José Figueroa-O'Farrill

Edinburgh Mathematical Physics Group

School of Mathematics



Neve Shalom  $\sim$  Wahat al-Salam, 27 May 2003

Which are the maximally symmetric spacetimes?

Which are the maximally symmetric spacetimes?

Locally, those which admit the maximum number of Killing vectors.

Which are the maximally symmetric spacetimes?

Locally, those which admit the maximum number of Killing vectors.

Recall:  $\xi^{\mu}$  is Killing  $\iff \nabla_{\mu}\xi_{\nu} = -\nabla_{\nu}\xi_{\mu}$ 

#### Which are the maximally symmetric spacetimes?

Locally, those which admit the maximum number of Killing vectors.

Recall: 
$$\xi^{\mu}$$
 is Killing  $\iff \nabla_{\mu}\xi_{\nu} = -\nabla_{\nu}\xi_{\mu}$ 

Differentiating

#### Which are the maximally symmetric spacetimes?

Locally, those which admit the maximum number of Killing vectors.

Recall:  $\xi^{\mu}$  is Killing  $\iff \nabla_{\mu}\xi_{\nu} = -\nabla_{\nu}\xi_{\mu}$ 

Differentiating  $\Longrightarrow$  Killing's identity

#### Which are the maximally symmetric spacetimes?

Locally, those which admit the maximum number of Killing vectors.

Recall: 
$$\xi^{\mu}$$
 is Killing  $\iff \nabla_{\mu}\xi_{\nu} = -\nabla_{\nu}\xi_{\mu}$ 

Differentiating  $\Longrightarrow$  Killing's identity:

$$\nabla_{\mu}\nabla_{\nu}\xi_{\rho} = R_{\mu\nu\rho}{}^{\sigma}\xi_{\sigma}$$

Therefore a Killing vector  $\xi$  is uniquely determined by

Therefore a Killing vector  $\boldsymbol{\xi}$  is uniquely determined by:  $\boldsymbol{\xi}(p)$ 

This is suggestive of parallel sections of a vector bundle.

This is suggestive of parallel sections of a vector bundle.

Indeed on the bundle

$$\mathcal{E}(M) = TM \oplus \Lambda^2 T^*M$$

This is suggestive of parallel sections of a vector bundle.

Indeed on the bundle

$$\mathcal{E}(M) = TM \oplus \Lambda^2 T^*M$$

there is a connection D defined on a section  $(\xi^{\mu}, F_{\mu\nu})$  of  $\mathcal{E}(M)$  by

This is suggestive of parallel sections of a vector bundle.

Indeed on the bundle

$$\mathcal{E}(M) = TM \oplus \Lambda^2 T^*M$$

there is a connection D defined on a section  $(\xi^{\mu}, F_{\mu\nu})$  of  $\mathcal{E}(M)$  by

$$D_{\mu} \begin{pmatrix} \xi_{\nu} \\ F_{\nu\rho} \end{pmatrix} = \begin{pmatrix} \nabla_{\mu} \xi_{\nu} - F_{\mu\nu} \\ \nabla_{\mu} F_{\nu\rho} - R_{\mu\nu\rho}{}^{\sigma} \xi_{\sigma} \end{pmatrix}$$

$$\implies (\xi^{\mu}, F_{\mu\nu}) \text{ is parallel}$$

 $\implies (\xi^{\mu}, F_{\mu\nu})$  is *parallel* if and only if

•  $\xi^{\mu}$  is a Killing vector

- $\implies (\xi^{\mu}, F_{\mu\nu})$  is *parallel* if and only if
- $\xi^{\mu}$  is a Killing vector, and
- $F_{\mu\nu} = \nabla_{\mu}\xi_{\nu}$

- $\implies (\xi^{\mu}, F_{\mu\nu})$  is *parallel* if and only if
- $\xi^{\mu}$  is a Killing vector, and
- $F_{\mu\nu} = \nabla_{\mu}\xi_{\nu}$

 $\mathcal{E}(M)$  has rank n(n+1)/2 for an n-dimensional M.

- $\Longrightarrow (\xi^{\mu}, F_{\mu\nu})$  is *parallel* if and only if
- $\xi^{\mu}$  is a Killing vector, and
- $F_{\mu\nu} = \nabla_{\mu}\xi_{\nu}$
- $\mathcal{E}(M)$  has rank n(n+1)/2 for an n-dimensional M.  $\implies \exists \leq n(n+1)/2$  linearly independent Killing vectors.

- $\Longrightarrow (\xi^{\mu}, F_{\mu\nu})$  is *parallel* if and only if
- $\xi^{\mu}$  is a Killing vector, and
- $F_{\mu\nu} = \nabla_{\mu}\xi_{\nu}$

 $\mathcal{E}(M)$  has rank n(n+1)/2 for an n-dimensional M.  $\implies \exists \leq n(n+1)/2$  linearly independent Killing vectors.

Maximal symmetry  $\implies \mathcal{E}(M)$  is flat

- $\implies (\xi^{\mu}, F_{\mu\nu})$  is *parallel* if and only if
- $\xi^{\mu}$  is a Killing vector, and
- $F_{\mu\nu} = \nabla_{\mu}\xi_{\nu}$

 $\mathcal{E}(M)$  has rank n(n+1)/2 for an n-dimensional M.  $\implies \exists \leq n(n+1)/2$  linearly independent Killing vectors.

Maximal symmetry  $\implies \mathcal{E}(M)$  is flat  $\implies M$  has constant sectional curvature  $\kappa$ .

•  $\kappa = 0$ : euclidean space  $\mathbb{E}^n$ 

- $\kappa = 0$ : euclidean space  $\mathbb{E}^n$
- $\kappa > 0$ : sphere

$$S^n \subset \mathbb{E}^{n+1}$$

- $\kappa = 0$ : euclidean space  $\mathbb{E}^n$
- $\kappa > 0$ : sphere

$$S^n \subset \mathbb{E}^{n+1}: \qquad x_1^2 + x_2^2 + \dots + x_{n+1}^2 = \frac{1}{\kappa^2}$$

- $\kappa = 0$ : euclidean space  $\mathbb{E}^n$
- $\kappa > 0$ : sphere

$$S^n \subset \mathbb{E}^{n+1}: \qquad x_1^2 + x_2^2 + \dots + x_{n+1}^2 = \frac{1}{\kappa^2}$$

•  $\kappa$  < 0: hyperbolic space

$$H^n \subset \mathbb{E}^{1,n}$$

- $\kappa = 0$ : euclidean space  $\mathbb{E}^n$
- $\kappa > 0$ : sphere

$$S^n \subset \mathbb{E}^{n+1}: \qquad x_1^2 + x_2^2 + \dots + x_{n+1}^2 = \frac{1}{\kappa^2}$$

•  $\kappa$  < 0: hyperbolic space

$$H^n \subset \mathbb{E}^{1,n}: \qquad -t_1^2 + x_1^2 + \dots + x_n^2 = \frac{-1}{\kappa^2}$$

•  $\kappa = 0$ : Minkowski space  $\mathbb{E}^{n-1,1}$ 

- $\kappa = 0$ : Minkowski space  $\mathbb{E}^{n-1,1}$
- $\kappa > 0$ : de Sitter space

$$\mathrm{dS}_n \subset \mathbb{E}^{1,n}$$

- $\kappa = 0$ : Minkowski space  $\mathbb{E}^{n-1,1}$
- $\kappa > 0$ : de Sitter space

$$dS_n \subset \mathbb{E}^{1,n}: \qquad -t_1^2 + x_1^2 + x_2^2 + \dots + x_n^2 = \frac{1}{\kappa^2}$$

- $\kappa = 0$ : Minkowski space  $\mathbb{E}^{n-1,1}$
- $\kappa > 0$ : de Sitter space

$$dS_n \subset \mathbb{E}^{1,n}: \qquad -t_1^2 + x_1^2 + x_2^2 + \dots + x_n^2 = \frac{1}{\kappa^2}$$

•  $\kappa$  < 0: anti de Sitter space

$$AdS_n \subset \mathbb{E}^{2,n-1}$$

- $\kappa = 0$ : Minkowski space  $\mathbb{E}^{n-1,1}$
- $\kappa > 0$ : de Sitter space

$$dS_n \subset \mathbb{E}^{1,n}: \qquad -t_1^2 + x_1^2 + x_2^2 + \dots + x_n^2 = \frac{1}{\kappa^2}$$

•  $\kappa$  < 0: anti de Sitter space

$$AdS_n \subset \mathbb{E}^{2,n-1}: \qquad -t_1^2 - t_2^2 + x_1^2 + \dots + x_{n-1}^2 = \frac{-1}{\kappa^2}$$

**Note**: the space form with  $\kappa = 0$  is a geometric limit of the space forms with  $\kappa \neq 0$ .

**Note**: the space form with  $\kappa=0$  is a geometric limit of the space forms with  $\kappa\neq0$ .

It remains to classify smooth discrete quotients of the universal covers of the above spaces.

**Note**: the space form with  $\kappa = 0$  is a geometric limit of the space forms with  $\kappa \neq 0$ .

It remains to classify smooth discrete quotients of the universal covers of the above spaces.

This is the *Clifford–Klein space form* problem, first posed by Killing in 1891 and reformulated in these terms by Hopf in 1925.

**Note**: the space form with  $\kappa = 0$  is a geometric limit of the space forms with  $\kappa \neq 0$ .

It remains to classify smooth discrete quotients of the universal covers of the above spaces.

This is the *Clifford–Klein space form* problem, first posed by Killing in 1891 and reformulated in these terms by Hopf in 1925.

The flat and spherical cases are completely solved (culminating in the work of Wolf in the 1970s), but the possible quotients of hyperbolic and lorentzian cases are still unclassified.

The supersymmetric analogue of the question:

The supersymmetric analogue of the question:

Which are the maximally symmetric spacetimes?

The supersymmetric analogue of the question:

Which are the maximally symmetric spacetimes?

is the question:

The supersymmetric analogue of the question:

Which are the maximally symmetric spacetimes?

is the question:

Which are the maximally supersymmetric backgrounds of supergravity theories?

The supersymmetric analogue of the question:

Which are the maximally symmetric spacetimes?

is the question:

Which are the maximally supersymmetric backgrounds of supergravity theories?

In this talk I will report on progress towards answering this question.

Based on work in collaboration with

#### Based on work in collaboration with

- George Papadopoulos (King's College, London)
  - ★ hep-th/0211089 (JHEP 03 (2003) 048)
  - ★ math.AG/0211170 (*J Geom Phys* to appear)

#### Based on work in collaboration with

- George Papadopoulos (King's College, London)
  - ★ hep-th/0211089 (JHEP 03 (2003) 048)
  - ★ math.AG/0211170 (*J Geom Phys* to appear)
- Ali Chamseddine and Wafic Sabra (CAMS, Beirut)
  - ★ in preparation

# Supergravities

	32		24	20	16		12	8	4
11	М .								
10	IIA IIB				1				
9	N=2				N = 1				
8	N=2				N = 1				
7	N=4		,		N=2				
6	(2,2)	(3,1) (4,0)	(2,1) $(3,0)$		(1,1)	(2, 0)		(1, 0)	
5	N = 8		N = 6		N=4			N = 2	
4	N = 8		N = 6	N = 5	N =	= 4	N = 3	N = 2	N = 1

[Van Proeyen, hep-th/0301005]

Let  $(M, g, \Phi, S)$  be a supergravity background

Let  $(M, g, \Phi, S)$  be a supergravity background:

 $\bullet$  (M,g) a lorentzian spin manifold

Let  $(M, g, \Phi, S)$  be a supergravity background:

- $\bullet$  (M,g) a lorentzian spin manifold
- • denotes collectively the other bosonic fields

Let  $(M, g, \Phi, S)$  be a supergravity background:

- $\bullet$  (M,g) a lorentzian spin manifold
- • denotes collectively the other bosonic fields
- S a real vector bundle of spinors

Let  $(M, g, \Phi, S)$  be a supergravity background:

- $\bullet$  (M,g) a lorentzian spin manifold
- • denotes collectively the other bosonic fields
- S a real vector bundle of spinors
- fermions have been put to zero

 $\overline{(M,g,\Phi,S)}$  is supersymmetric if it admits Killing spinors

 $(M,g,\Phi,S)$  is *supersymmetric* if it admits *Killing spinors*; that is, sections  $\varepsilon$  of S such that

$$D_{\mu}\varepsilon = 0$$

 $(M,g,\Phi,S)$  is *supersymmetric* if it admits *Killing spinors*; that is, sections  $\varepsilon$  of S such that

$$D_{\mu}\varepsilon = 0$$

where D is the connection on S

 $(M,g,\Phi,S)$  is *supersymmetric* if it admits *Killing spinors*; that is, sections  $\varepsilon$  of S such that

$$D_{\mu}\varepsilon = 0$$

where D is the connection on S

$$D_{\mu} = \nabla_{\mu} + \Omega_{\mu}(g, \Phi)$$

 $(M, g, \Phi, S)$  is *supersymmetric* if it admits *Killing spinors*; that is, sections  $\varepsilon$  of S such that

$$D_{\mu}\varepsilon=0$$

where D is the connection on S

$$D_{\mu} = \nabla_{\mu} + \Omega_{\mu}(g, \Phi)$$

defined by the supersymmetric variation of the gravitino:

$$\delta_{\varepsilon}\Psi_{\mu} = D_{\mu}\varepsilon$$

$$A(g,\Phi)\varepsilon=0$$

$$A(g,\Phi)\varepsilon = 0$$

where A is the algebraic operator defined by the supersymmetric variation of any other fermionic fields

$$A(g,\Phi)\varepsilon = 0$$

where A is the algebraic operator defined by the supersymmetric variation of any other fermionic fields (dilatinos, gauginos,...)

$$A(g,\Phi)\varepsilon=0$$

where A is the algebraic operator defined by the supersymmetric variation of any other fermionic fields (dilatinos, gauginos,...)

$$\delta_{\varepsilon}\chi = A\varepsilon$$

$$A(g,\Phi)\varepsilon=0$$

where A is the algebraic operator defined by the supersymmetric variation of any other fermionic fields (dilatinos, gauginos,...)

$$\delta_{\varepsilon}\chi = A\varepsilon$$

Maximal supersymmetry ⇒

$$A(g,\Phi)\varepsilon=0$$

where A is the algebraic operator defined by the supersymmetric variation of any other fermionic fields (dilatinos, gauginos,...)

$$\delta_{\varepsilon}\chi = A\varepsilon$$

Maximal supersymmetry  $\Longrightarrow D$  is flat

$$A(g,\Phi)\varepsilon=0$$

where A is the algebraic operator defined by the supersymmetric variation of any other fermionic fields (dilatinos, gauginos,...)

$$\delta_{\varepsilon}\chi = A\varepsilon$$

Maximal supersymmetry  $\Longrightarrow D$  is flat and A = 0.

$$A(g,\Phi)\varepsilon=0$$

where A is the algebraic operator defined by the supersymmetric variation of any other fermionic fields (dilatinos, gauginos,...)

$$\delta_{\varepsilon}\chi = A\varepsilon$$

Maximal supersymmetry  $\Longrightarrow D$  is flat and A = 0.

Typically A = 0 sets some gauge field strengths to zero

$$A(g,\Phi)\varepsilon = 0$$

where A is the algebraic operator defined by the supersymmetric variation of any other fermionic fields (dilatinos, gauginos,...)

$$\delta_{\varepsilon}\chi = A\varepsilon$$

Maximal supersymmetry  $\Longrightarrow D$  is flat and A = 0.

Typically A=0 sets some gauge field strengths to zero, and the flatness of D constrains the geometry and any remaining field strengths.

$$A(g,\Phi)\varepsilon=0$$

where A is the algebraic operator defined by the supersymmetric variation of any other fermionic fields (dilatinos, gauginos,...)

$$\delta_{\varepsilon}\chi = A\varepsilon$$

Maximal supersymmetry  $\Longrightarrow D$  is flat and A = 0.

Typically A=0 sets some gauge field strengths to zero, and the flatness of D constrains the geometry and any remaining field strengths. The strategy is therefore to study the flatness equations for D.

### **Classifications**

In the table we have highlighted the "top" theories whose maximally supersymmetric backgrounds are known:

### **Classifications**

In the table we have highlighted the "top" theories whose maximally supersymmetric backgrounds are known:

• 
$$D = 4 N = 1$$

[Tod (1984)]

#### **Classifications**

In the table we have highlighted the "top" theories whose maximally supersymmetric backgrounds are known:

• 
$$D = 4 \ N = 1$$
 [Tod (1984)]

• 
$$D = 6 (1,0)$$
,  $(2,0)$  [Chamseddine–FO–Sabra (2003)]

#### **Classifications**

In the table we have highlighted the "top" theories whose maximally supersymmetric backgrounds are known:

• 
$$D = 4 \ N = 1$$
 [Tod (1984)]

• 
$$D = 6 (1,0)$$
,  $(2,0)$  [Chamseddine–FO–Sabra (2003)]

• 
$$D=10~{\sf IIB}$$
 and  ${\sf I}$  [FO-Papadopoulos (2002)]

[Tod (1984)]

#### **Classifications**

In the table we have highlighted the "top" theories whose maximally supersymmetric backgrounds are known:

• 
$$D = 4 N = 1$$

• D = 6 (1,0), (2,0) [Chamseddine-FO-Sabra (2003)]

• D=10 IIB and I [FO-Papadopoulos (2002)]

•  $D=11~\mathrm{M}$  [FO-Papadopoulos (2001)]

bosonic fields

- bosonic fields:
  - $\star$  metric g

- bosonic fields:
  - $\star$  metric g, and
  - $\star$  closed 4-form F

- bosonic fields:
  - $\star$  metric g, and
  - $\star$  closed 4-form F

for a total of 44 + 84 = 128 bosonic physical degrees of freedom.

- bosonic fields:
  - $\star$  metric g, and
  - $\star$  closed 4-form F

for a total of 44 + 84 = 128 bosonic physical degrees of freedom.

• spinors are Majorana

- bosonic fields:
  - $\star$  metric g, and
  - $\star$  closed 4-form F

for a total of 44 + 84 = 128 bosonic physical degrees of freedom.

• spinors are Majorana; that is, associated to one of the two irreducible real 32-dimensional representations of  $C\ell(1,10)$ .

- bosonic fields:
  - $\star$  metric g, and
  - $\star$  closed 4-form F

for a total of 44 + 84 = 128 bosonic physical degrees of freedom.

• spinors are Majorana; that is, associated to one of the two irreducible real 32-dimensional representations of  $C\ell(1,10)$ . Therefore the gravitino also has 128 physical degrees of freedom.

• the gravitino variation defines the connection

$$D_{\mu} = \nabla_{\mu} - \frac{1}{288} F_{\nu\rho\sigma\tau} \left( \Gamma^{\nu\rho\sigma\tau}{}_{\mu} + 8\Gamma^{\nu\rho\sigma} \delta^{\tau}_{\mu} \right)$$

• the gravitino variation defines the connection

$$D_{\mu} = \nabla_{\mu} - \frac{1}{288} F_{\nu\rho\sigma\tau} \left( \Gamma^{\nu\rho\sigma\tau}{}_{\mu} + 8\Gamma^{\nu\rho\sigma} \delta^{\tau}_{\mu} \right)$$

For fixed  $\mu, \nu$ , the curvature  $\Re_{\mu\nu}$  of D can be expanded in terms of antisymmetric products of  $\Gamma$  matrices

• the gravitino variation defines the connection

$$D_{\mu} = \nabla_{\mu} - \frac{1}{288} F_{\nu\rho\sigma\tau} \left( \Gamma^{\nu\rho\sigma\tau}{}_{\mu} + 8\Gamma^{\nu\rho\sigma} \delta^{\tau}_{\mu} \right)$$

For fixed  $\mu, \nu$ , the curvature  $\Re_{\mu\nu}$  of D can be expanded in terms of antisymmetric products of  $\Gamma$  matrices

$$[D_{\mu}, D_{\nu}] = \mathcal{R}_{\mu\nu}{}^{I} \Gamma_{I}$$

the gravitino variation defines the connection

$$D_{\mu} = \nabla_{\mu} - \frac{1}{288} F_{\nu\rho\sigma\tau} \left( \Gamma^{\nu\rho\sigma\tau}{}_{\mu} + 8\Gamma^{\nu\rho\sigma} \delta^{\tau}_{\mu} \right)$$

For fixed  $\mu, \nu$ , the curvature  $\Re_{\mu\nu}$  of D can be expanded in terms of antisymmetric products of  $\Gamma$  matrices

$$[D_{\mu}, D_{\nu}] = \mathcal{R}_{\mu\nu}{}^{I} \Gamma_{I}$$

where *I* is an index labeling the following elements

$$\Gamma_a$$
  $\Gamma_{ab}$   $\Gamma_{abc}$   $\Gamma_{abcd}$   $\Gamma_{abcde}$ 

(We have used that  $\Gamma_{01...9
atural} = -1$  in this representation.)

(We have used that  $\Gamma_{01...9
atural} = -1$  in this representation.)

The flatness equations are the vanishing of the  $\Re_{\mu\nu}^{I}$ .

(We have used that  $\Gamma_{01...9
atural} = -1$  in this representation.)

The flatness equations are the vanishing of the  $\Re_{\mu\nu}^{I}$ .

Summarising the results:

(We have used that  $\Gamma_{01...9} = -1$  in this representation.)

The flatness equations are the vanishing of the  $\Re_{\mu\nu}^{I}$ .

Summarising the results:

• F is parallel:  $\nabla F = 0$ 

(We have used that  $\Gamma_{01...9b} = -1$  in this representation.)

The flatness equations are the vanishing of the  $\Re_{\mu\nu}^{I}$ .

Summarising the results:

• F is parallel:  $\nabla F = 0$ 

• the Riemann curvature tensor is determined  $\underbrace{\textit{algebraically}}_{\textit{algebraically}}$  in terms of F and g

(We have used that  $\Gamma_{01...9b} = -1$  in this representation.)

The flatness equations are the vanishing of the  $\Re_{\mu\nu}^{I}$ .

Summarising the results:

- F is parallel:  $\nabla F = 0$
- the Riemann curvature tensor is determined *algebraically* in terms of  ${\it F}$  and  ${\it g}$ :

$$R_{\mu\nu\rho\sigma} = T_{\mu\nu\rho\sigma}(F,g)$$

with T quadratic in F

(We have used that  $\Gamma_{01...9} = -1$  in this representation.)

The flatness equations are the vanishing of the  $\Re_{\mu\nu}^{I}$ .

Summarising the results:

- F is parallel:  $\nabla F = 0$
- the Riemann curvature tensor is determined <u>algebraically</u> in terms of F and g:

$$R_{\mu\nu\rho\sigma} = T_{\mu\nu\rho\sigma}(F,g)$$

with T quadratic in F. This means that  $R_{\mu\nu\rho\sigma}$  is parallel

(We have used that  $\Gamma_{01...9b} = -1$  in this representation.)

The flatness equations are the vanishing of the  $\Re_{\mu\nu}^{I}$ .

Summarising the results:

- F is parallel:  $\nabla F = 0$
- the Riemann curvature tensor is determined <u>algebraically</u> in terms of F and g:

$$R_{\mu\nu\rho\sigma} = T_{\mu\nu\rho\sigma}(F,g)$$

with T quadratic in F. This means that  $R_{\mu\nu\rho\sigma}$  is parallel; equivalently, that g is locally symmetric.

$$\iota_X \iota_Y \iota_Z F \wedge F = 0$$
 for all  $X, Y, Z$ 

$$\iota_X \iota_Y \iota_Z F \wedge F = 0$$
 for all  $X, Y, Z$ 

or

$$F_{\alpha\beta\gamma[\mu}F_{\nu\rho\sigma\tau]} = 0$$

$$\iota_X \iota_Y \iota_Z F \wedge F = 0$$
 for all  $X, Y, Z$ 

or

$$F_{\alpha\beta\gamma[\mu}F_{\nu\rho\sigma\tau]} = 0$$

The solution is that F is  $\frac{decomposable}{decomposable}$  into a wedge product of four 1-forms

$$\iota_X \iota_Y \iota_Z F \wedge F = 0$$
 for all  $X, Y, Z$ 

or

$$F_{\alpha\beta\gamma[\mu}F_{\nu\rho\sigma\tau]} = 0$$

The solution is that F is decomposable into a wedge product of four 1-forms:

$$F = \theta^1 \wedge \theta^2 \wedge \theta^3 \wedge \theta^4$$

$$\iota_X \iota_Y \iota_Z F \wedge F = 0$$
 for all  $X, Y, Z$ 

or

$$F_{\alpha\beta\gamma[\mu}F_{\nu\rho\sigma\tau]} = 0$$

The solution is that F is decomposable into a wedge product of four 1-forms:

$$F = \theta^1 \wedge \theta^2 \wedge \theta^3 \wedge \theta^4 \qquad \text{or} \qquad F_{\mu\nu\rho\sigma} = \theta^1_{[\mu} \theta^2_{\nu} \theta^3_{\rho} \theta^4_{\sigma]}$$

We can restrict to the tangent space at any one point in the spacetime:

We can restrict to the tangent space at any one point in the spacetime: the metric g defines a lorentzian inner product and F is either zero or defines a 4-plane

If *F* is zero, then the solution is flat.

If F is zero, then the solution is flat. Otherwise

If F is zero, then the solution is flat. Otherwise:

• if the plane is euclidean

If *F* is zero, then the solution is flat. Otherwise:

• if the plane is euclidean, we can choose a pseudo-orthonormal frame in which the only nonzero component of F is  $F_{1234}$ 

If *F* is zero, then the solution is flat. Otherwise:

- if the plane is euclidean, we can choose a pseudo-orthonormal frame in which the only nonzero component of F is  $F_{1234}$
- if the plane is lorentzian

If *F* is zero, then the solution is flat. Otherwise:

- if the plane is euclidean, we can choose a pseudo-orthonormal frame in which the only nonzero component of F is  $F_{1234}$
- if the plane is lorentzian, we can choose a pseudo-orthonormal frame in which the only nonzero component of F is  $F_{0123}$

If *F* is zero, then the solution is flat. Otherwise:

- if the plane is euclidean, we can choose a pseudo-orthonormal frame in which the only nonzero component of F is  $F_{1234}$
- if the plane is lorentzian, we can choose a pseudo-orthonormal frame in which the only nonzero component of F is  $F_{0123}$
- if the plane is null

We can restrict to the tangent space at any one point in the spacetime: the metric g defines a lorentzian inner product and F is either zero or defines a 4-plane: the plane spanned by the  $\theta^i$ .

If *F* is zero, then the solution is flat. Otherwise:

- if the plane is euclidean, we can choose a pseudo-orthonormal frame in which the only nonzero component of F is  $F_{1234}$
- if the plane is lorentzian, we can choose a pseudo-orthonormal frame in which the only nonzero component of F is  $F_{0123}$
- if the plane is null, we can choose a pseudo-orthonormal frame in which the only nonzero component of F is  $F_{-123}$

We now plug these expressions back into the equation which relates the curvature tensor to  ${\it F}$  and  ${\it g}$ 

We now plug these expressions back into the equation which relates the curvature tensor to  $\boldsymbol{F}$  and  $\boldsymbol{g}$  finding the following solutions:

• F euclidean

We now plug these expressions back into the equation which relates the curvature tensor to F and g finding the following solutions:

• F euclidean: a one parameter R > 0 family of vacua

$$AdS_7(-7R) \times S^4(8R) \qquad F = \sqrt{6R} \operatorname{dvol}(S^4)$$

We now plug these expressions back into the equation which relates the curvature tensor to F and g finding the following solutions:

• F euclidean: a one parameter R > 0 family of vacua

$$AdS_7(-7R) \times S^4(8R) \qquad F = \sqrt{6R} \operatorname{dvol}(S^4)$$

F lorentzian

We now plug these expressions back into the equation which relates the curvature tensor to F and g finding the following solutions:

• F euclidean: a one parameter R > 0 family of vacua

$$AdS_7(-7R) \times S^4(8R) \qquad F = \sqrt{6R} \operatorname{dvol}(S^4)$$

ullet F lorentzian: a one parameter R < 0 family of vacua

$$AdS_4(8R) \times S^7(-7R)$$
  $F = \sqrt{-6R} \operatorname{dvol}(AdS_4)$ 

ullet F null

$$g = 2dx^{+}dx^{-} - \frac{1}{36}\mu^{2} \left(4\sum_{i=1}^{3} (x^{i})^{2} + \sum_{i=4}^{9} (x^{i})^{2}\right) (dx^{-})^{2} + \sum_{i=1}^{9} (dx^{i})^{2}$$

$$g = 2dx^{+}dx^{-} - \frac{1}{36}\mu^{2} \left( 4\sum_{i=1}^{3} (x^{i})^{2} + \sum_{i=4}^{9} (x^{i})^{2} \right) (dx^{-})^{2} + \sum_{i=1}^{9} (dx^{i})^{2}$$
$$F = \mu dx^{-} \wedge dx^{1} \wedge dx^{2} \wedge dx^{3}$$

Notice that for  $\mu = 0$  we recover the flat space solution

$$g = 2dx^{+}dx^{-} - \frac{1}{36}\mu^{2} \left( 4\sum_{i=1}^{3} (x^{i})^{2} + \sum_{i=4}^{9} (x^{i})^{2} \right) (dx^{-})^{2} + \sum_{i=1}^{9} (dx^{i})^{2}$$
$$F = \mu dx^{-} \wedge dx^{1} \wedge dx^{2} \wedge dx^{3}$$

Notice that for  $\mu=0$  we recover the flat space solution; whereas for  $\mu\neq 0$  all solutions are equivalent

$$g = 2dx^{+}dx^{-} - \frac{1}{36}\mu^{2} \left( 4\sum_{i=1}^{3} (x^{i})^{2} + \sum_{i=4}^{9} (x^{i})^{2} \right) (dx^{-})^{2} + \sum_{i=1}^{9} (dx^{i})^{2}$$
$$F = \mu dx^{-} \wedge dx^{1} \wedge dx^{2} \wedge dx^{3}$$

Notice that for  $\mu=0$  we recover the flat space solution; whereas for  $\mu\neq 0$  all solutions are equivalent and coincide with the eleven-dimensional vacuum discovered by Kowalski-Glikman in 1984.

$$g = 2dx^{+}dx^{-} - \frac{1}{36}\mu^{2} \left( 4\sum_{i=1}^{3} (x^{i})^{2} + \sum_{i=4}^{9} (x^{i})^{2} \right) (dx^{-})^{2} + \sum_{i=1}^{9} (dx^{i})^{2}$$
$$F = \mu dx^{-} \wedge dx^{1} \wedge dx^{2} \wedge dx^{3}$$

Notice that for  $\mu=0$  we recover the flat space solution; whereas for  $\mu\neq 0$  all solutions are equivalent and coincide with the eleven-dimensional vacuum discovered by Kowalski-Glikman in 1984.

All vacua embed isometrically in  $\mathbb{E}^{2,11}$  as the intersections of two quadrics.

#### Solutions are related by Penrose limits

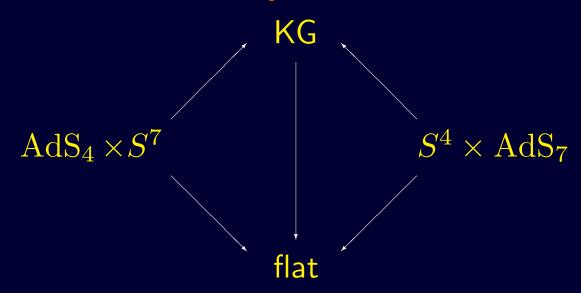
[Blau-FO-Hull-Papadopoulos hep-th/0201081] [Blau-FO-Papadopoulos hep-th/0202111]

$$AdS_4 \times S^7$$

$$S^4 \times AdS_7$$

[Blau–FO–Hull–Papadopoulos hep–th/0201081]  $\mbox{ [Blau–FO-Papadopoulos hep-th/0202111]} \mbox{ } \mbox{ }$ 

[Blau-FO-Hull-Papadopoulos hep-th/0201081] [Blau-FO-Papadopoulos hep-th/0202111]



[Back]

$$(1,0)$$
  $D=6$  supergravity

bosonic fields

- bosonic fields:
  - $\star$  metric g

- bosonic fields:
  - $\star$  metric g
  - $\star$  anti-selfdual closed 3-form F

- bosonic fields:
  - $\star$  metric g
  - $\star$  anti-selfdual closed 3-form F

for a total of 9 + 3 = 12 physical bosonic degrees of freedom

- bosonic fields:
  - $\star$  metric g
  - $\star$  anti-selfdual closed 3-form F

for a total of 9 + 3 = 12 physical bosonic degrees of freedom

spinors are positive-chirality symplectic Majorana–Weyl

- bosonic fields:
  - $\star$  metric g
  - $\star$  anti-selfdual closed 3-form F

for a total of 9 + 3 = 12 physical bosonic degrees of freedom

• spinors are positive-chirality symplectic Majorana–Weyl; i.e., associated to the 8-dimensional real representation of  $Spin(1, 5) \times Sp(1)$  having positive six-dimensional chirality.

- bosonic fields:
  - $\star$  metric g
  - $\star$  anti-selfdual closed 3-form F

for a total of 9 + 3 = 12 physical bosonic degrees of freedom

• spinors are positive-chirality symplectic Majorana–Weyl; i.e., associated to the 8-dimensional real representation of  $Spin(1,5) \times Sp(1)$  having positive six-dimensional chirality.

The gravitino has therefore also 12 physical degrees of freedom.

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu}{}^{ab} \Gamma_{ab}$$

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu}{}^{ab} \Gamma_{ab}$$

The connection D is actually induced from a  $metric\ connection$   $with\ torsion$ 

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu}{}^{ab} \Gamma_{ab}$$

The connection D is actually induced from a  $metric\ connection$  with torsion; i.e., Dg=0

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu}{}^{ab} \Gamma_{ab}$$

The connection D is actually induced from a *metric connection* with torsion; i.e., Dg=0 and

$$D_{\mu}\partial_{\nu} = \hat{\Gamma}_{\mu\nu}{}^{\rho}\partial_{\rho}$$

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu}{}^{ab} \Gamma_{ab}$$

The connection D is actually induced from a  $metric\ connection$  with torsion; i.e., Dg=0 and

$$D_{\mu}\partial_{\nu}=\hat{\Gamma}_{\mu\nu}{}^{\rho}\partial_{\rho}$$
 with  $\hat{\Gamma}_{\mu\nu}{}^{\rho}=\Gamma_{\mu\nu}{}^{\rho}+F_{\mu\nu}{}^{\rho}$ 

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu}{}^{ab} \Gamma_{ab}$$

The connection D is actually induced from a metric connection with torsion; i.e., Dg=0 and

$$D_{\mu}\partial_{\nu}=\hat{\Gamma}_{\mu\nu}{}^{\rho}\partial_{\rho}$$
 with  $\hat{\Gamma}_{\mu\nu}{}^{\rho}=\Gamma_{\mu\nu}{}^{\rho}+F_{\mu\nu}{}^{\rho}$ 

Maximal supersymmetry  $\implies D$  is flat.

A lorentzian manifold admitting a flat metric connection with torsion

A lorentzian manifold admitting a flat metric connection with torsion is locally isometric to a parallelised Lie group with bi-invariant metric.

A lorentzian manifold admitting a flat metric connection with torsion is locally isometric to a parallelised Lie group with bi-invariant metric.

As a corollary, vacua of (1,0) D=6 supergravity are locally isometric to six-dimensional Lie groups

A lorentzian manifold admitting a flat metric connection with torsion is locally isometric to a parallelised Lie group with bi-invariant metric.

As a corollary, vacua of (1,0) D=6 supergravity are locally isometric to six-dimensional Lie groups admitting a bi-invariant lorentzian metric

A lorentzian manifold admitting a flat metric connection with torsion is locally isometric to a parallelised Lie group with bi-invariant metric.

As a corollary, vacua of (1,0) D=6 supergravity are locally isometric to six-dimensional Lie groups admitting a bi-invariant lorentzian metric and whose parallelizing torsion is anti-self-dual.

A lorentzian manifold admitting a flat metric connection with torsion is locally isometric to a parallelised Lie group with bi-invariant metric.

As a corollary, vacua of (1,0) D=6 supergravity are locally isometric to six-dimensional Lie groups admitting a bi-invariant lorentzian metric and whose parallelizing torsion is anti-self-dual.

Equivalently, they are in one-to-one correspondence with six-dimensional Lie algebras with an invariant lorentzian metric

A lorentzian manifold admitting a flat metric connection with torsion is locally isometric to a parallelised Lie group with bi-invariant metric.

As a corollary, vacua of (1,0) D=6 supergravity are locally isometric to six-dimensional Lie groups admitting a bi-invariant lorentzian metric and whose parallelizing torsion is anti-self-dual.

Equivalently, they are in one-to-one correspondence with six-dimensional Lie algebras with an invariant lorentzian metric and with anti-selfdual structure constants  $f_{abc}$ .

A lorentzian manifold admitting a flat metric connection with torsion is locally isometric to a parallelised Lie group with bi-invariant metric.

As a corollary, vacua of (1,0) D=6 supergravity are locally isometric to six-dimensional Lie groups admitting a bi-invariant lorentzian metric and whose parallelizing torsion is anti-self-dual.

Equivalently, they are in one-to-one correspondence with six-dimensional Lie algebras with an invariant lorentzian metric and with anti-selfdual structure constants  $f_{abc}$ .

The solution to this problem is known.

Which Lie algebras have an invariant metric?

abelian Lie algebras

Which Lie algebras have an invariant metric?

• abelian Lie algebras with any metric

- abelian Lie algebras with any metric
- semisimple Lie algebras

- abelian Lie algebras with any metric
- semisimple Lie algebras with the Killing form (Cartan's criterion)

- abelian Lie algebras with any metric
- semisimple Lie algebras with the Killing form (Cartan's criterion)
- reductive Lie algebras = semisimple ⊕ abelian

- abelian Lie algebras with any metric
- semisimple Lie algebras with the Killing form (Cartan's criterion)
- reductive Lie algebras = semisimple ⊕ abelian
- classical doubles  $\mathfrak{h} \ltimes \mathfrak{h}^*$

- abelian Lie algebras with any metric
- semisimple Lie algebras with the Killing form (Cartan's criterion)
- reductive Lie algebras = semisimple ⊕ abelian
- classical doubles  $\mathfrak{h} \ltimes \mathfrak{h}^*$  with the dual pairing

#### Which Lie algebras have an invariant metric?

- abelian Lie algebras with any metric
- semisimple Lie algebras with the Killing form (Cartan's criterion)
- reductive Lie algebras = semisimple ⊕ abelian
- classical doubles  $\mathfrak{h} \ltimes \mathfrak{h}^*$  with the dual pairing

But there is a more general construction.

• g a Lie algebra with an invariant metric

- g a Lie algebra with an invariant metric
- h a Lie algebra acting on g via antisymmetric derivations

- g a Lie algebra with an invariant metric
- h a Lie algebra acting on g via antisymmetric derivations; i.e.,
  - ★ preserving the Lie bracket of g

- g a Lie algebra with an invariant metric
- $\mathfrak{h}$  a Lie algebra acting on  $\mathfrak{g}$  via antisymmetric derivations; i.e.,
  - ★ preserving the Lie bracket of g, and
  - ★ preserving the metric

- g a Lie algebra with an invariant metric
- h a Lie algebra acting on g via antisymmetric derivations; i.e.,
  - ★ preserving the Lie bracket of g, and
  - ★ preserving the metric
- since h preserves the metric on g, there is a linear map

$$\mathfrak{h} o \Lambda^2 \mathfrak{g}$$

$$\omega:\Lambda^2\mathfrak{g} o\mathfrak{h}^*$$

$$\omega:\Lambda^2\mathfrak{g} o\mathfrak{h}^*$$

is a cocycle

$$\omega:\Lambda^2\mathfrak{g} o\mathfrak{h}^*$$

is a *cocycle* because h preserves the Lie bracket in g

$$\omega:\Lambda^2\mathfrak{g} o\mathfrak{h}^*$$

is a *cocycle* because h preserves the Lie bracket in g

• so we build the central extension  $\mathfrak{g} \times_{\omega} \mathfrak{h}^*$ 

$$\omega:\Lambda^2\mathfrak{g} o\mathfrak{h}^*$$

is a *cocycle* because h preserves the Lie bracket in g

• so we build the central extension  $\mathfrak{g} \times_{\omega} \mathfrak{h}^*$ ; i.e.,

$$[X_a, X_b] = f_{ab}{}^c X_c + \omega_{ab i} H^i$$

$$\omega:\Lambda^2\mathfrak{g} o\mathfrak{h}^*$$

is a *cocycle* because h preserves the Lie bracket in g

• so we build the central extension  $\mathfrak{g} \times_{\omega} \mathfrak{h}^*$ ; i.e.,

$$[X_a, X_b] = f_{ab}{}^c X_c + \omega_{ab i} H^i$$

relative to bases  $X_a$ ,  $H_i$  and  $H^i$  for  $\mathfrak{g}$ ,  $\mathfrak{h}$  and  $\mathfrak{h}^*$ , respectively.

$$\omega:\Lambda^2\mathfrak{g} o\mathfrak{h}^*$$

is a *cocycle* because h preserves the Lie bracket in g

• so we build the central extension  $\mathfrak{g} \times_{\omega} \mathfrak{h}^*$ ; i.e.,

$$[X_a, X_b] = f_{ab}{}^c X_c + \omega_{ab i} H^i$$

relative to bases  $X_a$ ,  $H_i$  and  $H^i$  for  $\mathfrak{g}$ ,  $\mathfrak{h}$  and  $\mathfrak{h}^*$ , respectively.

•  $\mathfrak{h}$  acts on  $\mathfrak{g} \times_{\omega} \mathfrak{h}^*$  preserving the Lie bracket

$$\omega:\Lambda^2\mathfrak{g} o\mathfrak{h}^*$$

is a *cocycle* because h preserves the Lie bracket in g

• so we build the central extension  $\mathfrak{g} \times_{\omega} \mathfrak{h}^*$ ; i.e.,

$$[X_a, X_b] = f_{ab}{}^c X_c + \omega_{ab i} H^i$$

relative to bases  $X_a$ ,  $H_i$  and  $H^i$  for  $\mathfrak{g}$ ,  $\mathfrak{h}$  and  $\mathfrak{h}^*$ , respectively.

•  $\mathfrak{h}$  acts on  $\mathfrak{g} \times_{\omega} \mathfrak{h}^*$  preserving the Lie bracket, so we can form the double extension

$$\mathfrak{d}(\mathfrak{g},\mathfrak{h})=\mathfrak{h}\ltimes(\mathfrak{g} imes_{\omega}\mathfrak{h}^*)$$

$$egin{array}{ccccc} X_b & H_j & H^j \ X_a & \left(egin{array}{cccc} g_{ab} & 0 & 0 \ 0 & B_{ij} & \delta^j_i \ H^i & 0 & \delta^i_j & 0 \end{array}
ight) \end{array}$$

$$X_b \quad H_j \quad H^j \ X_a \quad \left(egin{array}{ccc} g_{ab} & 0 & 0 \ 0 & B_{ij} & \delta^j_i \ H^i & 0 & \delta^i_j & 0 \end{array}
ight)$$

where  $B_{ij}$  is any invariant symmetric bilinear form on  $\mathfrak{h}$  (not necessarily nondegenerate).

$$egin{array}{ccccc} X_b & H_j & H^j \ X_a & \left(egin{array}{cccc} g_{ab} & 0 & 0 \ 0 & B_{ij} & \delta^j_i \ H^i & 0 & \delta^i_j & 0 \end{array}
ight) \end{array}$$

where  $B_{ij}$  is any invariant symmetric bilinear form on  $\mathfrak{h}$  (not necessarily nondegenerate).

This construction is due to Medina and Revoy who proved an important structure theorem.

A metric Lie algebra is *indecomposable* if it is not the direct sum of two orthogonal ideals.

A metric Lie algebra is *indecomposable* if it is not the direct sum of two orthogonal ideals.

Theorem (Medina–Revoy (1985)).

A metric Lie algebra is *indecomposable* if it is not the direct sum of two orthogonal ideals.

Theorem (Medina–Revoy (1985)).

An indecomposable metric Lie algebra is either

A metric Lie algebra is *indecomposable* if it is not the direct sum of two orthogonal ideals.

Theorem (Medina–Revoy (1985)).

An indecomposable metric Lie algebra is either simple

A metric Lie algebra is *indecomposable* if it is not the direct sum of two orthogonal ideals.

#### Theorem (Medina–Revoy (1985)).

An indecomposable metric Lie algebra is either simple, onedimensional

### The structure theorem of Medina and Revoy

A metric Lie algebra is *indecomposable* if it is not the direct sum of two orthogonal ideals.

#### Theorem (Medina–Revoy (1985)).

An indecomposable metric Lie algebra is either simple, one-dimensional, or a double extension  $\mathfrak{d}(\mathfrak{g},\mathfrak{h})$  where  $\mathfrak{h}$  is either simple or one-dimensional.

# The structure theorem of Medina and Revoy

A metric Lie algebra is *indecomposable* if it is not the direct sum of two orthogonal ideals.

#### Theorem (Medina–Revoy (1985)).

An indecomposable metric Lie algebra is either simple, one-dimensional, or a double extension  $\mathfrak{d}(\mathfrak{g},\mathfrak{h})$  where  $\mathfrak{h}$  is either simple or one-dimensional.

Every metric Lie algebra is obtained as an orthogonal direct sum of indecomposables.

It is now easy to list all six-dimensional lorentzian Lie algebras.

It is now easy to list all six-dimensional lorentzian Lie algebras.

Notice that if the metric on  $\mathfrak{g}$  has signature (p,q) and  $\mathfrak{h}$  is r-dimensional, the metric on  $\mathfrak{d}(\mathfrak{g},\mathfrak{h})$  has signature (p+r,q+r).

It is now easy to list all six-dimensional lorentzian Lie algebras.

Notice that if the metric on  $\mathfrak{g}$  has signature (p,q) and  $\mathfrak{h}$  is r-dimensional, the metric on  $\mathfrak{d}(\mathfrak{g},\mathfrak{h})$  has signature (p+r,q+r).

Therefore a lorentzian Lie algebra takes the general form

It is now easy to list all six-dimensional lorentzian Lie algebras.

Notice that if the metric on  $\mathfrak{g}$  has signature (p,q) and  $\mathfrak{h}$  is r-dimensional, the metric on  $\mathfrak{d}(\mathfrak{g},\mathfrak{h})$  has signature (p+r,q+r).

Therefore a lorentzian Lie algebra takes the general form

reductive  $\oplus \mathfrak{d}(\mathfrak{a},\mathfrak{h})$ 

It is now easy to list all six-dimensional lorentzian Lie algebras.

Notice that if the metric on  $\mathfrak{g}$  has signature (p,q) and  $\mathfrak{h}$  is r-dimensional, the metric on  $\mathfrak{d}(\mathfrak{g},\mathfrak{h})$  has signature (p+r,q+r).

Therefore a lorentzian Lie algebra takes the general form

reductive 
$$\oplus \mathfrak{d}(\mathfrak{a},\mathfrak{h})$$

where  $\alpha$  is abelian with euclidean metric and  $\beta$  is one-dimensional.

It is now easy to list all six-dimensional lorentzian Lie algebras.

Notice that if the metric on  $\mathfrak{g}$  has signature (p,q) and  $\mathfrak{h}$  is r-dimensional, the metric on  $\mathfrak{d}(\mathfrak{g},\mathfrak{h})$  has signature (p+r,q+r).

Therefore a lorentzian Lie algebra takes the general form

reductive 
$$\oplus \mathfrak{d}(\mathfrak{a},\mathfrak{h})$$

where  $\alpha$  is abelian with euclidean metric and  $\beta$  is one-dimensional.

(Any semisimple factors in  $\mathfrak{a}$  factor out of the double extension.

[FO-Stanciu hep-th/9402035]

lacksquare  $\mathbb{R}^{5,1}$ 

- lacksquare  $\mathbb{R}^{5,1}$
- ullet  $\mathfrak{so}(3)\oplus \mathbb{R}^{2,1}$

- lacksquare  $\mathbb{R}^{5,1}$
- ullet  $\mathfrak{so}(3) \oplus \mathbb{R}^{2,1}$
- ullet  $\mathfrak{so}(2,1)\oplus \mathbb{R}^3$

- ullet  $\mathbb{R}^{5,1}$
- $ullet \mathfrak{so}(3) \oplus \mathbb{R}^{2,1}$
- $ullet \mathfrak{so}(2,1) \oplus \mathbb{R}^3$
- ullet  $\mathfrak{so}(2,1)\oplus \overline{\mathfrak{so}(3)}$

- lacksquare  $\mathbb{R}^{5,1}$
- $ullet \mathfrak{so}(3) \oplus \mathbb{R}^{2,1}$
- ullet  $\mathfrak{so}(2,1)\oplus \mathbb{R}^3$
- $ullet \mathfrak{so}(2,1) \oplus \mathfrak{so}(3)$
- ullet  $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$

- lacksquare  $\mathbb{R}^{5,1}$
- ullet  $\mathfrak{so}(3)\oplus\mathbb{R}^{2,1}$
- $ullet \mathfrak{so}(2,1) \oplus \mathbb{R}^3$
- $ullet \mathfrak{so}(2,1) \oplus \mathfrak{so}(3)$
- $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$ , actually a family of Lie algebras parametrised by homomorphisms

$$\mathbb{R} \to \Lambda^2 \mathbb{R}^4 \cong \mathfrak{so}(4)$$

lacksquare  $\mathbb{R}^{5,1}$ 

- lacksquare  $\mathbb{R}^{5,1}$
- $\mathfrak{so}(2,1) \oplus \mathfrak{so}(3)$  with "commensurate" metrics

- lacksquare  $\mathbb{R}^{5,1}$
- $\mathfrak{so}(2,1) \oplus \mathfrak{so}(3)$  with "commensurate" metrics, and
- $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$  with the image of  $\mathbb{R} \to \Lambda^2 \mathbb{R}^4$  self-dual

- lacksquare  $\mathbb{R}^{5,1}$
- $\mathfrak{so}(2,1) \oplus \mathfrak{so}(3)$  with "commensurate" metrics, and
- $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$  with the image of  $\mathbb{R} \to \Lambda^2 \mathbb{R}^4$  self-dual

The first case corresponds to the flat vacuum.

- lacksquare  $\mathbb{R}^{5,1}$
- $\mathfrak{so}(2,1) \oplus \mathfrak{so}(3)$  with "commensurate" metrics, and
- ullet  $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$  with the image of  $\mathbb{R} o \Lambda^2\mathbb{R}^4$  self-dual

The first case corresponds to the flat vacuum. The second case corresponds to  $AdS_3 \times S^3$  with equal radii of curvature and

$$F \propto \operatorname{dvol}(AdS_3) + \operatorname{dvol}(S^3)$$

- lacksquare  $\mathbb{R}^{5,1}$
- $\mathfrak{so}(2,1) \oplus \mathfrak{so}(3)$  with "commensurate" metrics, and
- ullet  $\mathfrak{d}(\mathbb{R}^4,\mathbb{R})$  with the image of  $\mathbb{R} o \Lambda^2 \mathbb{R}^4$  self-dual

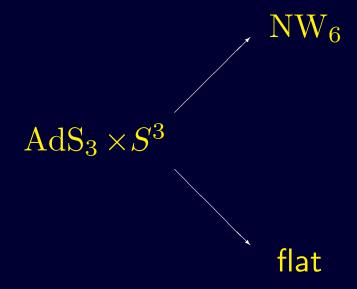
The first case corresponds to the flat vacuum. The second case corresponds to  $AdS_3 \times S^3$  with equal radii of curvature and

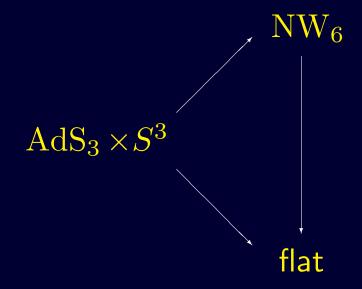
$$F \propto \operatorname{dvol}(AdS_3) + \operatorname{dvol}(S^3)$$

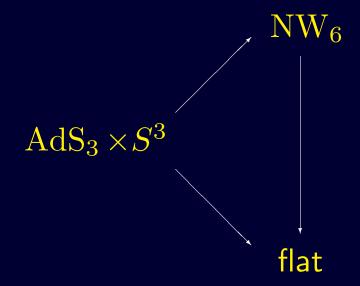
The third case is a six-dimensional version of the Nappi-Witten spacetime,  $NW_6$ , discovered by Meessen. [Meessen hep-th/0111031]

$$AdS_3 \times S^3$$









which in this case are group contractions à la Inönü-Wigner.

[Stanciu-FO hep-th/0303212, Olive-Rabinovici-Schwimmer hep-th/9311081]

[Back]

bosonic fields

- bosonic fields:
  - $\star$  metric g

- bosonic fields:
  - $\star$  metric g
  - $\star$  5 anti-selfdual closed 3-form  $F^i$

# $\overline{(2,0)}$ $\overline{D}=6$ supergravity

- bosonic fields:
  - $\star$  metric g
  - $\star$  5 anti-selfdual closed 3-form  $F^i$  transforming in the 5-dimensional representation of  $\mathrm{Sp}(2)\cong\mathrm{Spin}(5)$

- bosonic fields:
  - $\star$  metric g
  - $\star$  5 anti-selfdual closed 3-form  $F^i$  transforming in the 5-dimensional representation of  $\mathrm{Sp}(2)\cong\mathrm{Spin}(5)$

for a total of 9 + 15 = 24 physical bosonic degrees of freedom

# $\overline{(2,0)}$ D=6 supergravity

- bosonic fields:
  - $\star$  metric g
  - $\star$  5 anti-selfdual closed 3-form  $F^i$  transforming in the 5-dimensional representation of  $\mathrm{Sp}(2)\cong\mathrm{Spin}(5)$
  - for a total of 9 + 15 = 24 physical bosonic degrees of freedom
- spinors are positive-chirality symplectic Majorana-Weyl

- bosonic fields:
  - $\star$  metric g
  - $\star$  5 anti-selfdual closed 3-form  $F^i$  transforming in the 5-dimensional representation of  $\mathrm{Sp}(2)\cong\mathrm{Spin}(5)$
  - for a total of 9 + 15 = 24 physical bosonic degrees of freedom
- spinors are positive-chirality symplectic Majorana–Weyl; i.e., associated to the 16-dimensional real representation of  $Spin(1,5) \times Sp(2)$  having positive six-dimensional chirality.

### (2,0) D=6 supergravity

- bosonic fields:
  - $\star$  metric g
  - $\star$  5 anti-selfdual closed 3-form  $F^i$  transforming in the 5-dimensional representation of  $\mathrm{Sp}(2)\cong\mathrm{Spin}(5)$
  - for a total of 9 + 15 = 24 physical bosonic degrees of freedom
- spinors are positive-chirality symplectic Majorana–Weyl; i.e., associated to the 16-dimensional real representation of  $\mathrm{Spin}(1,5) \times \mathrm{Sp}(2)$  having positive six-dimensional chirality. The gravitino has therefore also 24 physical degrees of freedom.

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu\nu\rho}{}^{i} \gamma_{i} \Gamma^{\nu\rho}$$

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu\nu\rho}{}^{i} \gamma_{i} \Gamma^{\nu\rho}$$

Maximal supersymmetry  $\implies D$  is flat

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu\nu\rho}{}^{i} \gamma_{i} \Gamma^{\nu\rho}$$

Maximal supersymmetry  $\implies D$  is flat  $\implies$ 

$$\bullet \ F^i_{\mu\nu\rho} = F_{\mu\nu\rho}v^i$$

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu\nu\rho}{}^{i} \gamma_{i} \Gamma^{\nu\rho}$$

Maximal supersymmetry  $\Longrightarrow D$  is flat  $\Longrightarrow$ 

•  $F^i_{\mu\nu\rho}=F_{\mu\nu\rho}v^i$ , where F is an antiself-dual 3-form and v some constant unit vector

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu\nu\rho}{}^{i} \gamma_{i} \Gamma^{\nu\rho}$$

Maximal supersymmetry  $\Longrightarrow D$  is flat  $\Longrightarrow$ 

- $F^i_{\mu\nu\rho}=F_{\mu\nu\rho}v^i$ , where F is an antiself-dual 3-form and v some constant unit vector
- (g, F) is a vacuum solution of the (1, 0) theory

$$D_{\mu} = \nabla_{\mu} + \frac{1}{8} F_{\mu\nu\rho}{}^{i} \gamma_{i} \Gamma^{\nu\rho}$$

Maximal supersymmetry  $\implies D$  is flat  $\implies$ 

- $F^i_{\mu\nu\rho}=F_{\mu\nu\rho}v^i$ , where F is an antiself-dual 3-form and v some constant unit vector
- (g, F) is a vacuum solution of the (1, 0) theory
- $\implies (1,0)$  vacua  $\leftrightarrow (2,0)$  vacua up to  $\mathrm{Sp}(2)$  R-symmetry.

bosonic fields:

- bosonic fields:
  - $\star$  metric g

- bosonic fields:
  - $\star$  metric g,
  - ★ complex scalar

- bosonic fields:
  - $\star$  metric g,
  - $\star$  complex scalar  $\tau$ ,
  - $\star$  closed complex 3-form H

## $\overline{D} = 10$ IIB supergravity

- bosonic fields:
  - $\star$  metric g,
  - $\star$  complex scalar  $\tau$ ,
  - $\star$  closed complex 3-form H, and
  - $\star$  closed selfdual 5-form F

- bosonic fields:
  - $\star$  metric g,
  - $\star$  complex scalar  $\tau$ ,
  - $\star$  closed complex 3-form H, and
  - \* closed selfdual 5-form F
  - $\implies$  35 + 2 + 56 + 35 = 128 bosonic physical degrees of freedom

- bosonic fields:
  - $\star$  metric g,
  - $\star$  complex scalar  $\tau$ ,
  - $\star$  closed complex 3-form H, and
  - $\star$  closed selfdual 5-form F
  - $\implies$  35 + 2 + 56 + 35 = 128 bosonic physical degrees of freedom
- spinors are positive-chirality Majorana–Weyl spinors.
   There are two gravitini and two dilatini

- bosonic fields:
  - $\star$  metric g,
  - $\star$  complex scalar  $\tau$ ,
  - $\star$  closed complex 3-form H, and
  - $\star$  closed selfdual 5-form F
  - $\implies$  35 + 2 + 56 + 35 = 128 bosonic physical degrees of freedom
- spinors are positive-chirality Majorana-Weyl spinors.
  - There are two gravitini and two dilatini
  - $\implies 112 + 16 = 128$  fermionic physical degrees of freedom

• the dilatino variation gives rise to an algebraic Killing spinor equation

• the dilatino variation gives rise to an algebraic Killing spinor equation

Maximal supersymmetry  $\implies \tau$  is constant and H=0

- the dilatino variation gives rise to an algebraic Killing spinor equation
  - Maximal supersymmetry  $\implies \tau$  is constant and H=0
- the gravitino variation defines the connection

- the dilatino variation gives rise to an algebraic Killing spinor equation
  - Maximal supersymmetry  $\implies \tau$  is constant and H=0
- the gravitino variation defines the connection (with H=0 and au constant)

- the dilatino variation gives rise to an algebraic Killing spinor equation
  - Maximal supersymmetry  $\implies \tau$  is constant and H=0
- the gravitino variation defines the connection (with H=0 and au constant)

$$D_{\mu} = \nabla_{\mu} + i\alpha F_{\nu_1 \nu_2 \nu_3 \nu_4 \nu_5} \Gamma^{\nu_1 \nu_2 \nu_3 \nu_4 \nu_5} \Gamma_{\mu}$$

- the dilatino variation gives rise to an algebraic Killing spinor equation
  - Maximal supersymmetry  $\implies \tau$  is constant and H=0
- the gravitino variation defines the connection (with H=0 and au constant)

$$D_{\mu} = \nabla_{\mu} + i\alpha F_{\nu_1 \nu_2 \nu_3 \nu_4 \nu_5} \Gamma^{\nu_1 \nu_2 \nu_3 \nu_4 \nu_5} \Gamma_{\mu}$$

where we have written the two real spinors as a complex spinor

- the dilatino variation gives rise to an algebraic Killing spinor equation
  - Maximal supersymmetry  $\implies \tau$  is constant and H=0
- the gravitino variation defines the connection (with H=0 and au constant)

$$D_{\mu} = \nabla_{\mu} + i\alpha F_{\nu_1 \nu_2 \nu_3 \nu_4 \nu_5} \Gamma^{\nu_1 \nu_2 \nu_3 \nu_4 \nu_5} \Gamma_{\mu}$$

where we have written the two real spinors as a complex spinor, and  $\alpha$  depends on the constant value of  $\tau$ .

Expanding the curvature of D into antisymmetric products of  $\Gamma$ -matrices

F is parallel

• F is parallel:  $\nabla F = 0$ 

• F is parallel:  $\nabla F = 0$ 

• the Riemann curvature tensor is again determined  $\underbrace{algebraically}$  in terms of F and g

• F is parallel:  $\nabla F = 0$ 

• the Riemann curvature tensor is again determined *algebraically* in terms of F and g:

$$R_{\mu\nu\rho\sigma} = T_{\mu\nu\rho\sigma}(F,g)$$

with T quadratic in F

• F is parallel:  $\nabla F = 0$ 

• the Riemann curvature tensor is again determined *algebraically* in terms of F and g:

$$R_{\mu\nu\rho\sigma} = T_{\mu\nu\rho\sigma}(F,g)$$

with T quadratic in F. Again this means that  $R_{\mu\nu\rho\sigma}$  is parallel

• F is parallel:  $\nabla F = 0$ 

• the Riemann curvature tensor is again determined <u>algebraically</u> in terms of F and g:

$$R_{\mu\nu\rho\sigma} = T_{\mu\nu\rho\sigma}(F,g)$$

with T quadratic in F. Again this means that  $R_{\mu\nu\rho\sigma}$  is parallel, so that g is locally symmetric.

$$F_{\rho} \wedge F^{\rho} = 0$$

$$F_{\rho} \wedge F^{\rho} = 0 \qquad \text{or} \qquad F_{\mu_1 \mu_2 \mu_3 \rho [\nu_1} F^{\rho}{}_{\nu_2 \nu_3 \nu_4 \nu_5]} = 0$$

$$F_{\rho} \wedge F^{\rho} = 0 \qquad \text{or} \qquad F_{\mu_1 \mu_2 \mu_3 \rho [\nu_1} F^{\rho}{}_{\nu_2 \nu_3 \nu_4 \nu_5]} = 0$$

generalising both the Plücker relations

$$F_{\rho} \wedge F^{\rho} = 0 \qquad \text{or} \qquad F_{\mu_1 \mu_2 \mu_3 \rho [\nu_1} F^{\rho}{}_{\nu_2 \nu_3 \nu_4 \nu_5]} = 0$$

generalising both the Plücker relations and the Jacobi identity.

$$F_{\rho} \wedge F^{\rho} = 0$$
 or  $F_{\mu_1 \mu_2 \mu_3 \rho [\nu_1} F^{\rho}_{\nu_2 \nu_3 \nu_4 \nu_5]} = 0$ 

generalising both the Plücker relations and the Jacobi identity.

Again we can work in the tangent space at a point

$$F_{\rho} \wedge F^{\rho} = 0$$
 or  $F_{\mu_1 \mu_2 \mu_3 \rho [\nu_1} F^{\rho}_{\nu_2 \nu_3 \nu_4 \nu_5]} = 0$ 

generalising both the Plücker relations and the Jacobi identity.

Again we can work in the tangent space at a point, where g gives rise to a lorentzian innner product

$$F_{\rho} \wedge F^{\rho} = 0$$
 or  $F_{\mu_1 \mu_2 \mu_3 \rho [\nu_1} F^{\rho}_{\nu_2 \nu_3 \nu_4 \nu_5]} = 0$ 

generalising both the Plücker relations and the Jacobi identity.

Again we can work in the tangent space at a point, where g gives rise to a lorentzian innner product and F defines a self-dual 5-form obeying a quadratic equation.

$$F_{\rho} \wedge F^{\rho} = 0$$
 or  $F_{\mu_1 \mu_2 \mu_3 \rho [\nu_1} F^{\rho}_{\nu_2 \nu_3 \nu_4 \nu_5]} = 0$ 

generalising both the Plücker relations and the Jacobi identity.

Again we can work in the tangent space at a point, where g gives rise to a lorentzian innner product and F defines a self-dual 5-form obeying a quadratic equation.

This equation defines a generalisation of a Lie algebra known as a 4-Lie algebra (with an invariant metric). [Filippov (1985)]

$$F_{\rho} \wedge F^{\rho} = 0$$
 or  $F_{\mu_1 \mu_2 \mu_3 \rho [\nu_1} F^{\rho}_{\nu_2 \nu_3 \nu_4 \nu_5]} = 0$ 

generalising both the Plücker relations and the Jacobi identity.

Again we can work in the tangent space at a point, where g gives rise to a lorentzian innner product and F defines a self-dual 5-form obeying a quadratic equation.

This equation defines a generalisation of a Lie algebra known as a 4-Lie algebra (with an invariant metric). [Filippov (1985)]

(Unfortunate notation: a 2-Lie algebra is a Lie algebra.)

A Lie algebra is a vector space g

A Lie algebra is a vector space **g** together with an antisymmetric bilinear map

$$[\quad]:\Lambda^2\mathfrak{g} o\mathfrak{g}$$

A Lie algebra is a vector space g together with an antisymmetric bilinear map

$$[\phantom{a}]:\Lambda^2\mathfrak{g} o\mathfrak{g}$$

satisfying the condition

A Lie algebra is a vector space g together with an antisymmetric bilinear map

$$\lceil \ \ 
ceil : \Lambda^2 \mathfrak{g} o \mathfrak{g}$$

satisfying the condition: for all  $X \in \mathfrak{g}$  the map

$$\operatorname{ad}_X:\mathfrak{g}\to\mathfrak{g}$$
 defined by  $\operatorname{ad}_XY=[X,Y]$ 

A Lie algebra is a vector space g together with an antisymmetric bilinear map

$$\lceil \ \ ]:\Lambda^2\mathfrak{g} o\mathfrak{g}$$

satisfying the condition: for all  $X \in \mathfrak{g}$  the map

$$\operatorname{ad}_X:\mathfrak{g}\to\mathfrak{g}$$
 defined by  $\operatorname{ad}_XY=[X,Y]$ 

is a derivation over []

A Lie algebra is a vector space g together with an antisymmetric bilinear map

$$[\quad]:\Lambda^2\mathfrak{g} o\mathfrak{g}$$

satisfying the condition: for all  $X \in \mathfrak{g}$  the map

$$\operatorname{ad}_X:\mathfrak{g}\to\mathfrak{g}$$
 defined by  $\operatorname{ad}_XY=[X,Y]$ 

is a derivation over []; that is,

$$[X, [Y, Z]] = [[X, Y], Z] + [Y, [X, Z]]$$

## An *n-Lie algebra*

An n-Lie algebra is a vector space  $\mathbf{n}$ 

$$[\quad]:\Lambda^n\mathfrak{n} o\mathfrak{n}$$

$$[\quad]:\Lambda^n\mathfrak{n} o\mathfrak{n}$$

satisfying the condition

$$[\quad]:\Lambda^n\mathfrak{n} o\mathfrak{n}$$

satisfying the condition: for all  $X_1, \ldots, X_{n-1} \in \mathfrak{n}$ 

$$[\quad]:\Lambda^n\mathfrak{n} o\mathfrak{n}$$

satisfying the condition: for all  $X_1, \ldots, X_{n-1} \in \mathfrak{n}$ , the map

$$\operatorname{ad}_{X_1,...,X_{n-1}}:\mathfrak{n}\to\mathfrak{n}$$

$$[\quad]:\Lambda^n\mathfrak{n} \to \mathfrak{n}$$

satisfying the condition: for all  $X_1, \ldots, X_{n-1} \in \mathfrak{n}$ , the map

$$\operatorname{ad}_{X_1,...,X_{n-1}}:\mathfrak{n}\to\mathfrak{n}$$

defined by

$$\operatorname{ad}_{X_1,...,X_{n-1}} Y = [X_1,...,X_{n-1},Y]$$

is a derivation over []

is a derivation over []; that is,

$$[X_1, \dots, X_{n-1}, [Y_1, \dots, Y_n]] = \sum_{i=1}^n [Y_1, \dots, [X_1, \dots, X_{n-1}, Y_i], \dots, Y_n]$$

is a derivation over []; that is,

$$[X_1, \dots, X_{n-1}, [Y_1, \dots, Y_n]] = \sum_{i=1}^n [Y_1, \dots, [X_1, \dots, X_{n-1}, Y_i], \dots, Y_n]$$

If  $\langle -, - \rangle$  is a metric on  $\mathfrak{n}$ , we can define F by

$$F(X_1, \dots, X_{n+1}) = \langle [X_1, \dots, X_n], X_{n+1} \rangle$$

<u>is a derivation over</u> ; that is,

$$[X_1, \dots, X_{n-1}, [Y_1, \dots, Y_n]] = \sum_{i=1}^n [Y_1, \dots, [X_1, \dots, X_{n-1}, Y_i], \dots, Y_n]$$

If  $\langle -, - \rangle$  is a metric on  $\mathfrak{n}$ , we can define F by

$$F(X_1, \dots, X_{n+1}) = \langle [X_1, \dots, X_n], X_{n+1} \rangle$$

If F is totally antisymmetric then  $\langle -, - \rangle$  is an invariant metric.

is a derivation over []; that is,

$$[X_1, \dots, X_{n-1}, [Y_1, \dots, Y_n]] = \sum_{i=1}^n [Y_1, \dots, [X_1, \dots, X_{n-1}, Y_i], \dots, Y_n]$$

If  $\langle -, - \rangle$  is a metric on  $\mathfrak{n}$ , we can define F by

$$F(X_1, \dots, X_{n+1}) = \langle [X_1, \dots, X_n], X_{n+1} \rangle$$

If F is totally antisymmetric then  $\langle -, - \rangle$  is an *invariant metric*.

(n-Lie algebras also appear naturally in the context of Nambu dynamics. [Nambu (1973)])

In this language, IIB vacua are in one-to-one correspondence with ten-dimensional *selfdual lorentzian* 4-Lie algebras

In this language, IIB vacua are in one-to-one correspondence with ten-dimensional *selfdual lorentzian* 4-Lie *algebras*; but this is not particularly helpful since the theory of n-Lie algebras is still largely undeveloped.

In this language, IIB vacua are in one-to-one correspondence with ten-dimensional *selfdual lorentzian* 4-Lie *algebras*; but this is not particularly helpful since the theory of n-Lie algebras is still largely undeveloped.

One is forced to solve the equations.

In this language, IIB vacua are in one-to-one correspondence with ten-dimensional *selfdual lorentzian* 4-Lie *algebras*; but this is not particularly helpful since the theory of n-Lie algebras is still largely undeveloped.

One is forced to solve the equations. After A LOT of work, we found that a selfdual 5-form obeys the equation if and only if

In this language, IIB vacua are in one-to-one correspondence with ten-dimensional *selfdual lorentzian* 4-Lie *algebras*; but this is not particularly helpful since the theory of n-Lie algebras is still largely undeveloped.

One is forced to solve the equations. After A LOT of work, we found that a selfdual 5-form obeys the equation if and only if

$$F = G + \star G$$

In this language, IIB vacua are in one-to-one correspondence with ten-dimensional *selfdual lorentzian* 4-Lie *algebras*; but this is not particularly helpful since the theory of n-Lie algebras is still largely undeveloped.

One is forced to solve the equations. After A LOT of work, we found that a selfdual 5-form obeys the equation if and only if

$$F = G + \star G$$
 where  $G = \theta^1 \wedge \theta^2 \wedge \theta^3 \wedge \theta^4 \wedge \theta^5$ 

In this language, IIB vacua are in one-to-one correspondence with ten-dimensional *selfdual lorentzian* 4-Lie *algebras*; but this is not particularly helpful since the theory of n-Lie algebras is still largely undeveloped.

One is forced to solve the equations. After A LOT of work, we found that a selfdual 5-form obeys the equation if and only if

$$F = G + \star G$$
 where  $G = \theta^1 \wedge \theta^2 \wedge \theta^3 \wedge \theta^4 \wedge \theta^5$ 

[FO-Papadopoulos math.AG/0211170]

## *G* is decomposable;

G is decomposable; whence, if nonzero

G is decomposable; whence, if nonzero, it defines a 5-plane

G is decomposable; whence, if nonzero, it defines a 5-plane, and hence F defines two orthogonal planes.

G is decomposable; whence, if nonzero, it defines a 5-plane, and hence F defines two orthogonal planes.

If F = 0 we recover the flat vacuum.

If F = 0 we recover the flat vacuum. Otherwise there are two possibilities:

If F = 0 we recover the flat vacuum. Otherwise there are two possibilities:

• one plane is lorentzian and the other euclidean

If F=0 we recover the flat vacuum. Otherwise there are two possibilities:

• one plane is lorentzian and the other euclidean: we can choose a pseudo-orthonormal frame in which the only nonzero components of F are  $F_{01234}=F_{56789}$ 

If F=0 we recover the flat vacuum. Otherwise there are two possibilities:

- one plane is lorentzian and the other euclidean: we can choose a pseudo-orthonormal frame in which the only nonzero components of F are  $F_{01234}=F_{56789}$ , or
- both planes are null

If F = 0 we recover the flat vacuum. Otherwise there are two possibilities:

- one plane is lorentzian and the other euclidean: we can choose a pseudo-orthonormal frame in which the only nonzero components of F are  $F_{01234}=F_{56789}$ , or
- both planes are null: we can choose a pseudo-orthonormal frame in which the only nonzero components of F are  $F_{-1234} = F_{-5678}$ .

Plugging these expressions back into the relation between the curvature tensor to  $\emph{\emph{F}}$  and  $\emph{\emph{g}}$ 

F non-degenerate case

• F non-degenerate case: a one-parameter (R > 0) family of vacua

$$AdS_5(-R) \times S^5(R)$$
  $F = \sqrt{\frac{4R}{5}} \left( dvol(AdS_5) - dvol(S^5) \right)$ 

• F non-degenerate case: a one-parameter (R > 0) family of vacua

$$AdS_5(-R) \times S^5(R)$$
  $F = \sqrt{\frac{4R}{5}} \left( dvol(AdS_5) - dvol(S^5) \right)$ 

ullet F degenerate

• F non-degenerate case: a one-parameter (R > 0) family of vacua

$$AdS_5(-R) \times S^5(R)$$
  $F = \sqrt{\frac{4R}{5}} \left( dvol(AdS_5) - dvol(S^5) \right)$ 

ullet F degenerate: a one-parameter  $(\mu \in \mathbb{R})$  family of symmetric

$$g = 2dx^{+}dx^{-} - \frac{1}{4}\mu^{2} \sum_{i=1}^{8} (x^{i})^{2} (dx^{-})^{2} + \sum_{i=1}^{8} (dx^{i})^{2}$$

$$g = 2dx^{+}dx^{-} - \frac{1}{4}\mu^{2} \sum_{i=1}^{8} (x^{i})^{2} (dx^{-})^{2} + \sum_{i=1}^{8} (dx^{i})^{2}$$
$$F = \frac{1}{2}\mu dx^{-} \wedge (dx^{1} \wedge dx^{2} \wedge dx^{3} \wedge dx^{4} + dx^{5} \wedge dx^{6} \wedge dx^{7} \wedge dx^{8})$$

$$g = 2dx^{+}dx^{-} - \frac{1}{4}\mu^{2} \sum_{i=1}^{8} (x^{i})^{2} (dx^{-})^{2} + \sum_{i=1}^{8} (dx^{i})^{2}$$
$$F = \frac{1}{2}\mu dx^{-} \wedge (dx^{1} \wedge dx^{2} \wedge dx^{3} \wedge dx^{4} + dx^{5} \wedge dx^{6} \wedge dx^{7} \wedge dx^{8})$$

Again for  $\mu = 0$  we recover the flat space solution

$$g = 2dx^{+}dx^{-} - \frac{1}{4}\mu^{2} \sum_{i=1}^{8} (x^{i})^{2} (dx^{-})^{2} + \sum_{i=1}^{8} (dx^{i})^{2}$$
$$F = \frac{1}{2}\mu dx^{-} \wedge (dx^{1} \wedge dx^{2} \wedge dx^{3} \wedge dx^{4} + dx^{5} \wedge dx^{6} \wedge dx^{7} \wedge dx^{8})$$

Again for  $\mu = 0$  we recover the flat space solution; whereas for  $\mu \neq 0$  all solutions are isometric to the same plane wave

[Blau-FO-Hull-Papadopoulos hep-th/0110242]

$$g = 2dx^{+}dx^{-} - \frac{1}{4}\mu^{2} \sum_{i=1}^{8} (x^{i})^{2} (dx^{-})^{2} + \sum_{i=1}^{8} (dx^{i})^{2}$$
$$F = \frac{1}{2}\mu dx^{-} \wedge (dx^{1} \wedge dx^{2} \wedge dx^{3} \wedge dx^{4} + dx^{5} \wedge dx^{6} \wedge dx^{7} \wedge dx^{8})$$

Again for  $\mu = 0$  we recover the flat space solution; whereas for  $\mu \neq 0$  all solutions are isometric to the same plane wave

[Blau-FO-Hull-Papadopoulos hep-th/0110242]

Notice that g is a bi-invariant metric on a Lie group

$$g = 2dx^{+}dx^{-} - \frac{1}{4}\mu^{2} \sum_{i=1}^{8} (x^{i})^{2} (dx^{-})^{2} + \sum_{i=1}^{8} (dx^{i})^{2}$$
$$F = \frac{1}{2}\mu dx^{-} \wedge (dx^{1} \wedge dx^{2} \wedge dx^{3} \wedge dx^{4} + dx^{5} \wedge dx^{6} \wedge dx^{7} \wedge dx^{8})$$

Again for  $\mu=0$  we recover the flat space solution; whereas for  $\mu\neq 0$  all solutions are isometric to the same plane wave

[Blau-FO-Hull-Papadopoulos hep-th/0110242]

Notice that g is a bi-invariant metric on a Lie group: a ten-dimensional version of the Nappi-Witten spacetime.

[Stanciu-FO hep-th/0303212]

These vacua again embed isometrically in  $\mathbb{E}^{2,10}$  as intersections of quadrics

[Blau-FO-Hull-Papadopoulos hep-th/0201081]

[Berenstein-Maldacena-Nastase hep-th/0202021]

$$AdS_5 \times S^5$$

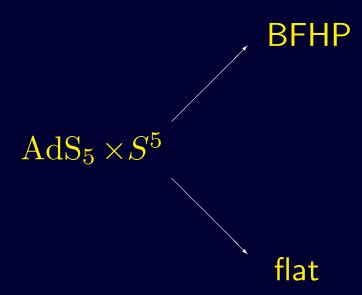
[Blau-FO-Hull-Papadopoulos hep-th/0201081]

[Berenstein-Maldacena-Nastase hep-th/0202021]



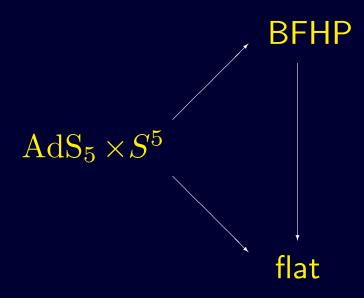
[Blau-FO-Hull-Papadopoulos hep-th/0201081]

[Berenstein-Maldacena-Nastase hep-th/0202021]



[Blau-FO-Hull-Papadopoulos hep-th/0201081]

[Berenstein-Maldacena-Nastase hep-th/0202021]



[Back]

• D=10: I, heterotic, IIA

• D=10: I, heterotic, IIA only have the flat vacuum.

• D=10: I, heterotic, IIA only have the flat vacuum. The same is true for any theory lower in the corresponding columns.

• D=10: I, heterotic, IIA only have the flat vacuum. The same is true for any theory lower in the corresponding columns. (Roman's massive supergravity has not vacua at all.)

- D=10: I, heterotic, IIA only have the flat vacuum. The same is true for any theory lower in the corresponding columns. (Roman's massive supergravity has not vacua at all.)
- D=6: (1,0) vacua do have reductions preserving all supersymmetry.

[Gauntlett-Gutowsky-Hull-Pakis-Reall hep-th/0209114] [Lozano-Tellechea-Meessen-Ortín hep-th/0206200]

- D=10: I, heterotic, IIA only have the flat vacuum. The same is true for any theory lower in the corresponding columns. (Roman's massive supergravity has not vacua at all.)
- D=6: (1,0) vacua do have reductions preserving all supersymmetry.

[Gauntlett-Gutowsky-Hull-Pakis-Reall hep-th/0209114] [Lozano-Tellechea-Meessen-Ortín hep-th/0206200]

This now has a natural explanation.

$$D{=}5\ N{=}2\ {\bf from}\ D{=}6\ (1,0)$$

$$D{=}5\ N{=}2\ {\sf from}\ D{=}6\ (1,0)$$

 $D=6 \ (1,0) \leadsto D=5 \ N=2$  coupled to a vector multiplet

$$D{=}5\ N{=}2\ {\sf from}\ D{=}6\ (1,0)$$

$$(g,F_3) \leadsto (h,\phi,F_2,G_2)$$

$$D{=}5\ N{=}2\ {\sf from}\ D{=}6\ (1,0)$$

$$(g,F_3) \leadsto (h,\phi,F_2,G_2)$$

Minimal D=5 N=2 requires a truncation

$$D{=}5\ N{=}2\ {\sf from}\ D{=}6\ (1,0)$$

$$(g,F_3) \leadsto (h,\phi,F_2,G_2)$$

Minimal D=5 N=2 requires a truncation

$$d\phi = 0 \qquad F_2 = G_2$$

$$D{=}5\ N{=}2\ {\sf from}\ D{=}6\ (1,0)$$

$$(g,F_3) \leadsto (h,\phi,F_2,G_2)$$

Minimal D=5 N=2 requires a truncation

$$d\phi = 0 \qquad F_2 = G_2$$

Let (M, g, F) be a vacuum solution of D=6 (1, 0)

$$D{=}5\ N{=}2\ {\sf from}\ D{=}6\ (1,0)$$

D=6 (1,0)  $\rightsquigarrow D=5$  N=2 coupled to a vector multiplet:

$$(g,F_3) \leadsto (h,\phi,F_2,G_2)$$

Minimal D=5 N=2 requires a truncation

$$d\phi = 0$$
  $F_2 = G_2$ 

Let (M, g, F) be a vacuum solution of D=6 (1,0): (M,g) a parallelised (anti-selfdual, lorentzian) Lie group with torsion F.

Let  $\xi$  be a (spacelike) left-invariant vector field

• Kaluza–Klein reduction yields space M/K of right K-cosets

- Kaluza–Klein reduction yields space M/K of right K-cosets
- $\xi$  leaves invariant all Killing spinors

- Kaluza–Klein reduction yields space M/K of right K-cosets
- $\xi$  leaves invariant all Killing spinors
- truncation is automatic

- Kaluza–Klein reduction yields space M/K of right K-cosets
- $\xi$  leaves invariant all Killing spinors
- truncation is automatic
- all vacua of minimal D=5 N=2 supergravity arise in this way:

- Kaluza–Klein reduction yields space M/K of right K-cosets
- $\xi$  leaves invariant all Killing spinors
- truncation is automatic
- all vacua of minimal D=5 N=2 supergravity arise in this way:  $AdS_2 \times S^3 \leftrightarrow AdS_3 \times S^2$

- Kaluza–Klein reduction yields space M/K of right K-cosets
- $\xi$  leaves invariant all Killing spinors
- truncation is automatic
- all vacua of minimal D=5 N=2 supergravity arise in this way:  $AdS_2 \times S^3 \leftrightarrow AdS_3 \times S^2$ ,  $\mathbb{E}^{1,4}$

- Kaluza–Klein reduction yields space M/K of right K-cosets
- $\xi$  leaves invariant all Killing spinors
- truncation is automatic
- all vacua of minimal D=5 N=2 supergravity arise in this way:  $AdS_2 \times S^3 \leftrightarrow AdS_3 \times S^2$ ,  $\mathbb{E}^{1,4}$ ,  $KG_5$

- Kaluza–Klein reduction yields space M/K of right K-cosets
- $\xi$  leaves invariant all Killing spinors
- truncation is automatic
- all vacua of minimal D=5 N=2 supergravity arise in this way:  $AdS_2 \times S^3 \leftrightarrow AdS_3 \times S^2$ ,  $\mathbb{E}^{1,4}$ ,  $KG_5$ , Gödel

- Kaluza–Klein reduction yields space M/K of right K-cosets
- $\xi$  leaves invariant all Killing spinors
- truncation is automatic
- all vacua of minimal D=5 N=2 supergravity arise in this way:  $AdS_2 \times S^3 \leftrightarrow AdS_3 \times S^2$ ,  $\mathbb{E}^{1,4}$ ,  $KG_5$ , Gödel, ...

Thank you.