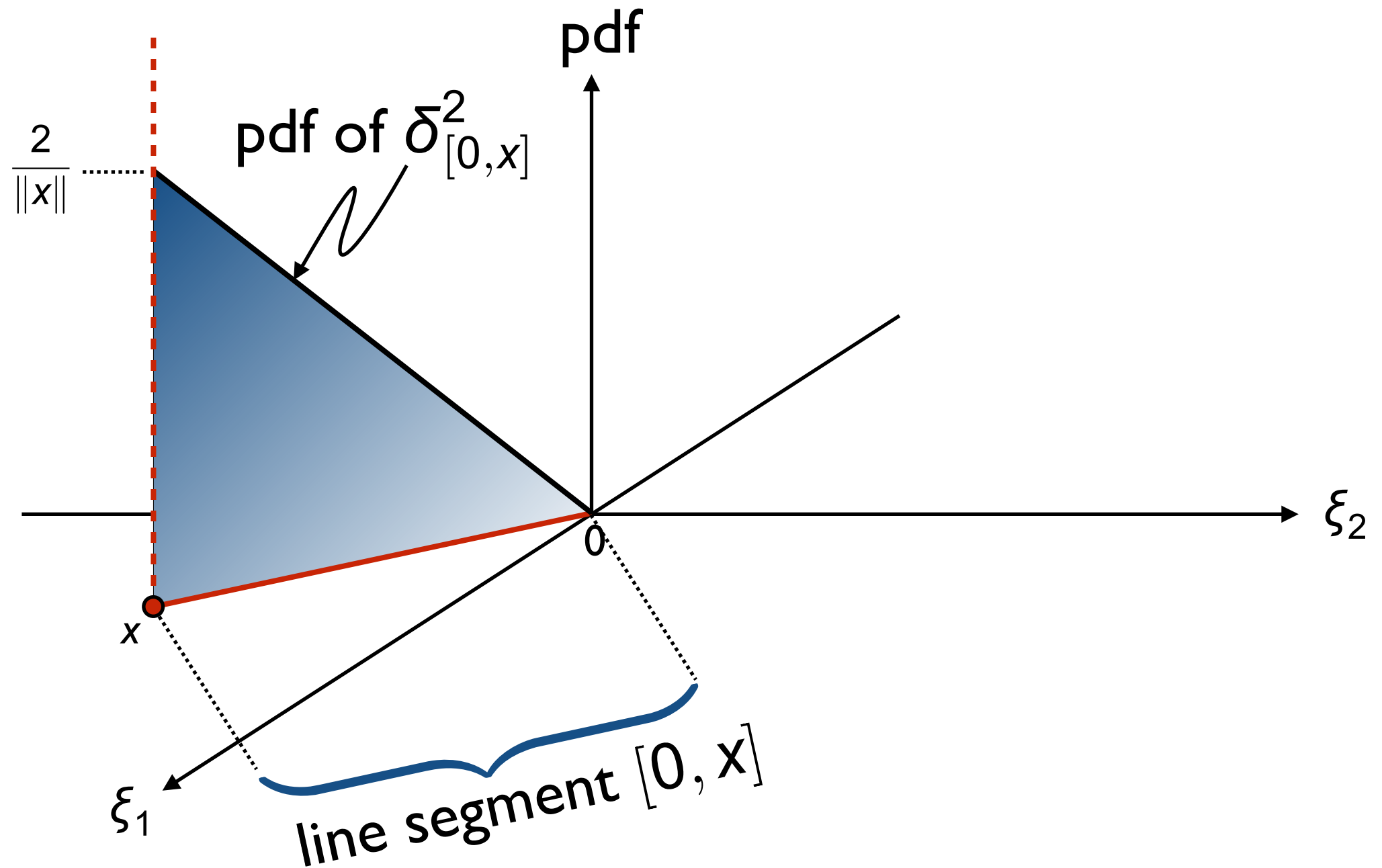
Radial Unimodal Distributions



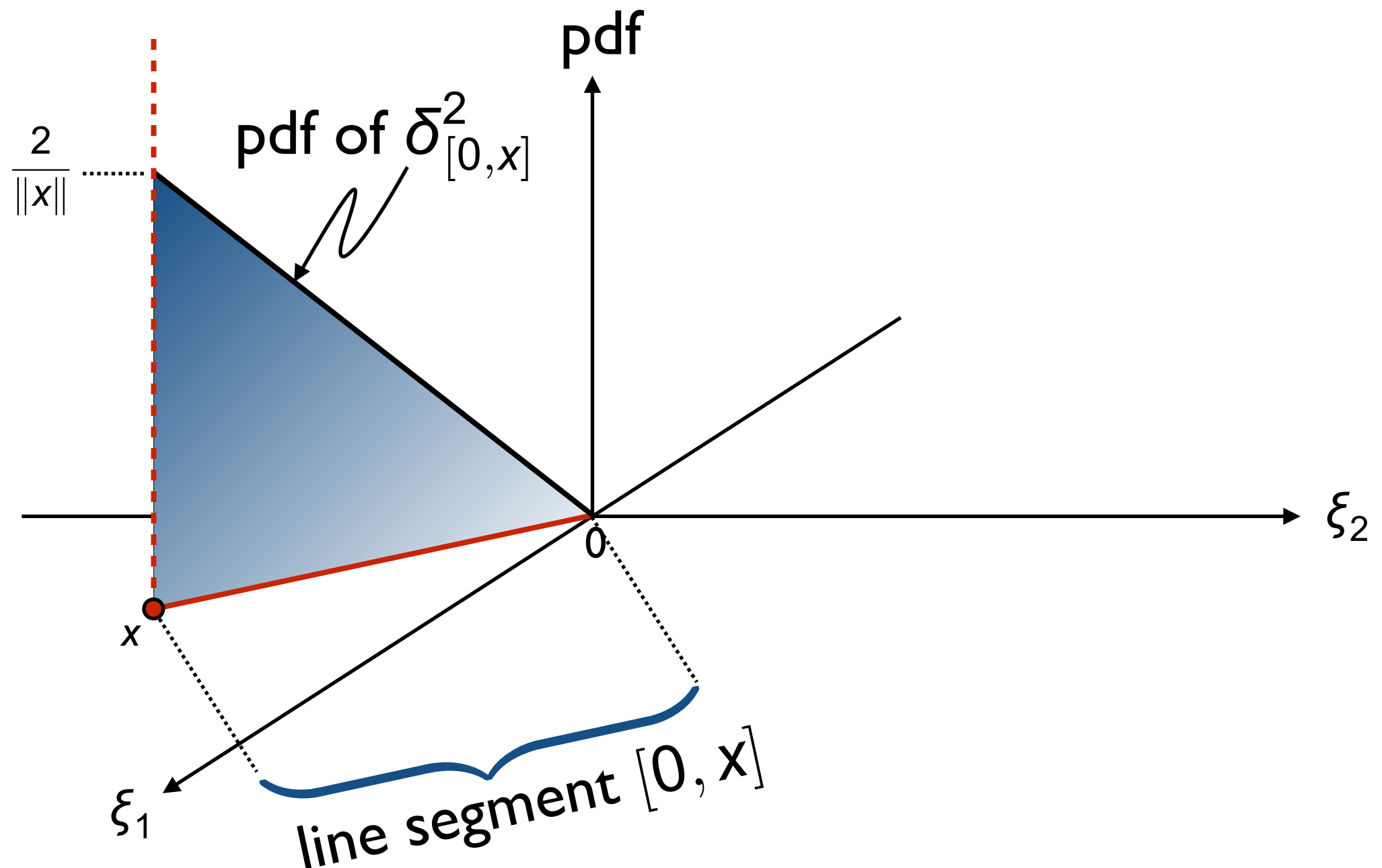
Radial Unimodal Distributions



Radial Unimodal Distributions

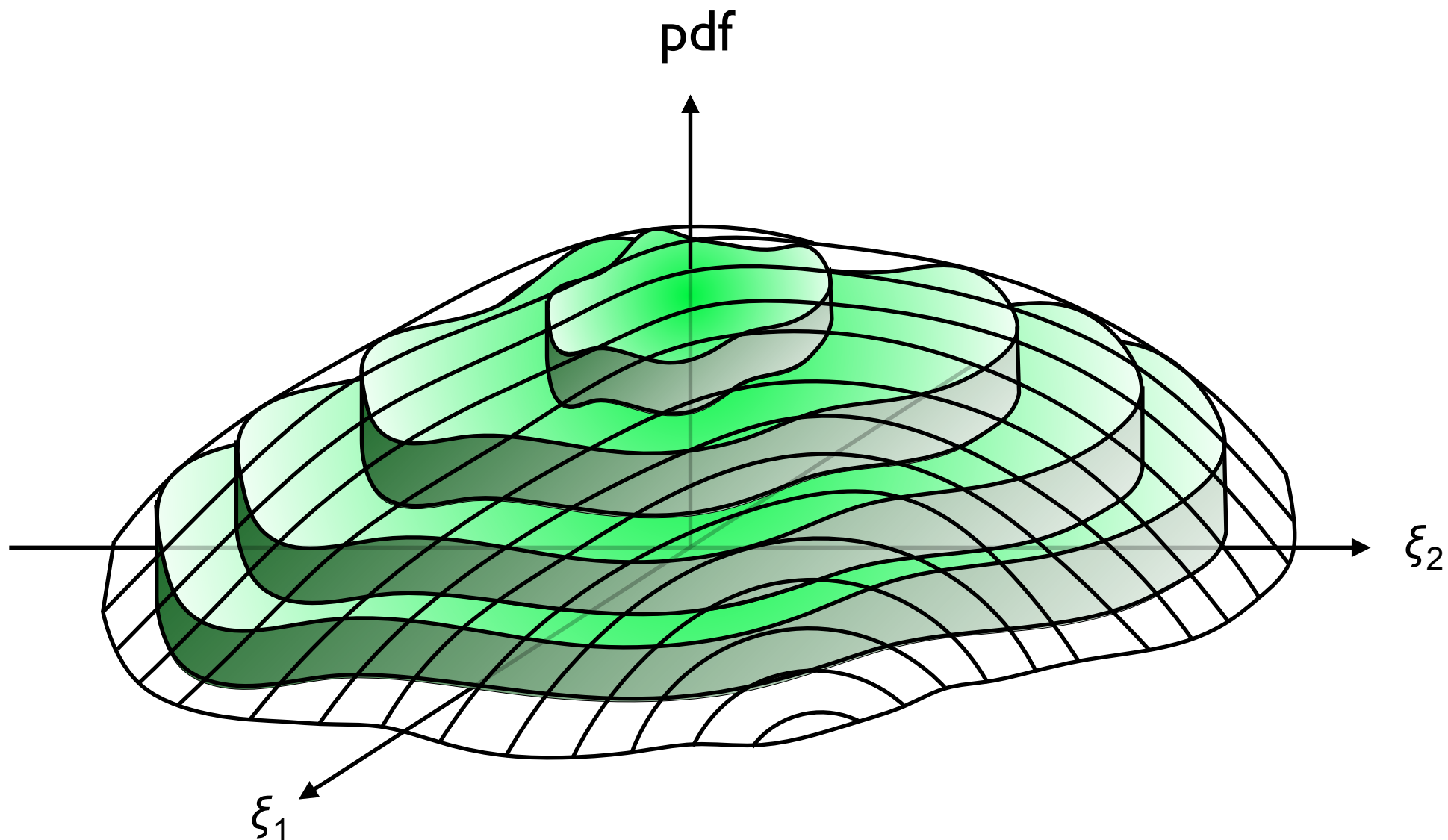


Radial Unimodal Distributions



$\delta^2_{[0,x]}$ is the distribution on $[0, x]$ with $\delta^2_{[0,x]}([0, tx]) = t^2 \forall t \in [0, 1]$.

Unimodal Bivariate Distributions



$$\mathbb{P}(\cdot) = \int_{-\infty}^{+\infty} \delta_{[0,x]}^2(\cdot) m(dx)$$

radial unimodal
distribution on $[0, x]$

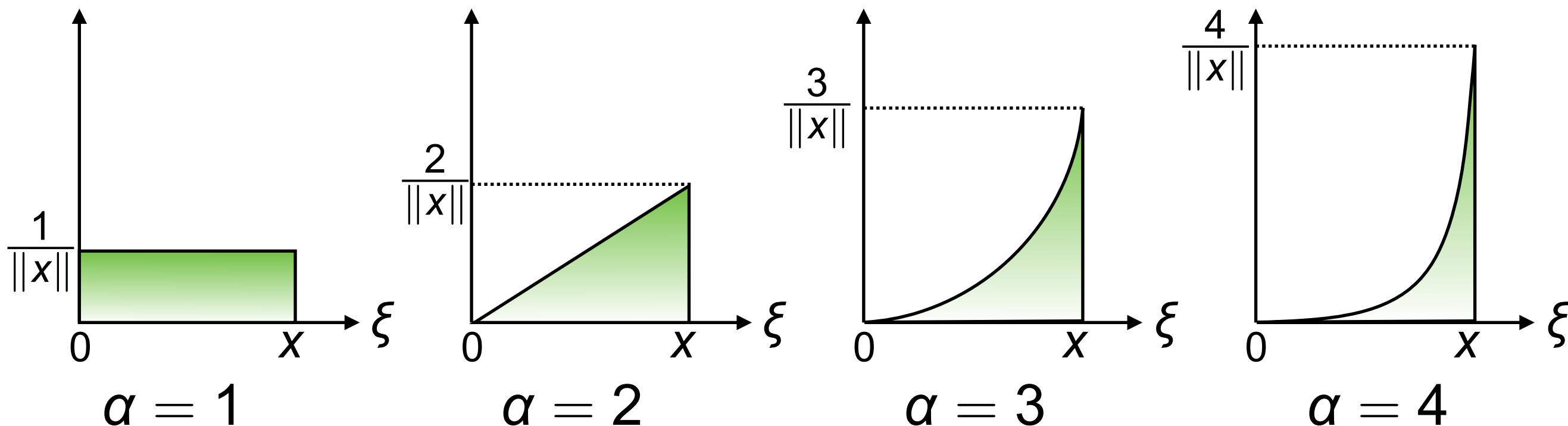
mixture
distribution

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Radial α -Unimodal Distributions

$\delta_{[0,x]}^\alpha$ is the distribution on $[0, x]$ with $\delta_{[0,x]}^\alpha([0, tx]) = t^\alpha \ \forall t \in [0, 1]$.



Dharmadhikari, Joag-Dev (1988):

$$\mathbb{P} \in \mathcal{P}_\alpha \quad \Longleftrightarrow \quad \exists! m \in \mathcal{P}_\infty : \mathbb{P}(\cdot) = \int_{\mathbb{R}^n} \delta_{[0,x]}^\alpha(\cdot) m(d\mathbf{x})$$

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Main Result

Theorem: If $0 \in \Xi$, then $\sup_{\mathbb{P} \in \mathcal{P}_\alpha(\mu, S)} \mathbb{P}(\xi \notin \Xi)$ is equivalent to:

$$\begin{aligned}
 & \max \quad \sum_{i=1}^k \lambda_i - \tau_i \\
 & \text{s.t.} \quad \mathbf{a}^\top \mathbf{z}_i \geq 0, \quad \tau_i \geq 0 \quad \forall i = 1, \dots, k \\
 & \quad \tau_i (\mathbf{a}_i^\top \mathbf{z}_i)^\alpha \geq \lambda_i^{\alpha+1} b_i^\alpha \quad \forall i = 1, \dots, k \\
 & \quad \sum_{i=1}^k \begin{pmatrix} \mathbf{Z}_i & \mathbf{z}_i \\ \mathbf{z}_i^\top & \lambda_i \end{pmatrix} \preceq \begin{pmatrix} \frac{n+2}{n} \mathbf{S} & \frac{n+1}{n} \boldsymbol{\mu} \\ \frac{n+1}{n} \boldsymbol{\mu}^\top & 1 \end{pmatrix} \\
 & \quad \begin{pmatrix} \mathbf{Z}_i & \mathbf{z}_i \\ \mathbf{z}_i^\top & \lambda_i \end{pmatrix} \succeq \mathbf{0} \quad \forall i = 1, \dots, k
 \end{aligned}$$

$\alpha \rightarrow \infty$: Generalized Chebyshev Bound

$\alpha = n$: Generalized Gauss Bound

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Feasibility Conditions

$$\mathcal{P}_\alpha(\mu, S) \neq \emptyset \quad \Longleftrightarrow \quad \begin{pmatrix} \frac{\alpha+2}{\alpha} S & \frac{\alpha+1}{\alpha} \mu \\ \frac{\alpha+1}{\alpha} \mu^\top & 1 \end{pmatrix} \succeq 0$$

Proof: $\mathbb{P} \in \mathcal{P}_\alpha$ iff $\mathbb{P}(\cdot) = \int \delta_{[0,x]}^\alpha(\cdot) m(dx)$ for $m \in \mathcal{P}_\infty$.

Feasibility Conditions

$$\mathcal{P}_\alpha(\mu, S) \neq \emptyset \quad \Longleftrightarrow \quad \begin{pmatrix} \frac{\alpha+2}{\alpha} S & \frac{\alpha+1}{\alpha} \mu \\ \frac{\alpha+1}{\alpha} \mu^\top & 1 \end{pmatrix} \succeq 0$$

Proof: $\mathbb{P} \in \mathcal{P}_\alpha$ iff $\mathbb{P}(\cdot) = \int \delta_{[0,x]}^\alpha(\cdot) m(dx)$ for $m \in \mathcal{P}_\infty$.

$$\begin{pmatrix} S & \mu \\ \mu^\top & 1 \end{pmatrix} = \begin{pmatrix} \frac{\alpha}{\alpha+2} S_m & \frac{\alpha}{\alpha+1} \mu_m \\ \frac{\alpha}{\alpha+1} \mu_m^\top & 1 \end{pmatrix}$$

Feasibility Conditions

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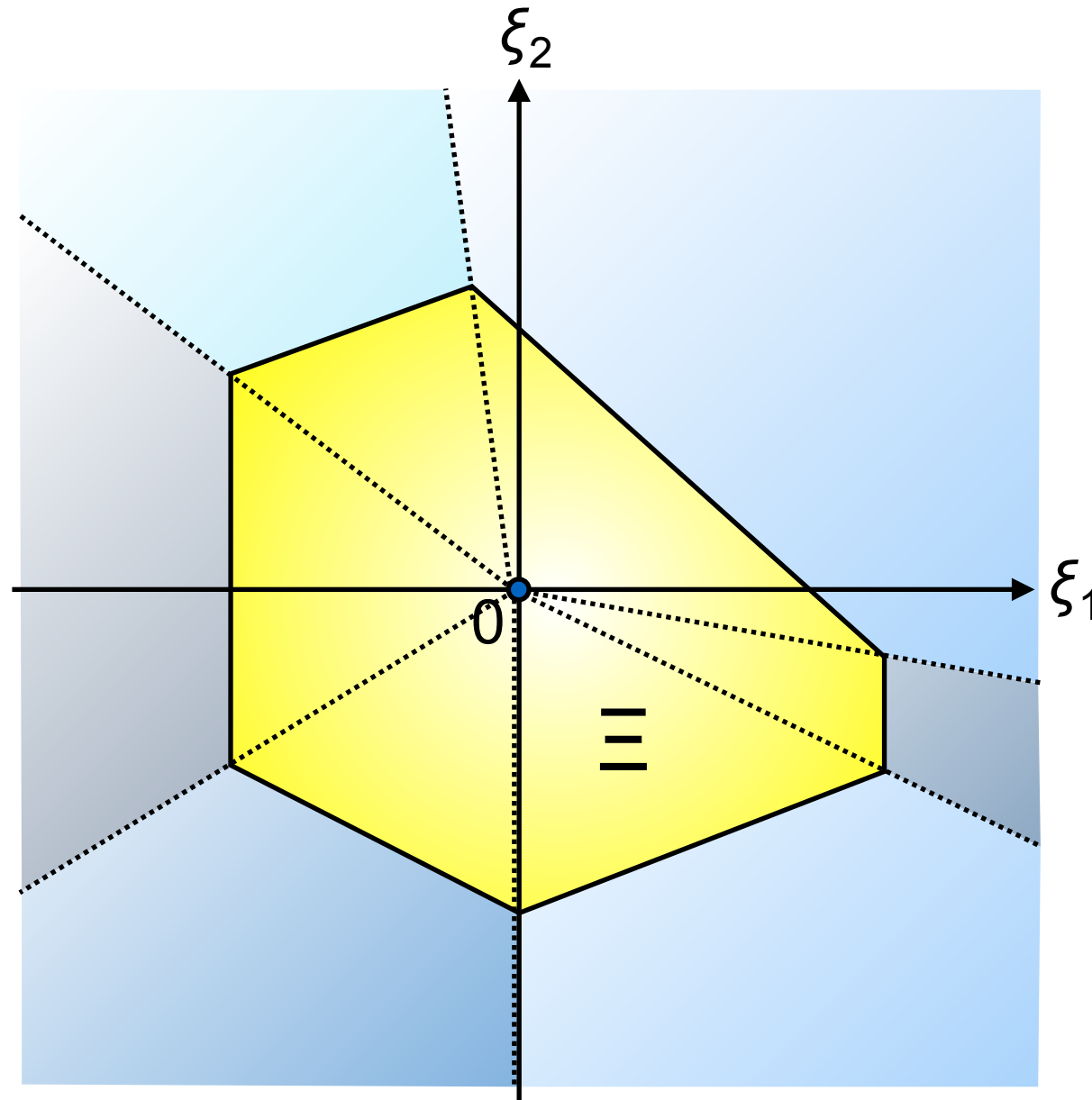
Covariance matrix $S_m - \mu_m \mu_m^\top$ must be psd. ■

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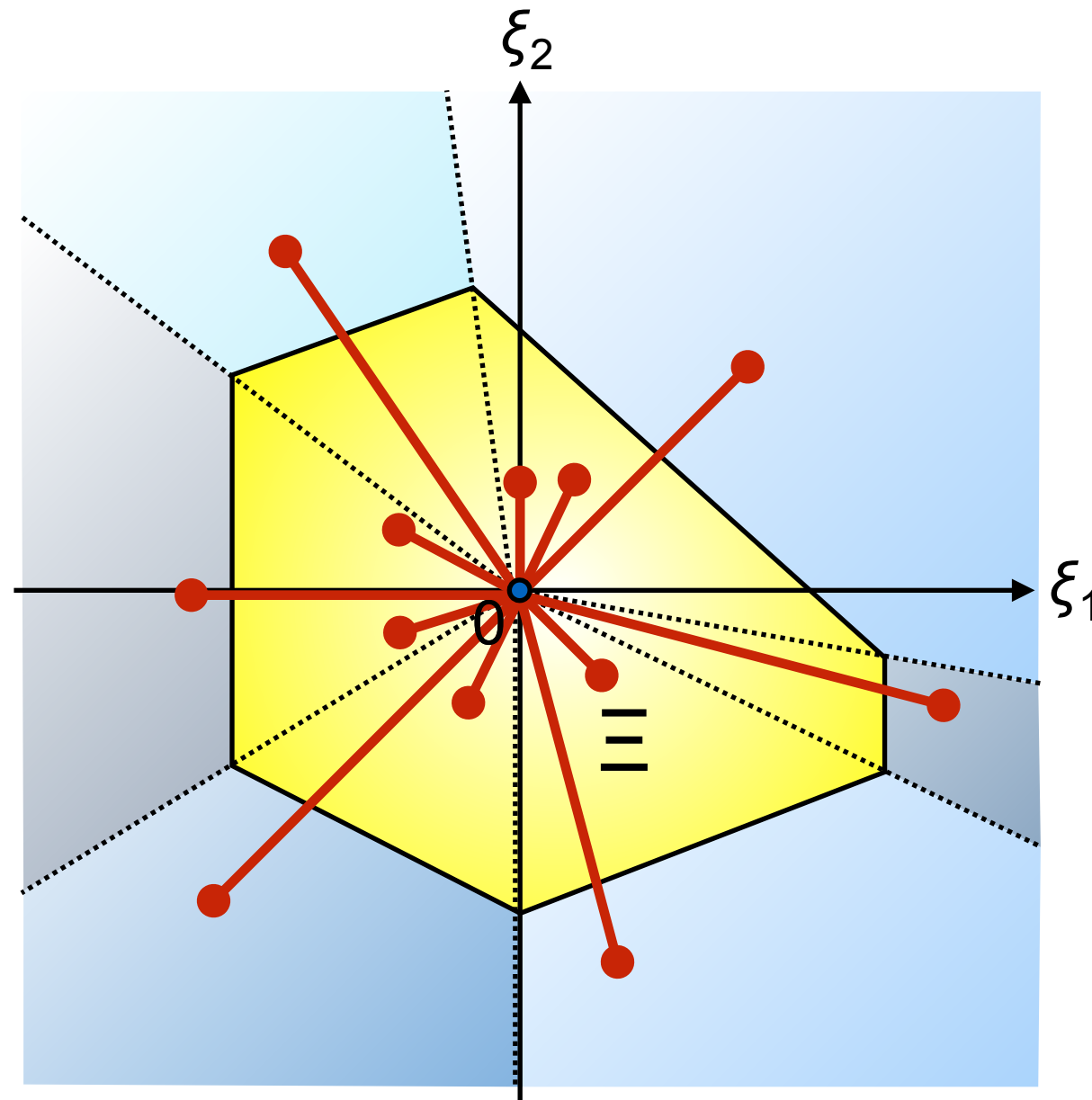
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Structure of the Extremal Distributions

Partition \mathbb{R}^n into
 k cones



Structure of the Extremal Distributions

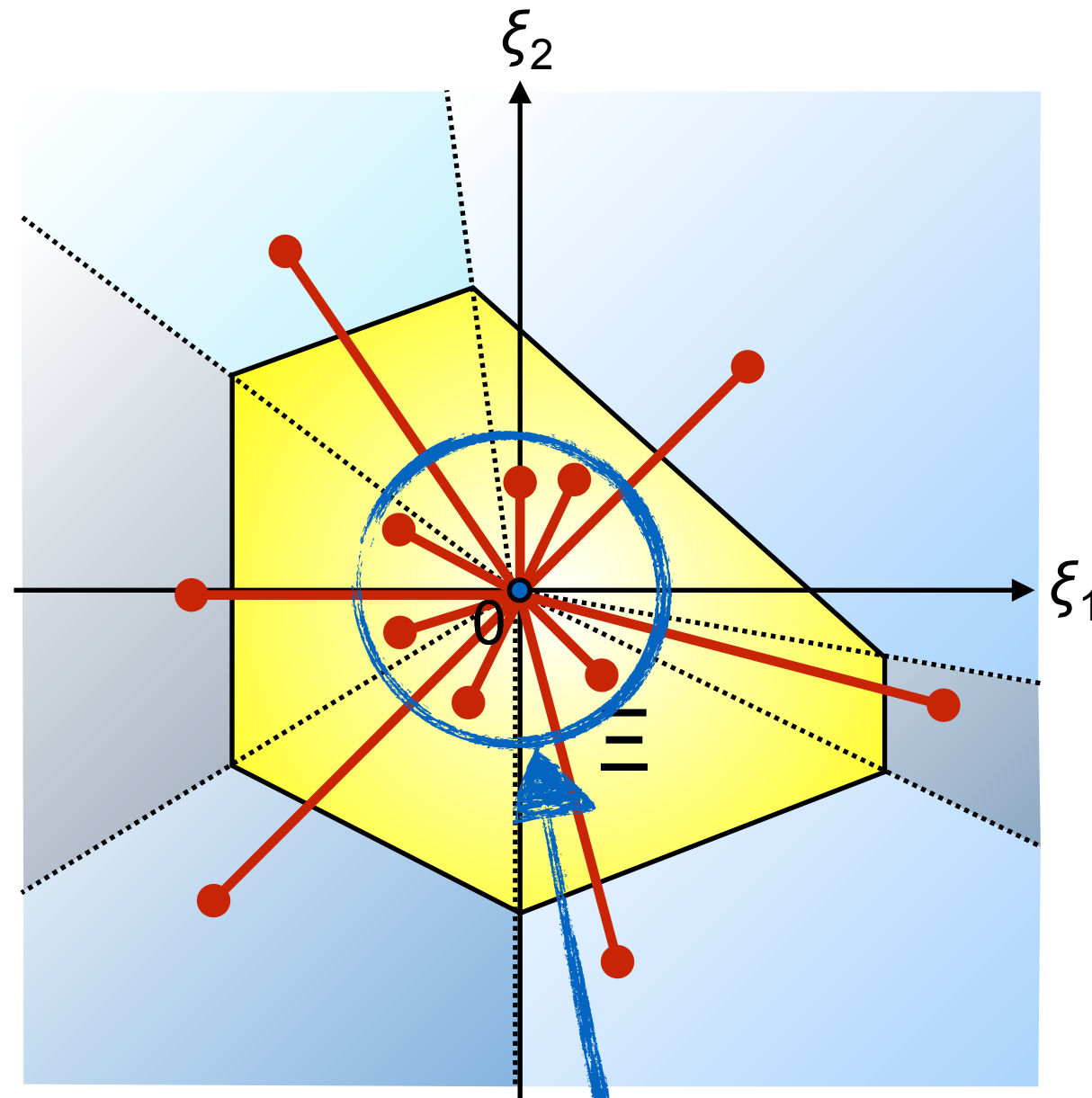


Extremal distribution:

$$\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^\alpha$$

Structure of the Extremal Distributions

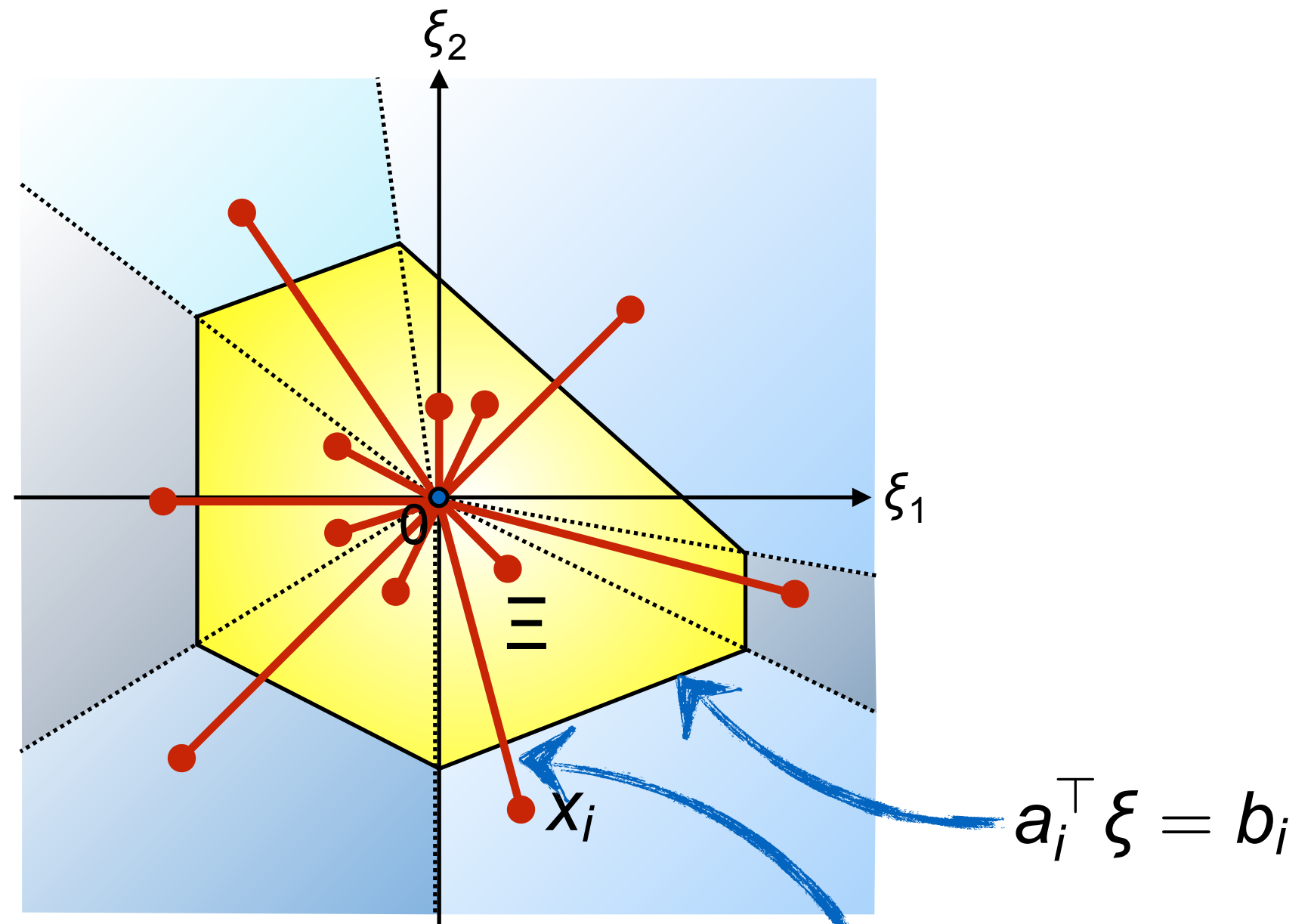
"Slack" distribution on Ξ



Extremal distribution: $\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^\alpha$

Structure of the Extremal Distributions

Radial α -unimodal
distribution for
sector of i th facet

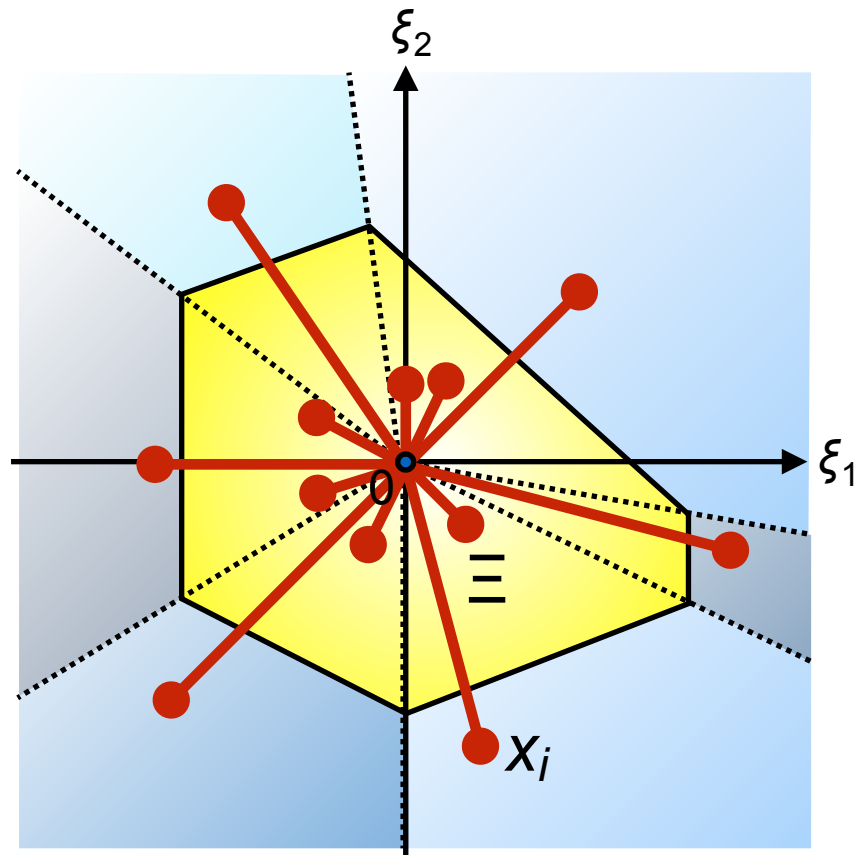


Extremal distribution: $\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^\alpha$

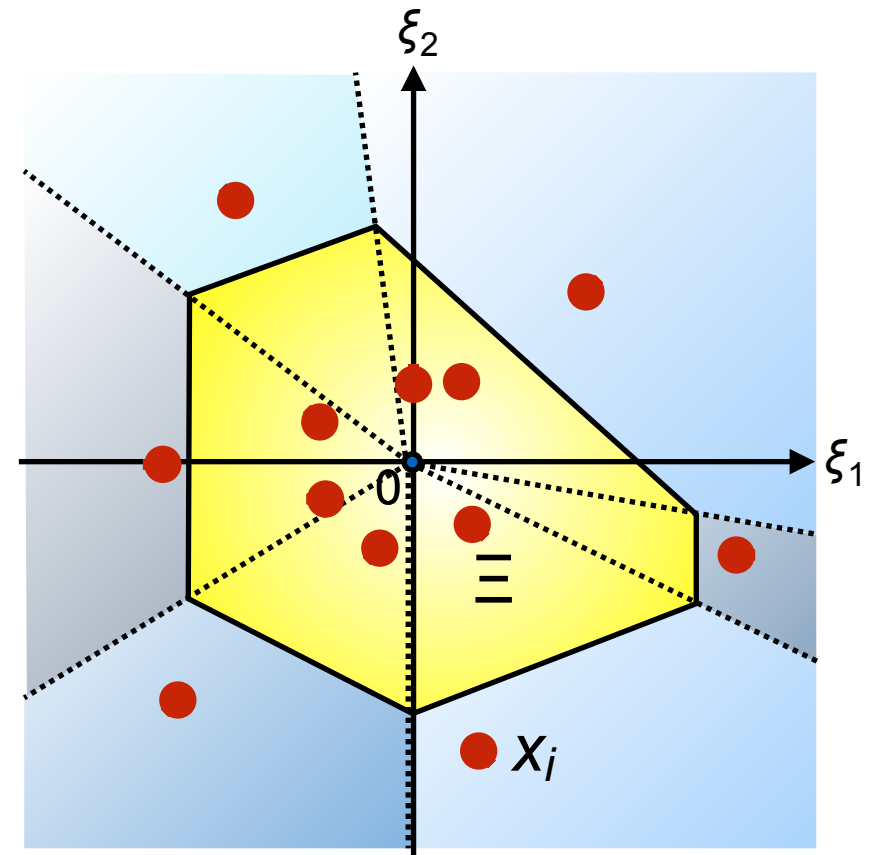
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Moment Conditions

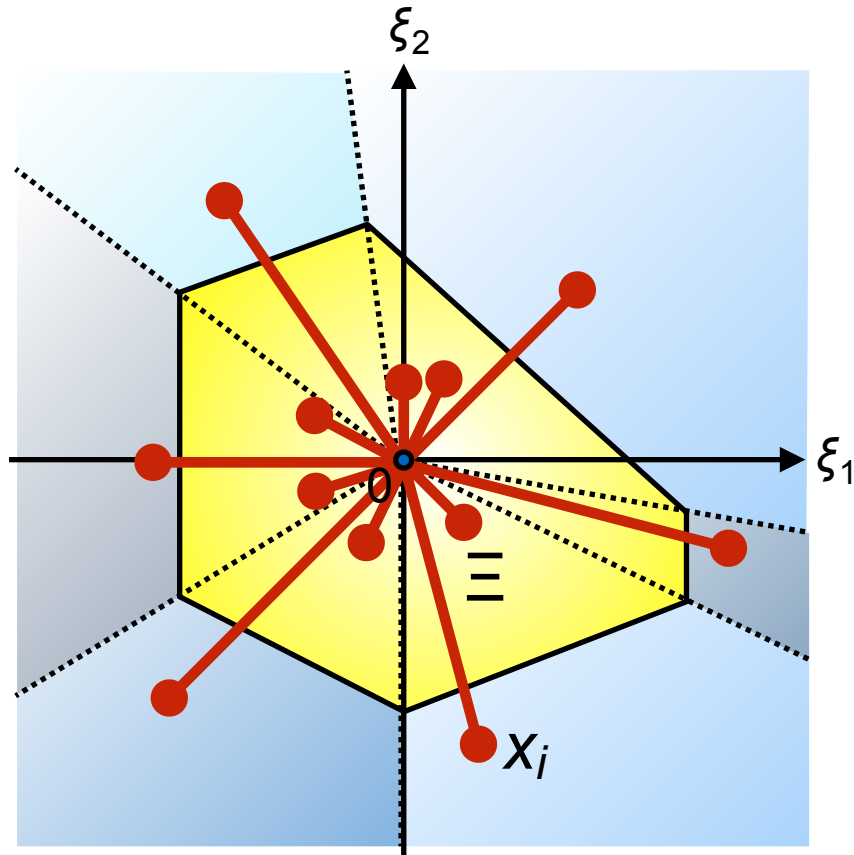


$$\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^{\alpha}$$

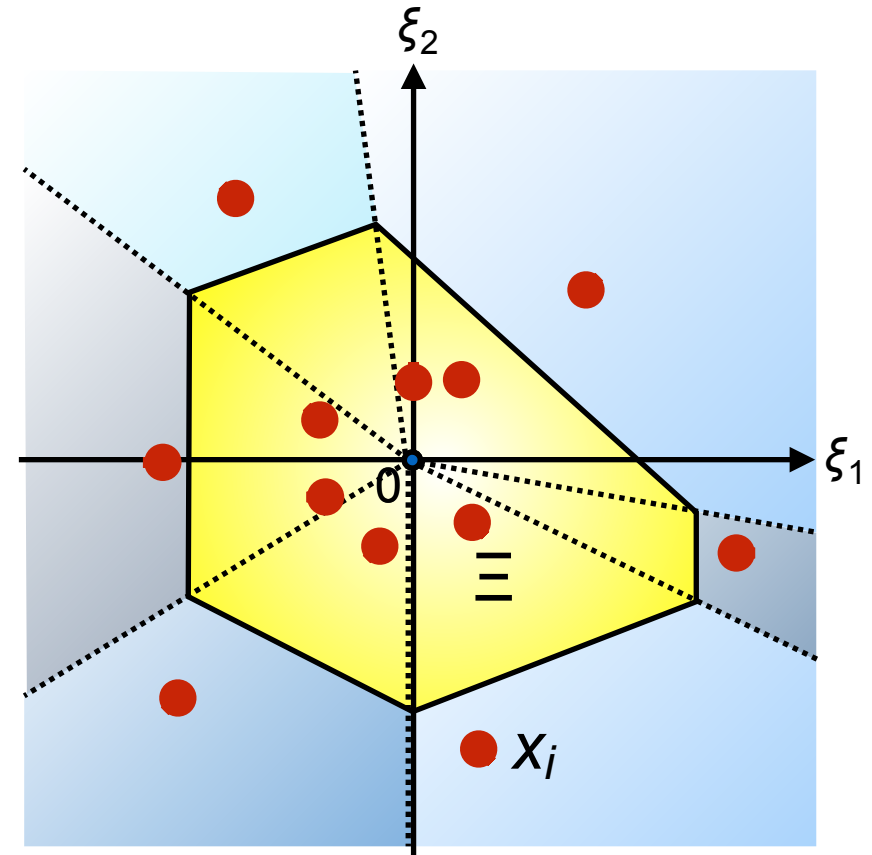


$$m^* = \lambda_0 \cdot m_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{x_i}$$

Moment Conditions



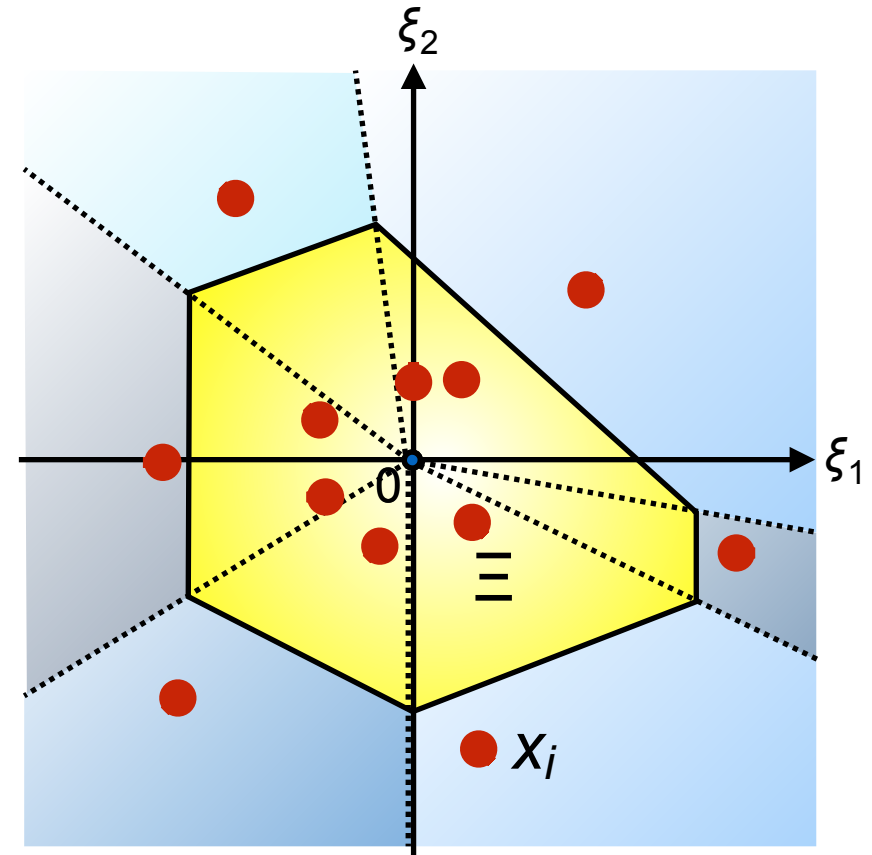
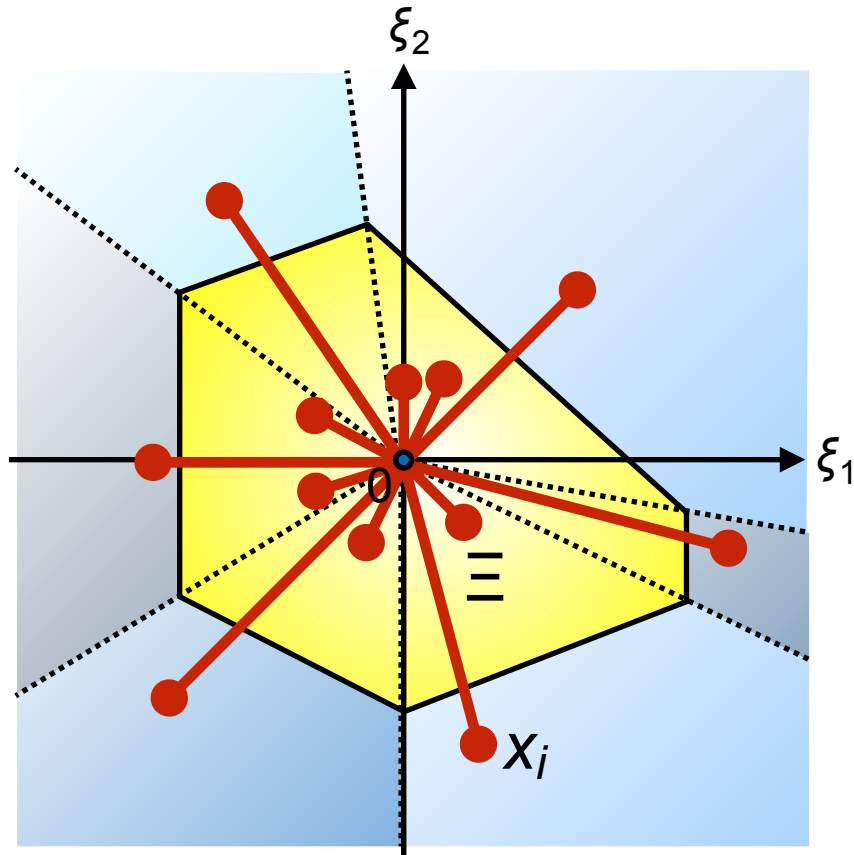
$$\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^\alpha$$



$$m^* = \lambda_0 \cdot m_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{x_i}$$

$$\mathbb{E}_{m^*} \left[\begin{pmatrix} \mathbf{x} \mathbf{x}^\top & \mathbf{x} \\ \mathbf{x}^\top & 1 \end{pmatrix} \right] = \begin{pmatrix} \frac{\alpha+2}{\alpha} \mathbf{S} & \frac{\alpha+1}{\alpha} \boldsymbol{\mu} \\ \frac{\alpha+1}{\alpha} \boldsymbol{\mu}^\top & 1 \end{pmatrix}$$

Moment Conditions

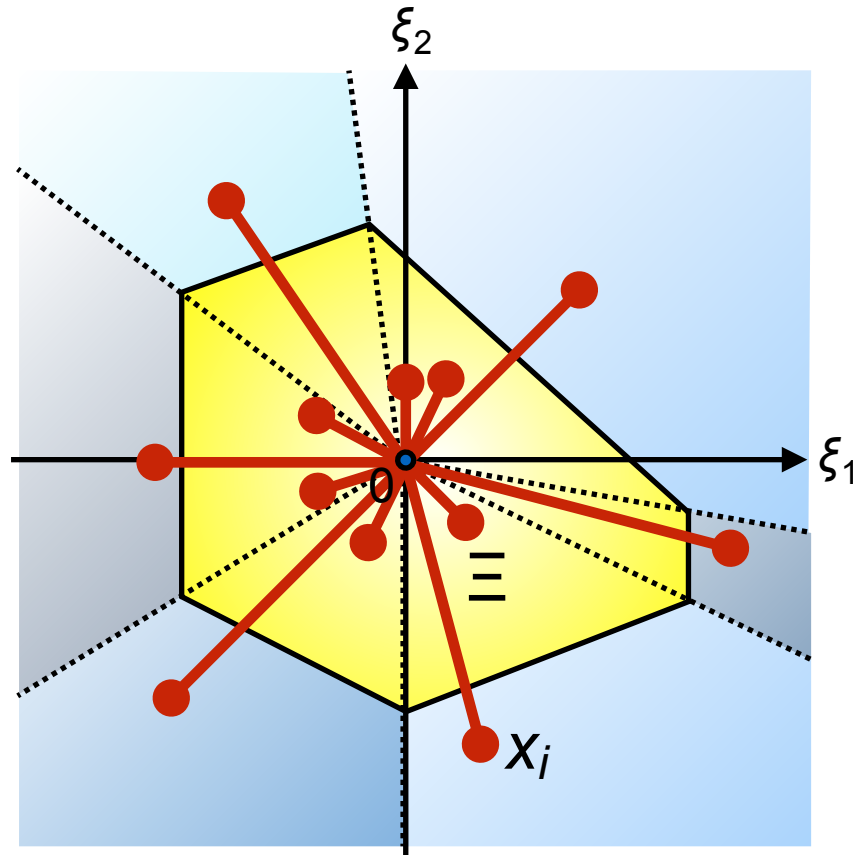


$$\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^{\alpha}$$

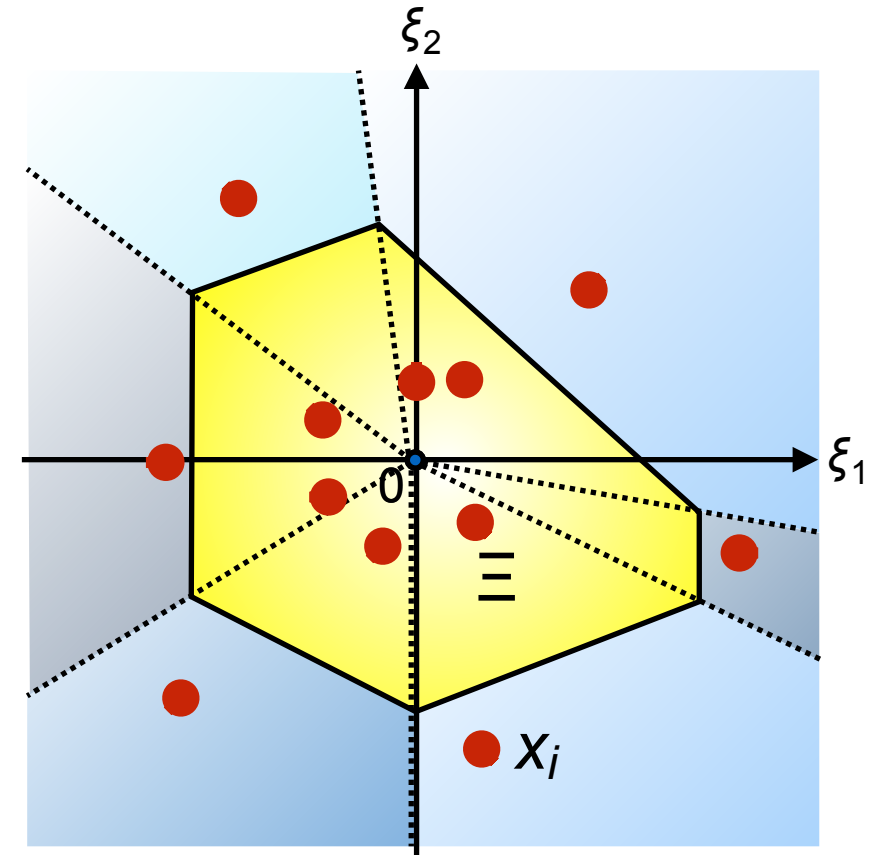
$$m^* = \lambda_0 \cdot m_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{x_i}$$

$$\lambda_0 \mathbb{E}_{m_0} \left[\begin{pmatrix} \mathbf{x} \mathbf{x}^{\top} & \mathbf{x} \\ \mathbf{x}^{\top} & 1 \end{pmatrix} \right] + \sum_{i=1}^k \lambda_i \begin{pmatrix} \mathbf{x}_i \mathbf{x}_i^{\top} & \mathbf{x}_i \\ \mathbf{x}_i^{\top} & 1 \end{pmatrix} = \begin{pmatrix} \frac{\alpha+2}{\alpha} \mathbf{S} & \frac{\alpha+1}{\alpha} \boldsymbol{\mu} \\ \frac{\alpha+1}{\alpha} \boldsymbol{\mu}^{\top} & 1 \end{pmatrix}$$

Moment Conditions



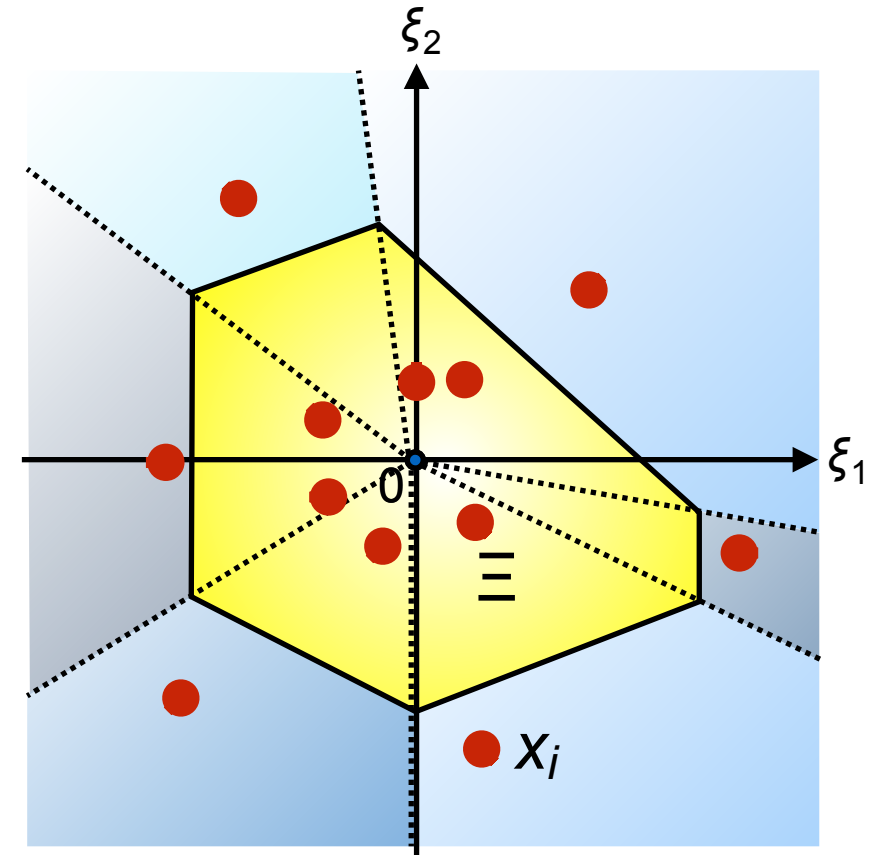
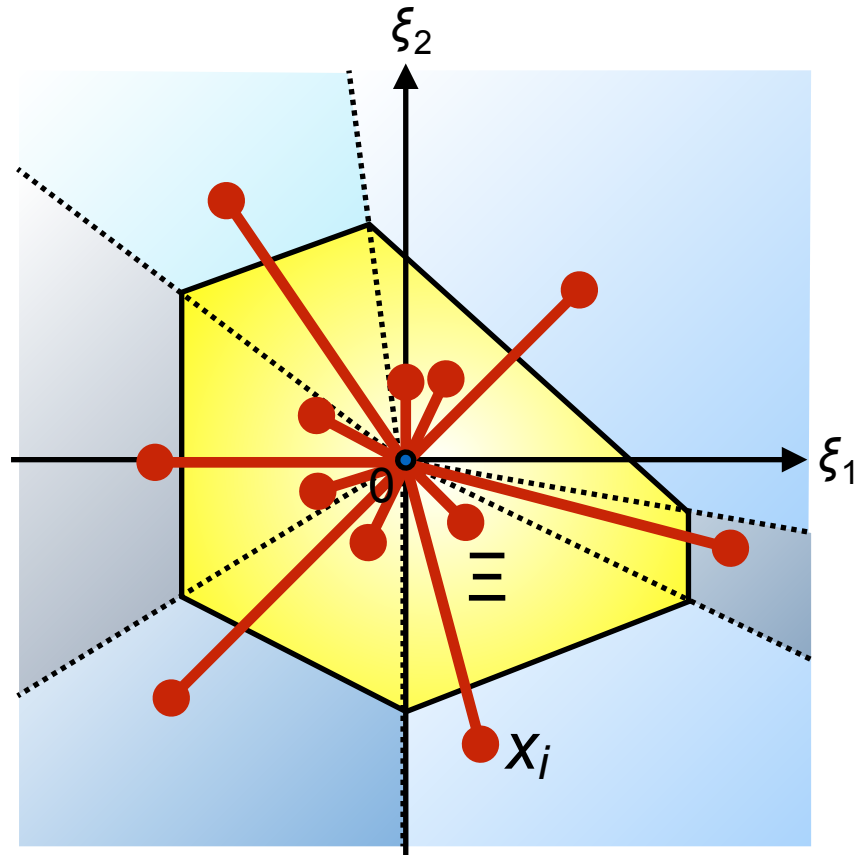
$$\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^\alpha$$



$$m^* = \lambda_0 \cdot m_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{x_i}$$

$$\sum_{i=1}^k \lambda_i \begin{pmatrix} x_i x_i^\top & x_i \\ x_i^\top & 1 \end{pmatrix} \preceq \begin{pmatrix} \frac{\alpha+2}{\alpha} S & \frac{\alpha+1}{\alpha} \mu \\ \frac{\alpha+1}{\alpha} \mu^\top & 1 \end{pmatrix}$$

Moment Conditions



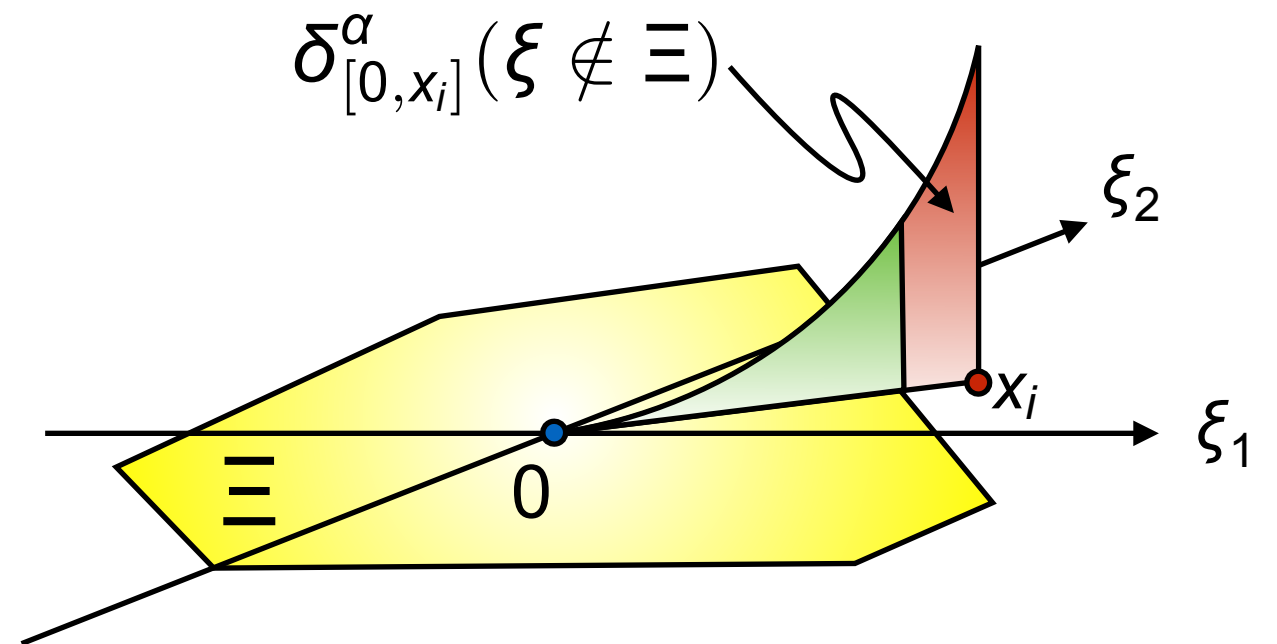
$$\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^{\alpha}$$

$$m^* = \lambda_0 \cdot m_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{x_i}$$

$$\sum_{i=1}^k \begin{pmatrix} z_i & z_i \\ z_i^{\top} & \lambda_i \end{pmatrix} \preceq \begin{pmatrix} \frac{\alpha+2}{\alpha} S & \frac{\alpha+1}{\alpha} \mu \\ \frac{\alpha+1}{\alpha} \mu^{\top} & 1 \end{pmatrix}, \quad \begin{pmatrix} z_i & z_i \\ z_i^{\top} & \lambda_i \end{pmatrix} \succeq 0 \quad \forall i$$

Objective Function

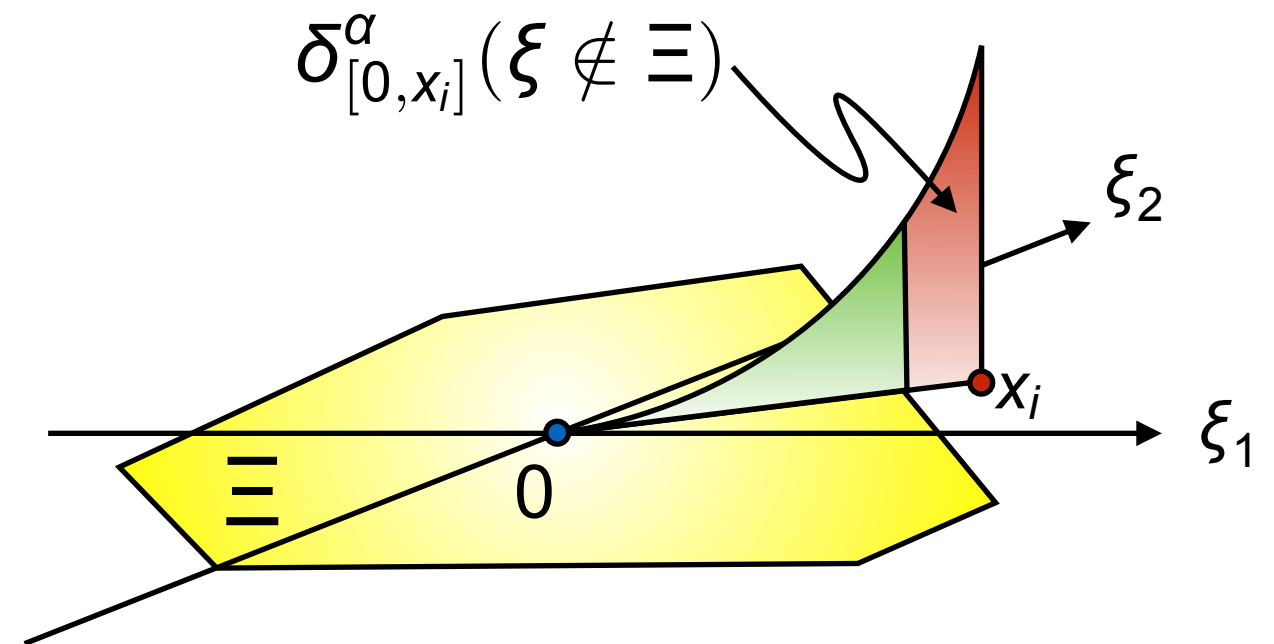
$$\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^\alpha$$



$$\mathbb{P}^*(\xi \notin \Xi) = \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^\alpha(\xi \notin \Xi)$$

Objective Function

$$\mathbb{P}^* = \lambda_0 \cdot \mathbb{P}_0 + \sum_{i=1}^k \lambda_i \cdot \delta_{[0, x_i]}^\alpha$$



$$\begin{aligned} \mathbb{P}^*(\xi \notin \Xi) &= \max_{\tau} \sum_{i=1}^k \lambda_i - \tau_i \\ \text{s.t.} \quad &\tau_i (\mathbf{a}_i^\top \mathbf{z}_i)^\alpha \geq \lambda_i^{\alpha+1} b_i^\alpha, \quad \tau_i \geq 0 \end{aligned}$$

In Summary...

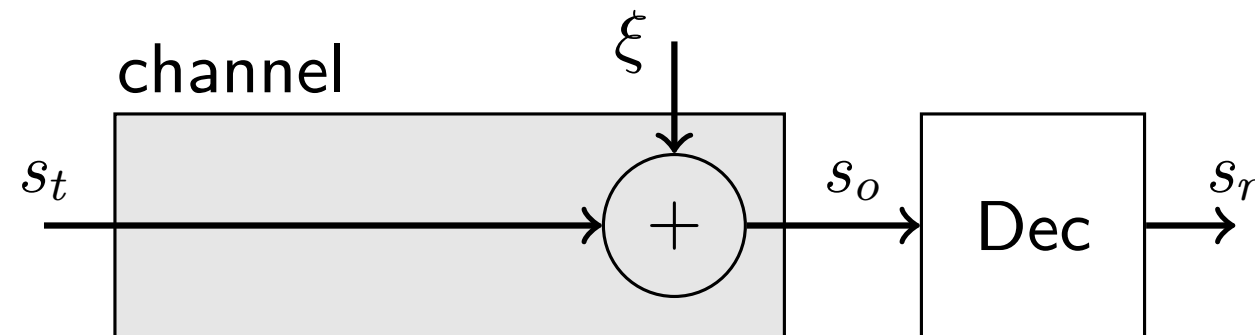
$$\begin{array}{ll}
 \max & \sum_{i=1}^k \lambda_i - \tau_i \\
 \text{s.t.} & \mathbf{a}^\top \mathbf{z}_i \geq 0, \tau_i \geq 0 \quad \forall i = 1, \dots, k \\
 & \tau_i (\mathbf{a}_i^\top \mathbf{z}_i)^\alpha \geq \lambda_i^{\alpha+1} b_i^\alpha \quad \forall i = 1, \dots, k \\
 & \sum_{i=1}^k \begin{pmatrix} \mathbf{Z}_i & \mathbf{z}_i \\ \mathbf{z}_i^\top & \lambda_i \end{pmatrix} \preceq \begin{pmatrix} \frac{n+2}{n} \mathbf{S} & \frac{n+1}{n} \boldsymbol{\mu} \\ \frac{n+1}{n} \boldsymbol{\mu}^\top & 1 \end{pmatrix} \\
 & \begin{pmatrix} \mathbf{Z}_i & \mathbf{z}_i \\ \mathbf{z}_i^\top & \lambda_i \end{pmatrix} \succeq 0 \quad \forall i = 1, \dots, k
 \end{array}$$

evaluation of $\mathbb{P}^*(\xi \notin \Xi)$

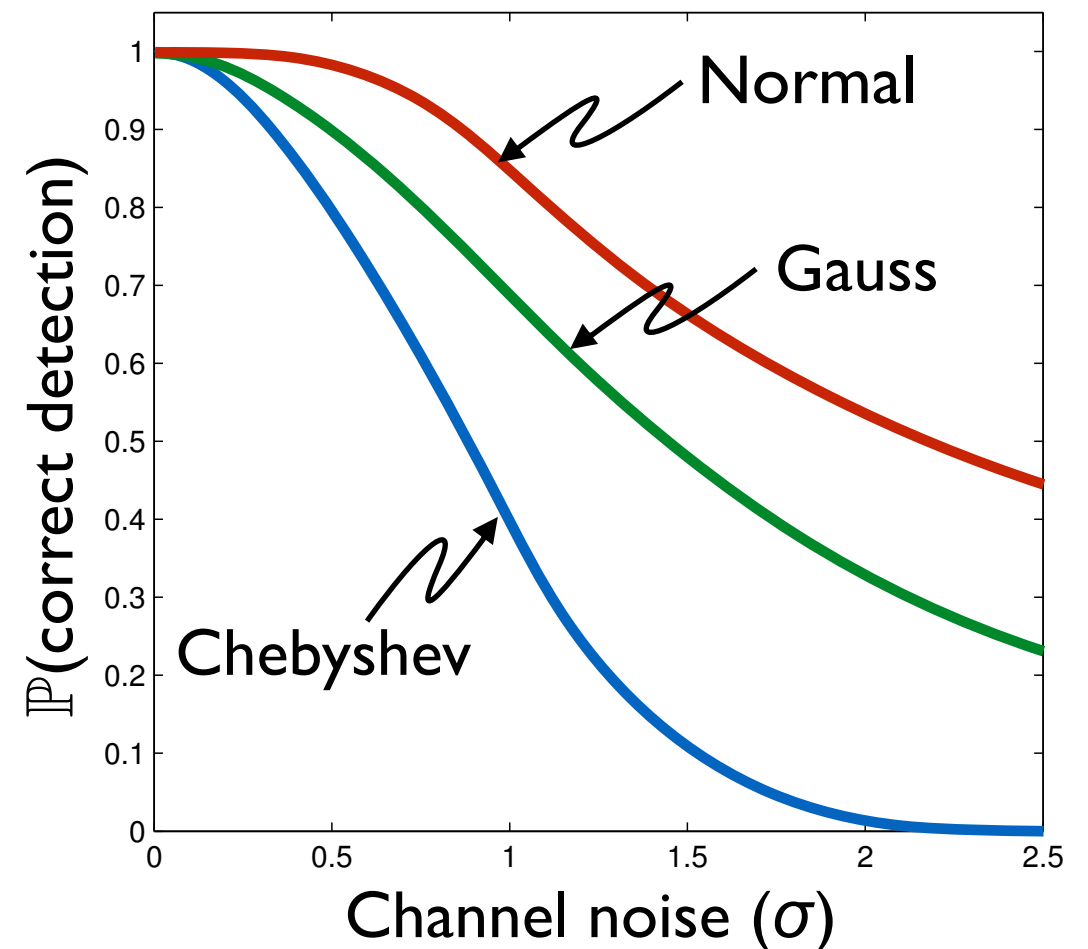
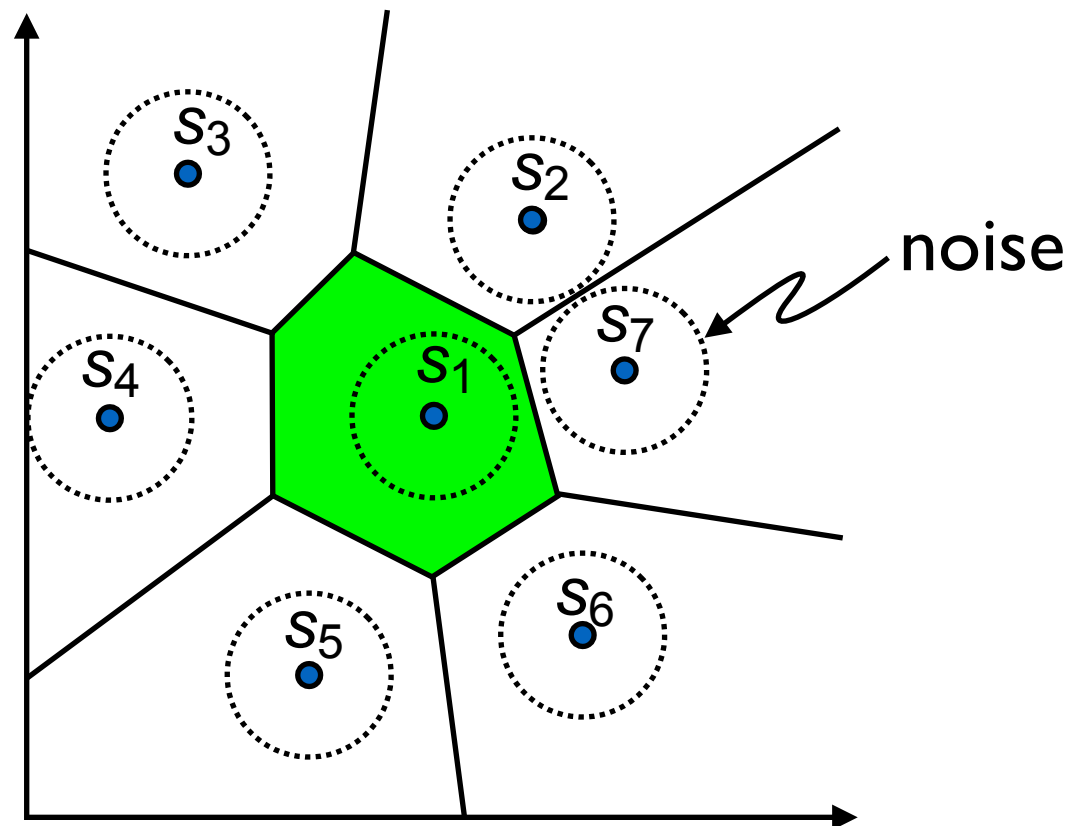
moment conditions for mixture distribution

Application: Digital Communication Limits

Transmit symbols s_1, s_2, \dots, s_7 over a noisy communication channel.



Minimum distance decoder

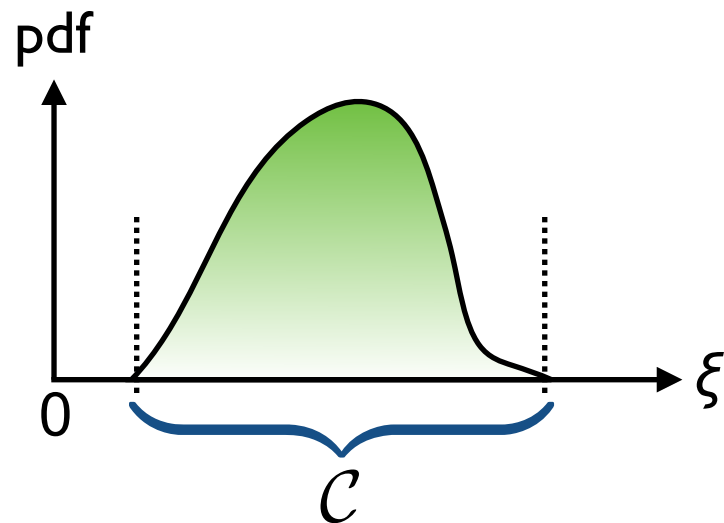


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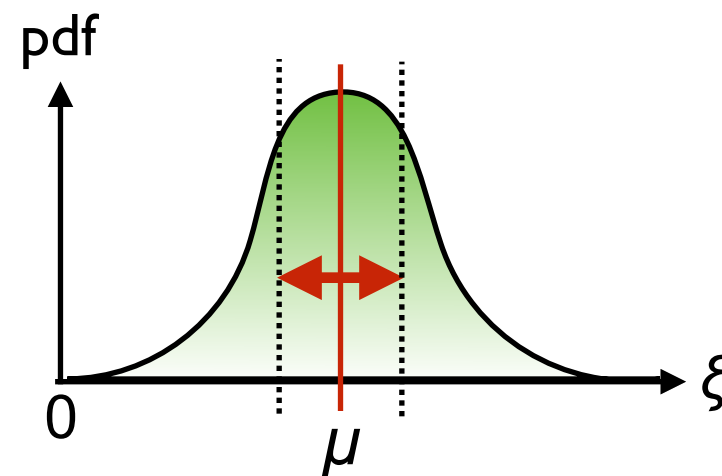
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Tractable Extensions

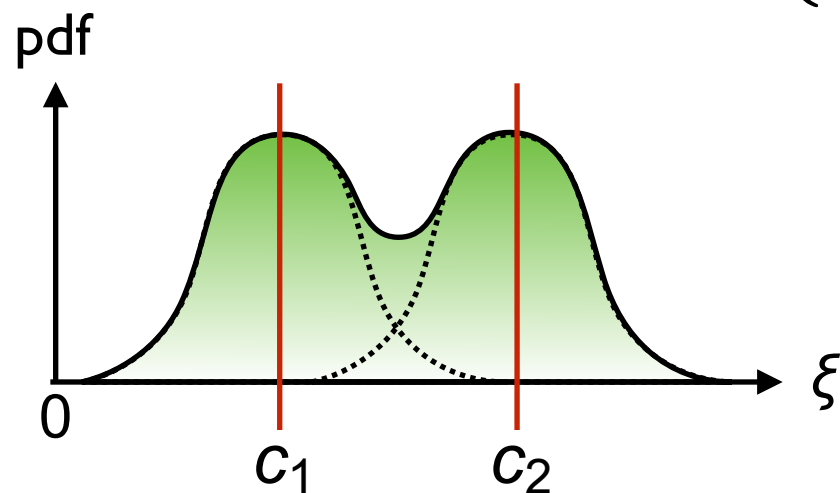
Support information: $\mathcal{P} = \{\mathbb{P} \in \mathcal{P}_\alpha(\mu, \mathcal{S}) : \mathbb{P}(\mathcal{C}) = 1\}$



Moment ambiguity: $\mathcal{P} = \bigcup_{(\mu, \mathcal{S}) \in \mathcal{M}} \mathcal{P}_\alpha(\mu, \mathcal{S})$



Multimodality: $\mathcal{P} = \left\{ \sum_m p_m \mathbb{P}_m : p \in \mathcal{U}, \mathbb{P}_m \in \mathcal{P}_\alpha(c_m) \forall m \right\} \cap \mathcal{P}(\mu, \mathcal{S})$



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