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John Milnor

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A DUALITY THEOREM FOR REIDEMEISTER TORSION

BY JOHN MILNOR

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This paper will show that the torsion invariant of Reidemeister, Franz, and de Rham for a manifold satisfies a duality relation, analogous to Poincaré duality. As an application one obtains a new proof that the Alexander polynomial of a knot is symmetric (a result first proved by Seifert [11]).

1. The duality theorem

First some algebraic preliminaries. Let P be a ring with an anti-automorphism $\rho \rightarrow \bar{\rho}$ of period two. Given any left P -module A define the dual module A^* to be $\text{Hom}_P(A, P)$, considered as a left P -module in the following way. For each $\rho \in P$ and $f: A \rightarrow P$ define $\rho f: A \rightarrow P$ by the formula

$$[a, \rho f] = [a, f] \bar{\rho},$$

where $[a, f]$ denotes the value of the function f at a . If A is free and finitely generated, then clearly A^* is free and finitely generated, and A^{**} can be identified with A . Note that any homomorphism $h: A_1 \rightarrow A_2$ gives rise to a dual homomorphism $h^*: A_2^* \rightarrow A_1^*$.

As an example consider the following geometrical situation. Let M be a simplicial complex whose underlying space is an oriented n -manifold without boundary. Let Π be a group of fixed point free simplicial automorphisms of M . Then the chain group $C_q(M; Z)$ can be considered as a free left module over the integral group ring $Z[\Pi]$.

Now suppose that M has a dual cell subdivision M' . Then the chain group $C_{n-q}(M'; Z)$ is also a free left $Z[\Pi]$ -module. We will assume that the quotient space M/Π is compact, so that these modules are finitely generated.

There is a canonical anti-automorphism $\rho \rightarrow \bar{\rho}$ of $Z[\Pi]$ which takes each group element π into π^{-1} .

LEMMA 1 (Reidemeister). *If the elements of Π are orientation preserving automorphisms of M , then the $Z[\Pi]$ -module $C_{n-q}(M'; Z)$ is canonically isomorphic to the dual of $C_q(M; Z)$. Furthermore the boundary homomorphism*

$$\partial: C_{n-q}(M'; Z) \longrightarrow C_{n-q-1}(M'; Z)$$

is (up to sign) dual to the corresponding homomorphism

$$\partial: C_{q+1}(M; Z) \longrightarrow C_q(M; Z) .$$

PROOF. For each chain $c' \in C_{n-q}(M'; Z)$ define a homomorphism

$$[\ , c']: C_q(M; Z) \longrightarrow Z[\Pi]$$

by the formula

$$[c, c'] = \sum_{\pi \in \Pi} \langle c, \pi c' \rangle \pi ;$$

where $\langle c, \pi c' \rangle$ denotes the (integer) intersection number of c and $\pi c'$. The required identities

$$\begin{aligned} [\pi c, c'] &= \pi [c, c'] , \\ [c, \pi c'] &= [c, c'] \bar{\pi} , \end{aligned}$$

and

$$[\partial c, c'] = \pm [c, \partial c']$$

are easily verified. (Compare Reidemeister [9], Burger [2], Blanchfield [1].) This proves Lemma 1.

Now let us apply this duality to the torsion invariant. Given a commutative field F and a homomorphism

$$h: Z[\Pi] \longrightarrow F ,$$

we can consider F as a right $Z[\Pi]$ -module and hence form the vector spaces

$$C_q = F \otimes_{\Pi} C_q(M; Z) , \quad C'_{n-q} = F \otimes_{\Pi} C_{n-q}(M'; Z)$$

over F .

Assume that we are given an involution $a \rightarrow \bar{a}$ of F which satisfies the identity $h(\bar{a}) = \bar{h}(a)$. Then the vector space C'_{n-q} is canonically isomorphic to the dual of C_q .

If the chain complex C_* is acyclic—i.e., if the sequence

$$0 \longrightarrow C_n \longrightarrow C_{n-1} \longrightarrow \cdots \longrightarrow C_0 \longrightarrow 0$$

is exact—then the torsion invariant

$$\Delta_h M \in F_0 / \pm h(\Pi)$$

is defined. (See Franz [6] or de Rham [10]. The definition as given in Milnor [7] will be repeated below.) Here F_0 denotes the multiplicative group $F - 0$ and $\pm h(\Pi)$ denotes the subgroup consisting of all elements $\pm h(\pi)$, $\pi \in \Pi$.

THEOREM 1. *This torsion invariant $\Delta = \Delta_h M$ satisfies the identity*

$$\Delta \bar{\Delta}^{g(n)} = \pm h(\Pi)$$

where $\varepsilon(n) = (-1)^n$.

Thus if n is odd the torsion invariant is self-conjugate:

$$\bar{\Delta}_n M = \Delta_n M,$$

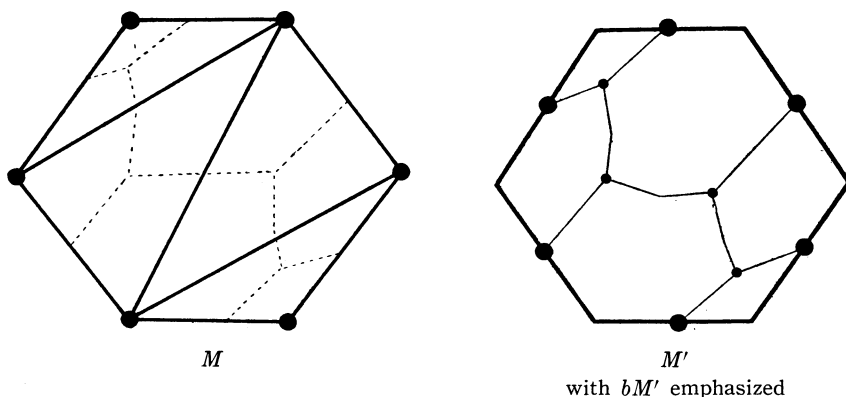
and if n is even the torsion is unitary:

$$\bar{\Delta}_n M = (\Delta_n M)^{-1}.$$

The classical illustration of torsion is provided by the (odd dimensional) lens manifolds. (See [6], [10].) One uses the field of complex numbers, and the usual complex conjugation operation. Hence Theorem 1 asserts that the resulting torsion element is essentially a real number.

For an even dimensional manifold, with F the field of complex numbers, the torsion must be a number on the unit circle defined up to multiplication by certain roots of unity. I do not know any non-trivial examples.

Before proving Theorem 1, it is convenient to consider the more general case of a triangulated n -manifold M with boundary bM . Again we assume that each simplex of M has a dual cell. For a q -simplex of bM one can define not only the dual $(n - q)$ -cell in M , but also the dual $(n - q - 1)$ -cell in bM . Taking the cells of both types we obtain a dual complex M' with subcomplex bM' .



Again assume that Π acts freely, preserving orientation, and that M/Π is compact.

LEMMA 2. *The left $Z[\Pi]$ -module $C_{n-q}(M', bM'; Z)$ is dual to $C_q(M; Z)$; and the boundary operator in $C_*(M', bM'; Z)$ is (up to sign) dual to the boundary operator in $C_*(M; Z)$.*

The proof is straightforward.

Again let $h: Z[\Pi] \rightarrow F$ be a homomorphism compatible with the conjugation operations.

THEOREM 1'. *If the torsion $\Delta_h M$ is defined (i.e., if the chain complex $F \otimes_{\Pi} C_*(M; Z)$ is acyclic) then $\Delta_h(M, bM)$ is defined, and conversely. Furthermore*

$$\Delta_h(M, bM) = (\bar{\Delta}_h M)^{-\varepsilon(n)}$$

where $\varepsilon(n) = (-1)^n$.

Clearly this result contains Theorem 1 as a special case. The following reformulation is usually more convenient to use. According to [7, Lemma 4], if both $\Delta_h M$ and $\Delta_h(M, bM)$ are defined, then $\Delta_h(bM)$ is also defined, and

$$\Delta_h(M, bM) = \Delta_h M / \Delta_h(bM).$$

Combining this information with Theorem 1', one obtains:

THEOREM 2. *If $\Delta_h M$ is defined then $\Delta_h(bM)$ is also defined, and*

$$\Delta_h(bM) = (\Delta_h M)(\bar{\Delta}_h M)^{\varepsilon(n)}.$$

Examples will be given in § 2.

In order to prove Theorems 1 and 1' it is first necessary to review the definition of torsion, as given in [7]. For any vector space C of dimension d over F , let ΛC denote the d^{th} exterior power $\Lambda^d C$. This is a one-dimensional vector space.

Given a short exact sequence

$$0 \longrightarrow A \longrightarrow B \longrightarrow C \longrightarrow 0,$$

and given generators $a \in \Lambda A$, $b \in \Lambda B$, construct a generator $b/a \in \Lambda C$ as follows. Choose a basis x_1, \dots, x_n for B so that the last $n - m$ vectors x_{m+1}, \dots, x_n form a basis for the subspace $A \subset B$. Thus a and b can be written in the form

$$a = f x_{m+1} \wedge \dots \wedge x_n, \quad b = g x_1 \wedge \dots \wedge x_n$$

for appropriate field elements $f, g \neq 0$. Define b/a to be the image in ΛC of

$$g f^{-1} x_1 \wedge \dots \wedge x_m.$$

This construction does not depend on the choice of basis.

Now suppose that one is given a long exact sequence

$$0 \longrightarrow C_n \longrightarrow C_{n-1} \longrightarrow \dots \longrightarrow C_0 \longrightarrow 0$$

and a preferred generator $v_q \in \Lambda C_q$ for each q . Using the short exact sequence

$$0 \longrightarrow C_n \longrightarrow C_{n-1} \longrightarrow \partial C_{n-1} \longrightarrow 0,$$

one constructs a generator

$$v_{n-1}/v_n \in \Lambda(\partial C_{n-1}) .$$

Proceeding inductively, using the sequences

$$0 \longrightarrow \partial C_{q+1} \longrightarrow C_q \longrightarrow \partial C_q \longrightarrow 0 ,$$

one constructs generators

$$v_q/(v_{q+1}/(\cdots/(v_{n-1}/v_n)\cdots)) \in \Lambda(\partial C_q)$$

for each q . These will be written briefly as $(v_q/v_{q+1}/\cdots/v_{n-1}/v_n)$.

In particular one obtains a generator

$$(v_1/v_2/\cdots/v_{n-1}/v_n) \in \Lambda(\partial C_1) = \Lambda C_0 .$$

Taking the ratio of this with the given generator $v_0 \in \Lambda C_0$ we obtain a field element

$$D = v_0/(v_1/v_2/\cdots/v_n) .$$

This ratio $D \in F_0$ is called the *torsion*¹ associated with $\{C_q, v_q\}$.

Note the identity

$$(1) \quad (v_1/v_2/\cdots/v_n) = D^{-1}v_0 .$$

Now let us apply duality to this situation. For any vector space C , note that $\Lambda(C^*)$ is canonically isomorphic to the dual $(\Lambda C)^*$ of ΛC . In fact given elements

$$v = x_1 \wedge \cdots \wedge x_n \in \Lambda C , \quad w = y_1 \wedge \cdots \wedge y_n \in \Lambda(C^*) ,$$

define $[v, w]$ to be the determinant of the matrix $\| [x_i, y_j] \|$. As an example, if x_1, \dots, x_n is a basis for C and x_1^*, \dots, x_n^* is the dual basis for C^* then $[x_1 \wedge \cdots \wedge x_n, x_1^* \wedge \cdots \wedge x_n^*] = 1$.

Consider a short exact sequence

$$0 \longrightarrow A \longrightarrow B \longrightarrow C \longrightarrow 0$$

together with the dual sequence

$$0 \longleftarrow A^* \longleftarrow B^* \longleftarrow C^* \longleftarrow 0 .$$

Let $a \in \Lambda A, b \in \Lambda B, b^* \in \Lambda B^*$, and $c^* \in \Lambda C^*$ be generators; with $[b, b^*] = 1$.

LEMMA 3. *Then $[b/a, c^*]$ is equal to $\pm[a, b^*/c^*]^{-1}$.*

PROOF. Choose a basis x_1, \dots, x_n for B so that x_{m+1}, \dots, x_n form a basis for A . Let x_1^*, \dots, x_n^* denote the dual basis for B^* , so that x_1^*, \dots, x_m^* form a basis for $C^* \subset B^*$. Define field elements f, g, h by

¹ Actually this element D is the reciprocal of the torsion as defined by Franz.

$$\begin{aligned} a &= fx_{m+1} \wedge \cdots \wedge x_n, & b &= gx_1 \wedge \cdots \wedge x_n, \\ b^* &= \bar{g}^{-1}x_1^* \wedge \cdots \wedge x_n^*, & c^* &= \bar{h}x_1^* \wedge \cdots \wedge x_m^*. \end{aligned}$$

Then $[b/a, c^*] = gf^{-1}h$ and $[a, b^*/c^*] = \pm fg^{-1}h^{-1}$. This completes the proof.

Now given an acyclic chain complex $0 \rightarrow C_n \rightarrow C_{n-1} \rightarrow \cdots \rightarrow C_0 \rightarrow 0$ with generators $v_q \in \Lambda C_q$, form the dual complex

$$0 \longrightarrow C_0^* \longrightarrow C_1^* \longrightarrow \cdots \longrightarrow C_n^* \longrightarrow 0$$

and the dual generators $v_q^* \in \Lambda C_q^*$. Just as before one constructs generators

$$(v_q^*/v_{q-1}^*/\cdots/v_1^*/v_0^*) \in \Lambda(\partial^* C_q^*)$$

by induction on q . The torsion $D_1 \in F$ of the dual complex is then defined by the identity

$$D_1 = v_n^*/(v_{n-1}^*/\cdots/v_1^*/v_0^*)$$

or

$$(2) \quad (v_{n-1}^*/v_{n-2}^*/\cdots/v_1^*/v_0^*) = D_1^{-1}v_n^*.$$

Applying Lemma 3 to the dual exact sequences

$$0 \longrightarrow \partial C_{q+1} \longrightarrow C_q \longrightarrow \partial C_q \longrightarrow 0,$$

and

$$0 \longleftarrow \partial^* C_q^* \longleftarrow C_q^* \longleftarrow \partial^* C_{q-1}^* \longleftarrow 0,$$

one obtains the identity

$$\begin{aligned} &[v_q/(v_{q+1}/\cdots/v_{n-1}/v_n), (v_{q-1}^*/\cdots/v_1^*/v_0^*)] \\ &= \pm [(v_{q+1}/\cdots/v_{n-1}/v_n), v_q^*/(v_{q-1}^*/\cdots/v_1^*/v_0^*)]^{-1}. \end{aligned}$$

In other words the field element

$$\pm f = [(v_{q+1}/\cdots/v_{n-1}/v_n), (v_q^*/v_{q-1}^*/\cdots/v_1^*/v_0^*)]^{\varepsilon(q)}$$

is independent of q .

Taking $q = 0$ and making use of formula (1) this gives

$$\pm f = [(v_1/\cdots/v_{n-1}/v_n), v_0^*] = [D^{-1}v_0, v_0^*] = D^{-1}.$$

On the other hand, taking $q = n - 1$ and using the formula (2) it gives

$$\pm f = [v_n, D_1^{-1}v_n^*]^{\varepsilon(n-1)} = \bar{D}_1^{\varepsilon(n)}.$$

Therefore the torsion D_1 of the dual complex satisfies the identity

$$(3) \quad D\bar{D}_1^{\varepsilon(n)} = \pm 1.$$

This completes the purely algebraic part of the proof.

The remainder of the proof is straightforward. The q -cells of M determine a preferred basis for $C_q(M; Z)$ and hence a preferred generator

$$v_q \in \Lambda C_q = \Lambda(F \otimes_{\Pi} C_q(M; Z)) .$$

This generator is well defined up to multiplication by elements of the form $\pm h(\pi)$. If $D \in F_0$ denotes the torsion associated with $\{C_q, v_q\}$ then $\Delta_h M$ is defined to be the coset $\Delta_h M = \pm h(\Pi)D \in F_0 / \pm h(\Pi)$.

The $(n - q)$ -cells of $M' - bM'$ determine a dual basis for $C_{n-q}(M', bM'; Z)$ and hence determine the dual generator

$$v_q^* \in \Lambda C_q^* = \Lambda(F \otimes_{\Pi} C_{n-q}(M', bM'; Z)) .$$

Thus if D_1 denotes the torsion associated with $\{C_q^*, v_q^*\}$ then

$$\Delta_h(M', bM') = \pm h(\Pi)D_1 \in F_0 / \pm h(\Pi) .$$

According to formula (3):

$$(\Delta_h M)(\bar{\Delta}_h(M', bM'))^{\varepsilon(n)} = \pm h(\Pi) .$$

But since M and M' have a common subdivision, we have

$$\Delta_h(M, bM) = \Delta_h(M', bM') .$$

This completes the proof of Theorems 1, 1' and 2.

2. Applications to knot theory

In this section, Π will always be an infinite cyclic multiplicative group with generator t . As field F take the quotient field of the integral group ring $Z[\Pi]$. Thus F can be described as the field $Q(t)$ of rational functions in one variable t over the rational numbers. Let $I: Z[\Pi] \rightarrow Q(t)$ be the imbedding, and define the conjugation operation in $Q(t)$ by $\bar{f}(t) = f(t^{-1})$.

LEMMA 4. *Let K be a finite polyhedron having the homology of the circle, and let $L = \tilde{K}$ be its infinite cyclic covering complex. Then the torsion*

$$\Delta_t L \in Q(t)_0 / \pm \Pi$$

is defined.

The proof will be given later.

As an application consider any differentiable imbedding of the $(n - 2)$ -sphere in the n -sphere. Removing a tubular neighborhood of the $(n - 2)$ -sphere from S^n we obtain a compact manifold K with boundary. Choose some C^1 -triangulation of K (see Whitehead [13]) and let $M = \tilde{K}$ denote the infinite cyclic covering complex.

THEOREM 3. *If M is obtained from a differentiable imbedding $S^{n-2} \rightarrow S^n$ as above, then the torsion $\Delta_I M$ is defined and satisfies the symmetry relation*

$$\begin{aligned}\Delta_I M &= \bar{\Delta}_I M && \text{for } n \text{ odd,} \\ (\Delta_I M)(\bar{\Delta}_I M) &= \pm \Pi/(t-1)^2 && \text{for } n \text{ even.}\end{aligned}$$

PROOF. It follows from Lemma 4 that $\Delta_I M$ is defined. According to Theorem 2 we have

$$(*) \quad (\Delta_I M)(\bar{\Delta}_I M)^{\varepsilon(n)} = \Delta_I(bM).$$

But the boundary bM is clearly equivariantly diffeomorphic to the product $\tilde{S}^1 \times S^{n-2}$; where \tilde{S}^1 denotes the universal covering space of the circle. Thus bM can be given an equivariant cell structure consisting of four cells

$$e^1 \times e^{n-2}, \quad e^0 \times e^{n-2}, \quad e^1 \times e^0, \quad e^0 \times e^0$$

together with their translates under the action of Π . The boundary relations are

$$\partial(e^1 \times e^{n-2}) = (t-1)(e^0 \times e^{n-2}), \quad \partial(e^1 \times e^0) = (t-1)(e^0 \times e^0).$$

The torsion invariant

$$D = e^0 \times e^0 / (e^1 \times e^0 / \cdots / 1 / e^0 \times e^{n-2} / e^1 \times e^{n-2})$$

for this chain complex can easily be computed. In fact D is equal to $(t-1)^{-1-\varepsilon(n)}$. The torsion computed from any C^1 -triangulation of bM will be the same, since this cell complex has a C^1 -triangulation as an equivariant subdivision. Therefore

$$\Delta_I(bM) = \pm \Pi/(t-1)^{1+\varepsilon(n)}.$$

Combining this information with the formula (*) we obtain Theorem 3.

As an example, consider the standard imbedding of S^{n-2} in S^n . Then

$$\Delta_I M = \pm \Pi/(t-1).$$

Therefore $(\Delta_I M)(\bar{\Delta}_I M)^{\varepsilon(n)} = \pm \Pi/(t-1)(t^{-1}-1)^{\varepsilon(n)}$ is equal to $\pm \Pi/(t-1)^{1+\varepsilon(n)}$, as required by Theorem 3.

Now let us specialize to the case $n = 3$.

THEOREM 4. *If K is a complex of dimension ≤ 2 , or a manifold of dimension ≤ 3 , having the homology of a circle, then the torsion invariant $\Delta_I \tilde{K}$ is equal to $\pm \Pi A(t)/(t-1)$, where $A(t)$ denotes the Alexander polynomial of the fundamental group.*

Combining this with Theorem 3 we see that the Alexander polynomial $A(t)$ for the complement of a knot in S^3 satisfies the relation

$$A(t)/(t-1) = \pm t^i A(t^{-1})/(t^{-1}-1)$$

hence

$$A(t^{-1}) = \mp t^{-i-1} A(t).$$

Combining this with the fact that $A(1) = \pm 1$ (see for example Fox [4]) one easily obtains the following:

COROLLARY (Seifert). *The Alexander polynomial $A(t)$ of a knot has the form $\pm t^j(a_0 + a_1 t + \dots + a_{2r} t^{2r})$ with $a_0 = a_{2r}$, $a_1 = a_{2r-1}$, \dots , $a_{r-1} = a_{r+1}$.*

Note. The possibility that this corollary could be proved in this way was conjectured by Reidemeister [8, § 5]. The above proof is close to that given by Blanchfield [1].

The rest of this paper will be devoted to the proofs of Lemma 4 and Theorem 4.

In order to prove Lemma 4 one must show that the chain complex $Q(t) \otimes_{\Pi} C_*(L; Z)$ is acyclic. Let $e_1^q, \dots, e_{\alpha_q}^q$ denote the standard basis for $C_q(L; Z)$, with one basis element for each q -cell of $K = L/\Pi$. The boundary homomorphism on $C_q(L; Z)$ can be described by a matrix $\|a_{ij}^q(t)\|$ over the integral domain $Z[\Pi]$, which is defined by:

$$\partial e_i^q = \sum_j a_{ij}^q(t) e_j^{q-1}.$$

Let r_q denote the rank of this matrix. Note that the difference $\alpha_q - r_q - r_{q+1}$ is equal to the q^{th} Betti number of the chain complex

$$C_* = Q(t) \otimes_{\Pi} C_*(L; Z).$$

Now consider the chain complex $C_*(K; Z)$. Note that the boundary homomorphism

$$\partial: C_q(K; Z) \longrightarrow C_{q-1}(K; Z)$$

can be described by a matrix of integers $\|a_{ij}^q(1)\|$ which is a homomorphic image of the matrix above. Therefore the rank r'_q of this boundary homomorphism satisfies $r'_q \leq r_q$. This implies that the Betti numbers $\alpha_q - r'_q - r'_{q+1}$ of $C_*(K; Z)$ are greater than or equal to the corresponding Betti numbers of C_* . But K has the homology of a circle. Therefore the chain complex C_* can have non-trivial homology at most in the dimensions 0 and 1.

On the other hand $H_0(C_*)$ is zero. For if e_i^0 denotes any vertex, then there certainly exists a 1-chain c with $\partial c = t e_i^0 - e_i^0$. Since $t - 1$ is a unit in $Q(t)$, this implies that e_i^0 itself is a boundary.

Finally, since the Euler characteristic $\alpha_0 - \alpha_1 + \alpha_2 - \dots \pm \alpha_n$ is

zero, the group $H_1(C_*)$ must also be zero. This completes the proof of Lemma 4.

PROOF OF THEOREM 4. If K is a 3-manifold, then by pushing in one free face at a time, we can collapse K down to a 2-dimensional subcomplex. These collapsings do not affect the torsion. (Compare Whitehead [14].)

Furthermore the simplicial complex K can be replaced by a CW-complex K_1 with a single vertex e_1^0 . For let e^1 be any edge of K , and let K' be the CW-complex obtained from K by collapsing e^1 to a point. It is not difficult to show that $\Delta_r \tilde{K}' = \Delta_r \tilde{K}$. Now iterate this procedure, always selecting an edge e^1 which has distinct end points. After a finite number of stages we obtain a complex K_1 with a single vertex.

Let $L = \tilde{K}_1$. The boundary of any edge e_j^1 of L clearly has the form

$$\partial e_j^1 = (t^r - t^s)e_1^0.$$

Without loss of generality we may assume that the first edge e_1^1 has boundary equal to $(t - 1)e_1^0$. For otherwise it is only necessary to adjoin a suitable 2-cell to K , having such an edge as free face. (Again compare Whitehead [14].)

Now consider the matrices $\|a_{ij}^2(t)\|$ and $\|a_{ji}^1(t)\|$ as defined earlier. If $m = \alpha_2$ denotes the number of 2-cells, then the relation $\alpha_2 - \alpha_1 + \alpha_0 = 0$ implies that $\alpha_1 = m + 1$. Thus $\|a_{ij}^2(t)\|$ is an $m \times (m + 1)$ -matrix and $\|a_{ji}^1(t)\|$ is an $(m + 1) \times 1$ -matrix. It is well known that $\|a_{ij}^2(t)\|$ is precisely the Alexander matrix of that presentation of the fundamental group of K which is associated with the given cell structure. (Compare Fox [3, p. 547] and [4].) Hence the Alexander polynomial $A(t)$ is defined to be a generator of the principal ideal in $Z[\Pi]$ generated by the $m \times m$ minor determinants of $\|a_{ij}^2(t)\|$.

The first column of $\|a_{ij}^2(t)\|$ can be expressed as a linear combination of the remaining columns. This follows from the relation

$$\sum_j a_{ij}^2 a_{ji}^1 = 0,$$

together with the fact that $a_{11}^1 = t - 1$, and that each a_{ji}^1 has the form $t^r - t^s$; and hence is divisible by $t - 1$. Therefore $A(t)$ can be defined as the determinant of the matrix obtained by deleting the first column of $\|a_{ij}^2\|$.

Now let us compute the torsion invariant. Let

$$v_2 = e_1^2 \wedge \cdots \wedge e_m^2, \quad v_1 = e_1^1 \wedge \cdots \wedge e_{m+1}^1, \quad v_0 = e_1^0,$$

and note that

$$e_1^1 \wedge (\partial e_1^2 \wedge \partial e_2^2 \wedge \cdots \wedge \partial e_m^2) = A(t)v_1.$$

Therefore, using the exact sequence

$$0 \longrightarrow C_2 \xrightarrow{\partial} C_1 \xrightarrow{\partial} C_0 \longrightarrow 0,$$

we have $A(t)v_1/v_2 = \partial e_1^1 = (t-1)v_0$, hence $v_0/(v_1/v_2) = A(t)/(t-1)$. This completes the proof of Theorem 4.

REMARK. A similar computation can be carried out for a knot with n components in S^3 , $n \geq 2$. In this case the torsion

$$\Delta_I M \in Q(t_1, \dots, t_n)/\pm \Pi$$

associated with the maximal abelian covering is precisely equal to the Alexander polynomial $A(t_1, \dots, t_n)$. Applying the duality theorem, one obtains the symmetry relation

$$A(t_1^{-1}, \dots, t_n^{-1}) = \pm t_1^{i_1} \dots t_n^{i_n} A(t_1, \dots, t_n)$$

which is due to Torres [12]. (See also [1], [5].)

PRINCETON UNIVERSITY

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