

h-principles supplement  
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"almost symplectic": non-deg  
2-forms

Thm:  $\mathcal{L}_{\text{symp}}(V) \xrightarrow{\sim} \mathcal{S}_{\text{symp}}^a(V) \xrightarrow{\sim} \mathcal{I}_{\text{symp}}(V)$

is a homotopy equivalence if  $V$  open.

h-principles for partial differential relations on open mfd's

$V$  open,  $X$  natural fibre bundle. Then any open

Diff  $V$ -invariant differential relation  $R \subset X^{(n)}$

(E.g. Laplace's equation  $\sum_i \partial_i^2 f = 0$  for  $f: \mathbb{R}^n \rightarrow \mathbb{R}$ )

$\Rightarrow X = \mathbb{R}^{n+1}$ ,  $V = \mathbb{R}^n$

$X^{(2)}$  has coords  $X_i, y, z_i, W_{ij}$   
 $\begin{matrix} & \uparrow & \uparrow & \uparrow & \uparrow \\ V & f & \frac{\partial f}{\partial x_i} & \frac{\partial^2 f}{\partial x_i \partial x_j} & \frac{\partial^3 f}{\partial x_i \partial x_j \partial x_k} \end{matrix}$

although this is not Diff  $V$ -invariant and not open -  
just an example of a PDE.

A PDR might be  $\sum_i \partial_i^2 f > 0$

satisfies a parametric h-principle. Relative h-princ.  
also holds for  $B \subset V$  closed st. every component  
of  $V \setminus B$  has an exit to  $\infty$ .

What does "satisfies a parametric h-principle" mean?

smooth

(V) Given a section  $S: V \rightarrow X$ , we obtain a section  $J_S^r: V \rightarrow X^{(r)}$ . These sections of  $X^{(r)}$  are called holonomic.

A "formal solution" of our PDR is a section of  $X^{(r)}$  satisfying the PDR.

"satisfies an h-principle" means any formal solution can be deformed to a holonomic solution, i.e., without changing holonomic solutions (i.e., holonomic solutions  $\xrightarrow{\text{h.e.}}$  formal solutions).

A "relative h-principle" means you start with a formal solution which is holonomic on a nbhd of  $B \subseteq V$ , and can deform to a holonomic solution without changing the solution on some (possibly smaller) nbhd of  $B$ .

Pf of thm: We will see that every  $\omega \in \mathcal{I}_{\text{symp}}$  can be deformed in  $\mathcal{I}_{\text{symp}}$  to  $\tilde{\omega} \in \mathcal{S}_{\text{symp}}^a$   $\forall a \in H^2(V)$ .

Assume  $a=0$  (why?)

We have

$$\Lambda^1 V \xrightarrow{J^1} (\Lambda^1 V)^{(1)} \rightarrow \Lambda^2 V$$

Diagram showing a map from  $\Lambda^1 V$  to  $\Lambda^2 V$  via  $(\Lambda^1 V)^{(1)}$ .

global sec.

Now note: any 2-form  $\omega \in \mathcal{I}_{\text{symp}}$   $\leadsto F_\omega \in \Gamma((\Lambda^1 V)^{(1)})$

can we find a global section  $F_\omega$  s.t.  $\tilde{D} F_\omega = \omega$

"formal primitive" of  $\omega$ .

Let  $V \otimes V \xrightarrow{W} T^*V \xrightarrow{\tilde{D}} T^*V$

The non-degeneracy condition in  $\Omega^2(V)$  gives an open PDR on  $(\Lambda^1 V)^{(1)}$ .

The h-principle gives  $F_t \in \text{Sec}(\Lambda^1 V)^{(1)}$  s.t.  $F_1 = F_\omega$

with  $\frac{1}{2} \langle V, V \rangle$  symplectic is  $WT \xrightarrow{\tilde{D}} VT$   $F_0 = J_\alpha^1$  for some  $\alpha \in \Omega^1 V$

Take  $\omega_t = \tilde{D} \circ F_t$

$\Rightarrow \omega_0 = \tilde{D} \circ J_\alpha^1 = d\alpha$

$\omega_1 = \omega$

This gives you your deformation.

Thm:  $\mathcal{S}_{\text{cont}}^+ \hookrightarrow \mathcal{I}_{\text{cont}}^+$  is h.e. for  $V$  open

$\uparrow$   
cont. str. in  $V$

co-oriented

$\uparrow$   
 $\{(\xi, \omega)\}$

co-oriented hyperplane distribution

in  $TV$  positive conformal symplectic str. in  $\xi$

(need conf. symplectic struc. given by  $d\alpha$  to be cont.)

Rmk: For closed manifolds, almost everything is unknown.

Thm:  $V^n, (W^{2n}, \omega)$ . All forms of h-principle hold for

Lagrangian immersions  $f: V^n \rightarrow W^{2n}$  if we

include the condition  $[f^* \omega] = 0 \in H^2(V)$ .

see today

What is a "formal Lagrangian immersion"?

In particular, every isotropic monomorphism

$$TV \longrightarrow TW \quad (\text{i.e. map } V \xrightarrow{i} W \text{ with "maps"} \\ T_x V \rightarrow T_x W \quad \forall x \in V, \text{ which are isotropic})$$

can be deformed to a Lagrangian immersion  
 $V \rightarrow W$ .

Cor: If  $TV \rightarrow TW$  is isotropic,  $\dim V < \frac{1}{2} \dim W$ ,  
 you can deform to an isotropic embedding.