Six-dimensional supergravity and lorentzian Lie groups

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* hep-th/0303212 (JHEP 06 (2003) 025)

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 * hep-th/0306278
- George Papadopoulos (King's College, London)
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 * math.AG/0211170 (J Geom Phys to appear)

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Equivalently, they are parallel sections of the bundle

 $\mathcal{E}(M) = TM \oplus \mathfrak{so}(TM)$

$$D_X \begin{pmatrix} \xi \\ A \end{pmatrix} = \begin{pmatrix} \nabla_X \xi - A(X) \\ \nabla_X A - R(X,\xi) \end{pmatrix}$$

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$$\subset \mathbb{E}^{2,n-1}$$
: $-t_1^2 - t_2^2 + x_1^2 + \dots + x_{n-1}^2 = \frac{-1}{\kappa^2}$

Note: the $\kappa \neq 0$ spaces are *quadrics* in a flat space in one dimension higher

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The flat and spherical cases are solved (culminating in the work of Wolf in the 1970s), but the hyperbolic and lorentzian cases remain largely open despite many partial results.

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In this talk I will report on the solution of the local problem in several supergravity theories.

Note: A maximally supersymmetric supergravity background will be abbreviated *vacuum*.

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Extremals of this action—namely, Ricci-flat manifolds—are called *spacetimes*.

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The maximally symmetric solutions are the lorentzian space forms: smooth discrete quotients of Minkowski space and (the universal covers of) de Sitter and anti de Sitter spaces, depending on the sign of λ .

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What is so interesting about this action?

It is *invariant*

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Also... this really only works as written in four dimensions. In other dimensions supergravity theories might have other fields and both the action and supersymmetry transformations become *more complicated*. But supergravity theories are *uniquely* determined by representation theory (of relevant superalgebras).

Supergravities

	32	24	20	16	12	8	4
11	M						
10	IIA IIB			1			
9	N=2			N = 1			-
8	N=2			N = 1			
7	N=4			N=2			
6	(2,2) $(3,1)$ $(4,0)$	(2,1) $(3,0)$		(1,1) $(2,0)$		(1, 0)	
5	N=8	N=6		N = 4		N=2	
4	N = 8	N = 6	N = 5	N = 4	N=3	N=2	N=1

[Van Proeyen, hep-th/0301005]

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- (g, Φ) obey the field equations with fermions (e.g., Ψ) put to zero
- S a real vector bundle of spinors (i.e., modules over $C\ell(TM)$)

(M, g, Φ, S) is supersymmetric if it admits Killing spinors

 $D\varepsilon = 0$

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defined by the supersymmetry variation of the gravitino:

$$\delta_{\varepsilon}\Psi = D\varepsilon$$

(putting all fermions to zero)

 $A(g,\Phi)\varepsilon = 0$

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where A is a section of End(S) defined by the supersymmetric variation of any other fermionic fields

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Typically A = 0 sets some fields to zero, and the flatness of D constrains the geometry and any remaining fields. The strategy is therefore to study the flatness equations for D.

In the table we have highlighted the "top" theories whose vacua are known already:

• $D = 4 \ N = 1$

[Tod (1984)]

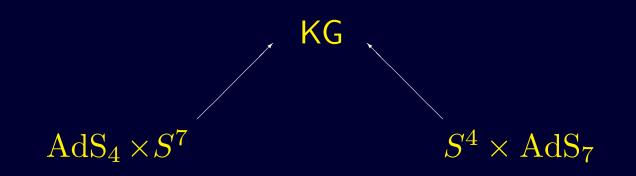
- $D = 4 \ N = 1$ [Tod (1984)]
- D = 6 (1, 0), (2, 0) [Chamseddine-FO-Sabra, Gutowski-Martelli-Reall]

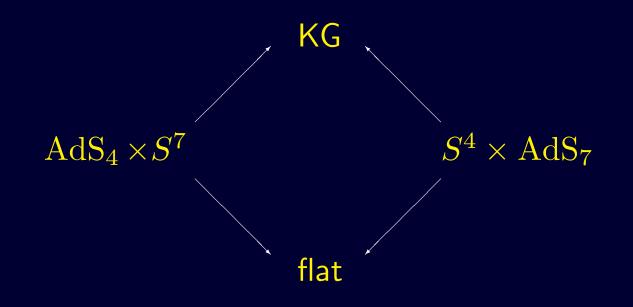
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- D = 10 IIB and I [FO-Papadopoulos]

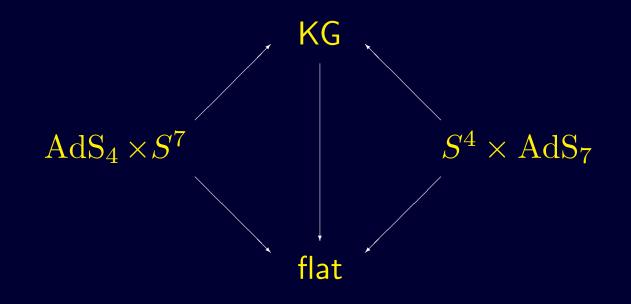
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- D = 11 M [FO-Papadopoulos]

 $AdS_4 \times S^7$

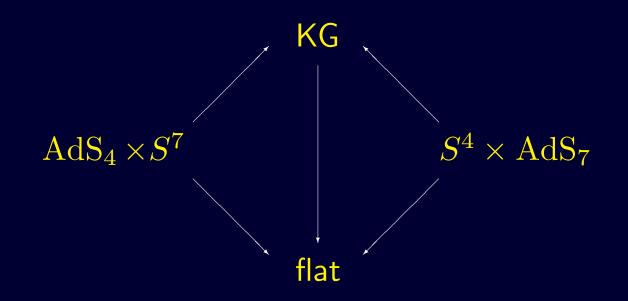
 $S^4 \times \mathrm{AdS}_7$





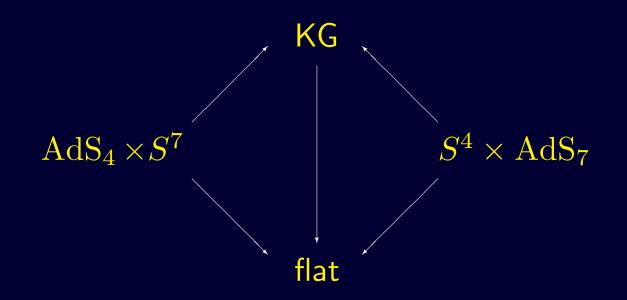


Vacua of D = 11 supergravity



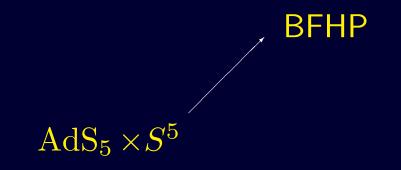
where KG is an indecomposable lorentzian symmetric space with solvable tranvection group (cf. Cahen–Wallach)

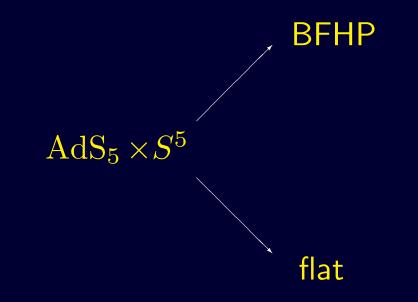
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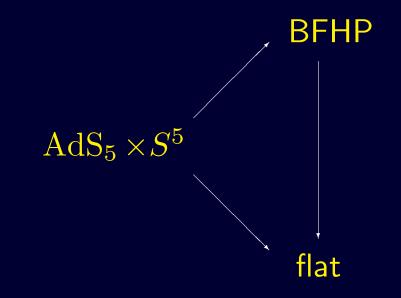


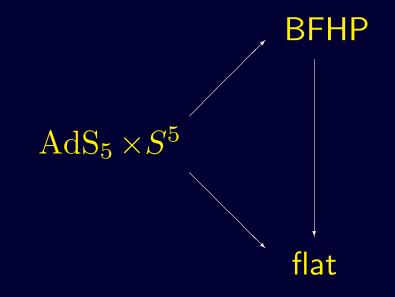
where KG is an indecomposable lorentzian symmetric space with solvable tranvection group (cf. Cahen–Wallach), discovered in this context by Kowalski-Glikman.

 $AdS_5 \times S^5$









where BFHP is a Cahen–Wallach space, locally isometric to a lorentzian Lie group.

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is a real 8-dimensional representation of $Spin(1,5) \times Sp(1)$.

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A pseudoriemannian manifold admitting a flat metric connection with closed torsion

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- \mathfrak{h} acts on $\mathfrak{g} \times_{\omega} \mathfrak{h}^*$ preserving the Lie bracket, so we can form the *double extension*

 $\mathfrak{d}(\mathfrak{g},\mathfrak{h})=\mathfrak{h}\ltimes(\mathfrak{g} imes_\omega\mathfrak{h}^*)$

$$\begin{array}{cccc}
\mathfrak{g} & \mathfrak{h} & \mathfrak{h}^* \\
\mathfrak{g} \\
\mathfrak{h} \\
\mathfrak{h}^* \begin{pmatrix} \langle -, - \rangle_{\mathfrak{g}} & 0 & 0 \\ 0 & B & \mathrm{id} \\ 0 & \mathrm{id} & 0 \end{pmatrix}
\end{array}$$

where

 $\star \langle -, - \rangle_{\mathfrak{g}}$ is the invariant metric on \mathfrak{g}

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* $\langle -, - \rangle_{\mathfrak{g}}$ is the invariant metric on \mathfrak{g} , * id stands for the dual pairing between \mathfrak{h} and \mathfrak{h}^* , and * *B* is any invariant symmetric bilinear form on \mathfrak{h}

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\mathfrak{g} \\
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This construction is due to Medina and Revoy.

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An indecomposable metric Lie algebra is either simple, onedimensional, or a double extension $\mathfrak{d}(\mathfrak{g}, \mathfrak{h})$ where \mathfrak{h} is either simple or one-dimensional. Every metric Lie algebra is obtained as an orthogonal direct sum

of indecomposables.

[See also FO-Stanciu hep-th/9506152]

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- $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$

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- ∂(ℝ⁴, ℝ), actually a family of Lie algebras parametrised by homomorphisms

$$\mathbb{R} \to \Lambda^2 \mathbb{R}^4 \cong \mathfrak{so}(4)$$



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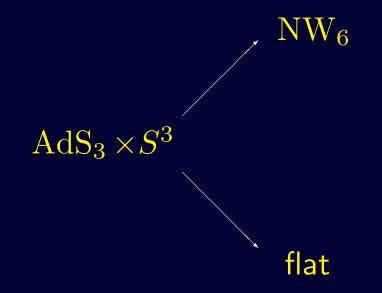
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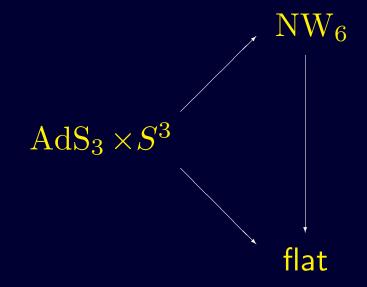
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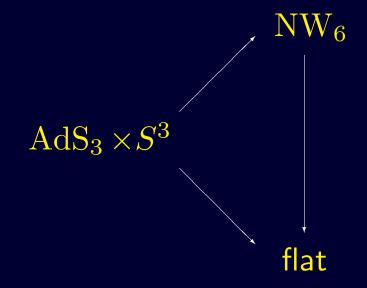
The third case is a six-dimensional version of the Nappi-Witten spacetime, NW_6 , discovered by Meessen. [Meessen hep-th/0111031]

$AdS_3 \times S^3$

 NW_6 $\mathrm{AdS}_3 \times S^3$







which can be interpreted here as group contractions à la Inönü–Wigner.

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and SU(2) with the group of matrices

$$\begin{pmatrix} a & b \\ -\overline{b} & \overline{a} \end{pmatrix} \qquad \text{with } |a|^2 + |b|^2 = 1$$

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$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \qquad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \qquad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Nonzero Lie brackets:

$$[X_0, X_1] = -2X_2$$

 $[X_0, X_2] = 2X_1$
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$$\begin{split} & [\mathsf{X}_0,\mathsf{X}_1] = -2\mathsf{X}_2 & [\mathsf{X}_5,\mathsf{X}_3] = -2\mathsf{X}_4 \\ & [\mathsf{X}_0,\mathsf{X}_2] = 2\mathsf{X}_1 & [\mathsf{X}_5,\mathsf{X}_4] = 2\mathsf{X}_3 & , \\ & [\mathsf{X}_1,\mathsf{X}_2] = 2\mathsf{X}_0 & [\mathsf{X}_3,\mathsf{X}_4] = -2\mathsf{X}_5 \end{split}$$

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and inner product:

 $\langle \mathsf{X}_i, \mathsf{X}_j \rangle = \eta_{ij} ,$

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N is obtained by exponentiating the null vector $U = sX_0 + sX_5$, with complementary null vector $V = -X_0 + X_5$.

```
Introduce \Omega > 0 and a new basis:
```

 $\mathsf{P}_i = \Omega \mathsf{X}_i$

$$\mathsf{P}_i = \Omega \mathsf{X}_i \qquad \mathsf{J} = \frac{1}{2}\mathsf{U}$$

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for i = 1, 2, 3, 4.

$$\mathsf{P}_i = \Omega \mathsf{X}_i \qquad \mathsf{J} = \frac{1}{2}\mathsf{U} \qquad \mathsf{K} = \Omega^2 \mathsf{V}$$

for i = 1, 2, 3, 4.

The contracted Lie algebra is the limit $\Omega \to 0$ of the Lie brackets in the new basis:

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for $i = 1, 2, \overline{3, 4}$.

The contracted Lie algebra is the limit $\Omega \rightarrow 0$ of the Lie brackets in the new basis:

$$\begin{bmatrix} \mathsf{J}, \mathsf{P}_1 \end{bmatrix} = -\mathsf{P}_2$$
$$\begin{bmatrix} \mathsf{J}, \mathsf{P}_2 \end{bmatrix} = \mathsf{P}_1$$

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with K central.

$$\langle \mathsf{P}_i,\mathsf{P}_j
angle=\delta_{ij}$$

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This is precisely the (anti-selfdual, lorentzian) double extension $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$.

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This is precisely the (anti-selfdual, lorentzian) double extension $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$.

In summary, the Penrose limit

 $\mathrm{AdS}_3 \times S^3 \rightsquigarrow NW_6$

$$\langle \mathsf{P}_i,\mathsf{P}_j
angle=\delta_{ij}\qquad \langle \mathsf{J},\mathsf{K}
angle=1~.$$

This is precisely the (anti-selfdual, lorentzian) double extension $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$.

In summary, the Penrose limit

 $\mathrm{AdS}_3 \times S^3 \rightsquigarrow NW_6$

is the group contraction

 $\mathrm{SU}(1,1) \times \mathrm{SU}(2) \rightsquigarrow D(\mathbb{R}^4,\mathbb{R})$

• bosonic fields:

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 - ★ gravitino Ψ , a section of $T^*M \otimes S$, where $S = [\Delta_+ \otimes \Sigma]$ is a real 16-dimensional representation of $\text{Spin}(1,5) \times \text{Sp}(2)$

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In summary, up to the action of the Sp(2) R-symmetry group, (2,0) vacua are in one-to-one correspondence with (1,0) vacua.

Thank you.

Lunch beckons.