

S-EQUIVALENCE OF KNOTS

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ABSTRACT. S-equivalence of classical knots is investigated, as well as its relationship with mutation and the unknotting number. Furthermore, we identify the kernel of Bredon's double suspension map, and give a geometric relation between slice and algebraically slice knots. Finally, we show that every knot is S-equivalent to a prime knot.

1. INTRODUCTION

An *oriented knot* k is a smooth (or PL) oriented pair (S^3, S^1) ; two knots are regarded as the same if there is an orientation preserving diffeomorphism sending one onto the other. An *unoriented knot* k is defined in the same way, but without regard to the orientation of S^1 . Every oriented knot is spanned by an oriented surface, a Seifert surface, and this gives rise to a matrix of linking numbers called a Seifert matrix. Any two Seifert matrices of the same knot are S-equivalent: the definition of S-equivalence is given in, for example, [14, 21, 11]. It is the equivalence relation generated by ambient surgery on a Seifert surface of the knot. In [19], two oriented knots are defined to be *S-equivalent* if their Seifert matrices are S-equivalent, and the following result is proved.

Theorem 1. *Two oriented knots are S-equivalent if and only if they are related by a sequence of doubled-delta moves shown in Figure 1.*

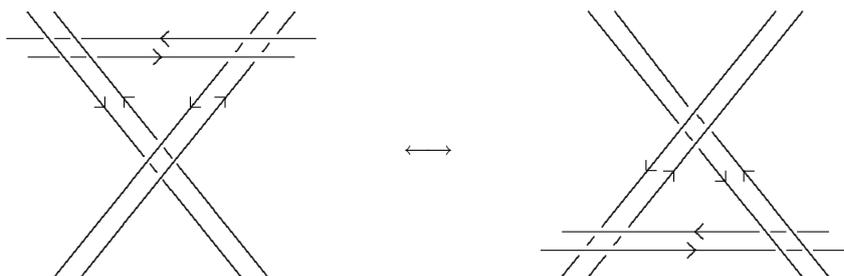


FIGURE 1. The doubled-delta move

It is, of course, from this result that the concept of S-equivalence of knots derives its interest. Note that, as pointed out in [19], a knot is S-equivalent to the trivial knot if and only if it has Alexander polynomial one.

Date: September 26, 2003.

1991 Mathematics Subject Classification. Primary 57M25; Secondary 57Q45.

Key words and phrases. S-equivalence, mutation, Seifert matrix, unknotting number, doubled-delta move, knot module, algebraically slice, prime knot.

It has long been known that mutation of a knot preserves the Alexander, Jones, Homfly and Kauffman polynomials (see [7, 17, 18, 16]), and it was shown in [10] that it does not preserve the knot module. Here we investigate some properties of S-equivalence of knots and its relationship with mutation. We show that cancellation does not hold for S-equivalence, that S-equivalence does not imply mutation, and that mutation does not imply S-equivalence.

For a knot k S-equivalent to the trivial knot we define $\delta(k)$ to be the least number of doubled-delta moves needed to unknot k , and by relating this to the unknotting number we show that $\delta(k)$ can be arbitrarily large.

We also show that two knots are sent to the same image under Bredon's double suspension map (see [2]) if and only if they are S-equivalent. Moreover we show that a knot is algebraically slice if and only if it is S-equivalent to a slice knot, with a corresponding result for doubly-slice knots.

Finally we use results of Lickorish [15] to show that every knot is S-equivalent to a prime knot.

2. S-EQUIVALENCE

Theorem 2. *There exist oriented knots k, l, m such that $k + m$ is S-equivalent to $l + m$ but k is not S-equivalent to l .*

Proof. Examples are given in [1] of simple $(4q+1)$ -knots K, L, M such that $K+M = L+M$ but $K \neq L$, for each $q \geq 1$. Since simple knots in higher dimensions are in one-one correspondence with the S-equivalence classes of Seifert matrices, we can let U, V, W be Seifert matrices of K, L, M respectively, and then $U \oplus W$ is S-equivalent to $V \oplus W$ but U is not S-equivalent to V . Now as pointed out in [8], the Seifert matrices of classical knots are the same as those that occur with simple $(4q+1)$ -knots, so there exist classical knots k, l, m with Seifert matrices U, V, W respectively: this establishes the result. \square

Suppose that k is S-equivalent to the trivial knot: we define $\delta(k)$ to be the least number of doubled-delta moves needed to change k to the trivial knot.

Theorem 3. *For any k S-equivalent to the trivial knot, $u(k) \leq 8\delta(k)$ where $u(k)$ is the unknotting number of k . In particular, $\delta(k)$ can be arbitrarily large.*

Proof. Clearly a doubled-delta move can be accomplished by eight unknotting moves: in Figure 1 simply change the four crossings in the top left-hand part, slide the horizontal band down and then change the four crossings in the bottom right-hand part. This shows that $u(k) \leq 8\delta(k)$. By [6, p 354] there are knots with Alexander polynomial one and arbitrarily large unknotting number. The result follows. \square

In [2] Bredon defines a semigroup homomorphism $\omega^2 : K_1 \rightarrow K_5$, where K_n denotes the semigroup of isotopy classes of smooth simple n -knots. Bredon's definition and results are more general, but this is all we shall need here. Bredon shows that ω^2 preserves the Seifert matrix; since the simple 5-knots are classified by the S-equivalence class of the Seifert matrix, we have the following.

Theorem 4. $\omega^2(k) = \omega^2(l)$ if and only if k and l are S-equivalent.

3. S-EQUIVALENCE AND MUTATION

If the oriented knots k, l are positive mutants, i.e. if they are related by a mutation which does not require any changes in orientation, then by [12, Theorem 2.1], they have the same Seifert matrix and so they are S-equivalent. The converse fails, as the following result shows.

Theorem 5. *There exist oriented knots k, l such that k is S-equivalent to l but k and l are not equivalent by any sequence of mutations even as unoriented knots.*

Proof. Take k to be the trivial knot and l to be the Kinoshita-Terasaka knot. Both have trivial Alexander polynomial and are therefore S-equivalent, but l has non-trivial Jones polynomial and so cannot be equivalent by mutation to k . Alternatively one can take l to be the Conway knot. These knots appear as $11n_{42}$ and $11n_{34}$ respectively in the Knotscape table, available from the website of Morwen Thistlethwaite: www.math.utk.edu/~morwen/. \square

Theorem 6. *There exist unoriented knots k, l such that k is a mutant of l but k is not S-equivalent to l however the orientations are chosen.*

Proof. In [10] it is shown that if h' denotes the reverse of h , i.e. with the orientation of S^1 reversed, then $h+h$ and $h+h'$ are mutants as unoriented knots. If we take h to be the pretzel knot $(25, -3, 13)$, it is shown in [9] that h has Steinitz-Fox-Smythe row ideal class ρ which does not satisfy $\rho^2 = 1$. (The arguments used are those of [3].) Furthermore, the row ideal class of h' is τ , the column ideal class of h , so that the row ideal class of $h+h$ is $\rho^2 \neq 1$, whereas the row ideal class of $h+h'$ is $\rho\tau = 1$. Thus $k = h+h$ and $l = h+h'$ have non-isomorphic knot modules. If we give k the opposite orientation, then its row ideal class is $\tau^2 \neq 1$, so that $k' = h'+h'$ and $l = h+h'$ have non-isomorphic knot modules. Thus neither k nor k' is S-equivalent to l however the orientations are chosen. \square

4. S-EQUIVALENCE AND ALGEBRAICALLY SLICE KNOTS

Recall that a knot $k = (S^3, S^1)$ is *slice* if it is the boundary of a smooth ball-pair (B^4, B^2) . Every Seifert matrix of a slice knot is unimodularly congruent to one of the form

$$(4.1) \quad A = \begin{pmatrix} 0 & * \\ * & * \end{pmatrix},$$

all the blocks being $g \times g$ for some g (see [13, Lemma 2]). This is a necessary but not a sufficient condition for k to be slice, so we say that k is *algebraically slice* if it has a Seifert matrix S-equivalent to one of the form in (4.1).

Theorem 7. *A knot k is algebraically slice if and only if it is S-equivalent to a slice knot.*

Proof. Clearly if k is S-equivalent to a slice knot then k is algebraically slice.

Conversely, suppose that k is algebraically slice, and let A be a Seifert matrix of the form (4.1) which is in the S-equivalence class given by k ; then

$$A - A' = \begin{pmatrix} 0 & B \\ -B' & D \end{pmatrix},$$

where $|A - A'| = |B|^2$, so $|B| = \pm 1$. Thus there exist square unimodular integer matrices X, Y such that $X'BY = I$, the identity matrix. Then we have

$$\begin{pmatrix} X' & 0 \\ 0 & Y' \end{pmatrix} \begin{pmatrix} 0 & B \\ -B' & D \end{pmatrix} \begin{pmatrix} X & 0 \\ 0 & Y \end{pmatrix} = \begin{pmatrix} 0 & X'BY \\ -Y'B'X & Y'DY \end{pmatrix} = \begin{pmatrix} 0 & I \\ -I' & C \end{pmatrix},$$

where $C = Y'DY$. So we may assume that A satisfies

$$(4.2) \quad A - A' = \begin{pmatrix} 0 & I \\ -I' & C \end{pmatrix}$$

whilst retaining the form in (4.1). Taking transposes in (4.2) we find that $C' = -C$, so the diagonal entries of C are all zero. By (integer) row moves on A , i.e. by adding appropriate integer multiples of the first g rows to the last g rows, we can kill off the entries of C above the diagonal and by the corresponding column moves we kill off the entries of C below the diagonal. This gives a unimodular congruence of A which allows us to assume that

$$(4.3) \quad A - A' = \begin{pmatrix} 0 & I \\ -I' & 0 \end{pmatrix},$$

A still having the form in (4.1). Let the corresponding basis of $H_1(V)$ be

$$f_1, f_3, \dots, f_{2g-1}, f_2, f_4, \dots, f_{2g}.$$

Then we can construct a knot l having A as its Seifert matrix by modifying the

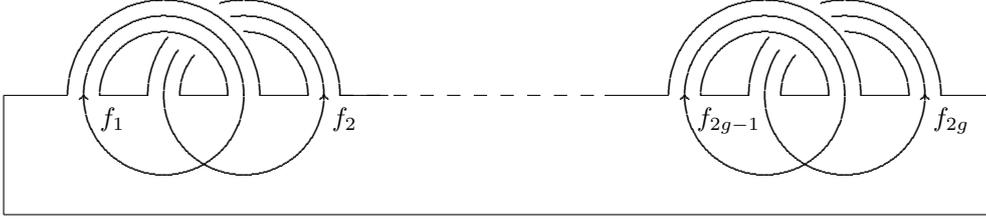


FIGURE 2. A standard circle basis

trivial knot shown in Figure 2. We do not alter the f_{odd} , but change the embeddings of the f_{even} to fit the entries in A . We can now do ambient surgery on the f_{odd} in B^4 to show that l is a slice knot: take a product $V \times [0, 1] \subset \partial B^4 \times [0, 1] \subset B^4$, where $V \times \{0\} \subset \partial B^4$. Then attaching a 2-handle to $V \times [0, 1]$ along each of $f_1 \times \{1\}, f_3 \times \{1\}, \dots, f_{2g-1} \times \{1\}$ gives a 3-manifold W embedded in B^4 such that $\partial W = V \cup B^2$ and $\partial(B^4, B^2) = (S^3, S^1) = l$. (We have performed g surgeries which would reduce a closed orientable surface of genus g to S^2 , and hence reduce V to a disc.) Thus k is S-equivalent to l which is slice. \square

A knot $k = (S^3, S^1)$ is *doubly-slice* if it is the intersection of an unknotted 2-knot (S^4, S^2) with the equatorial $S^3 \subset S^4$. Every Seifert matrix of a doubly-slice knot is S-equivalent to one of the form

$$(4.4) \quad A = \begin{pmatrix} 0 & * \\ * & 0 \end{pmatrix},$$

all the blocks being square (see [20, Theorem 2.3]). Again, this is a necessary but not a sufficient condition for k to be doubly-slice, so we say that k is *algebraically doubly-slice* if k has a Seifert matrix S-equivalent to one of the form (4.4).

Theorem 8. *A knot is algebraically doubly-slice if and only if it is S-equivalent to a doubly-slice knot.*

Proof. Clearly if k is S-equivalent to a doubly-slice knot then k is algebraically doubly-slice.

Conversely, suppose that k is algebraically doubly-slice; then the proof above yields a Seifert matrix A of the form (4.4) which is in the S-equivalence class given by k and such that $A - A'$ has the form (4.3.) Let B_+^4/B_-^4 be the northern/southern hemispheres of S^4 , and construct W_+/W_- as above in B_+^4/B_-^4 using $\{f_1, f_3, \dots, f_{2g-1}\}/\{f_2, f_4, \dots, f_{2g}\}$ respectively. Then $W_+ \cup W_- \cong B^3$ and l is doubly-slice. \square

The reef knot is cobordant to the trivial knot, indeed it is doubly-slice, but is not S-equivalent to the trivial knot, for it has Alexander polynomial $(1 - t + t^2)^2$. On the other hand, if a knot is S-equivalent to the trivial knot then its Alexander polynomial is 1, so by [4] or [5, Theorem 11.7B] it is topologically slice. But by [6] we know that there are infinitely many such knots which are not slice in the smooth category.

5. S-EQUIVALENCE AND PRIME KNOTS

In this section we use results due to Lickorish in order to show that every S-equivalence class contains a prime knot.

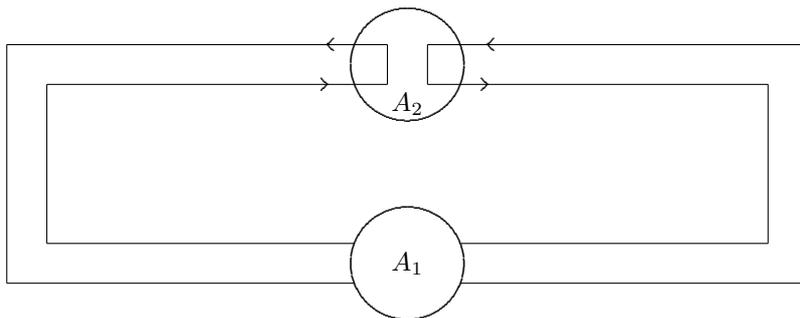


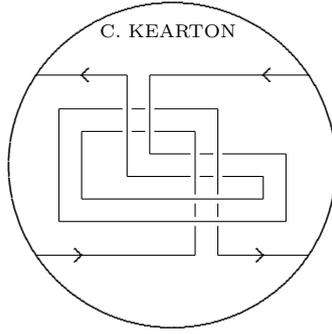
FIGURE 3. Prime tangle plus trivial tangle

Theorem 9. *Every knot k is S-equivalent to a prime knot.*

Proof. First note that by the results of [22], every untwisted double of a non-trivial knot has genus 1, hence is prime, and has Alexander polynomial one, so is S-equivalent to the trivial knot. Thus we can assume that k is non-trivial.

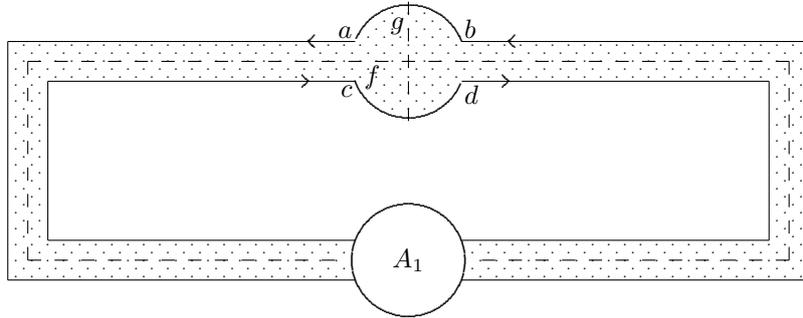
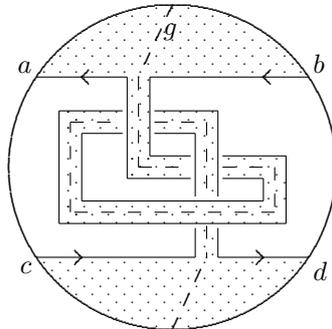
By the proof of [15, Theorem 4], k is the sum of a prime (two-string) tangle with the trivial tangle (see [15] for definitions). We can redraw [15, Figure 4] as Figure 3 above. Here A_1, A_2 are 3-balls, $(A_1, k \cap A_1)$ is a prime tangle and $(A_2, k \cap A_2)$ is the trivial tangle. Strictly speaking A_2 should be the closure of $S^3 - A_1$, but it is more convenient to draw A_1 and A_2 with a product neighbourhood between them. The tangle in Figure 4 is shown to be prime in [15, §2]; let us call it (A_3, t_3) .

Let l be the knot formed by replacing $(A_2, k \cap A_2)$ by (A_3, t_3) in Figure 3; put another way, let l be formed by adding the prime tangle $(A_1, k \cap A_1)$ to the prime tangle (A_3, t_3) . By [15, Theorem 1], l is a prime knot (it is easily checked that it

FIGURE 4. The prime tangle (A_3, t_3)

has only one component). As explained in [15], there are many ways of adding two given tangles; we shall specify below which way to choose.

We need a Seifert surface for l . First note that applying Seifert's algorithm to k shows that there is a Seifert surface V for k contained in A_1 except for the two outlying discs. The first part of our surface is shown in Figure 5, and is formed by attaching a disc to V along two arcs in its boundary (of course, $V \cap A_1$ is not shown). We are looking at the positive side of the surface. The second part is shown in Figure 6; here we are looking at the negative side. These parts are joined along the arcs ab and cd to form U , which is a Seifert surface of l . The disc in the first part of the surface is lying in the plane and the second part is above the plane (except for the edges ab and cd). The genus of U is one greater than that of V , and the diagrams show two extra generators needed for $H_1(U)$, i.e. f, g .

FIGURE 5. First part of the Seifert surface U FIGURE 6. Second part of the Seifert surface U

Let i_+ denote the map which pushes a cycle off U for a small distance in the positive normal direction. By putting the appropriate number of twists in the

bands of U we may arrange for $L(i_+f, f) = 0$ and $L(i_+g, g) = 0$, where $L(u, v)$ denotes the linking number in S^3 of the two disjoint cycles u, v . Note that although this changes l , we are simply taking a different sum of the two tangles, achieved by using a different homeomorphism between their boundaries (see [15] for details). Moreover $L(i_+g, f) = 0$, and we can orient the cycles so that $L(i_+f, g) = +1$.

Then if V gives rise to a Seifert matrix A , U yields a Seifert matrix of the form

$$B = \begin{pmatrix} A & \alpha & 0 \\ \beta & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix},$$

where α (β) is a column (row) vector over \mathbb{Z} . The obvious column and corresponding row operations show that B is congruent by a unimodular matrix to

$$\begin{pmatrix} A & \alpha & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

which is S-equivalent to A . Thus l is S-equivalent to k , and by [15, Theorem 1] l is prime. \square

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