

## On the signature invariants of a non-singular complex sesqui-linear form

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The purpose of this note is to make clear the relationship between two types of signatures defined for a non-singular real bilinear or complex sesqui-linear form, and then, to get a result in the algebraic topology.

Let  $l: V \times V \rightarrow C$  be a complex sesqui-linear form of finite dimension; a matrix representation  $x^* \Gamma y$  is used and a symbol " $*$ " stands for the transpose of the conjugate of the matrix or the vector. Let  $t$  be an indeterminant which may be thought either as an automorphism or as a variable ranging over the complex numbers. We call  $\Gamma(t) = \Gamma - \Gamma^* t$  an Alexander matrix and  $\det \Gamma(t)$  the Alexander polynomial. The first series of signatures consists of the signature  $\tau_\omega$  of the hermitian form  $l_\omega = x^* \Gamma_\omega y$  with  $\Gamma_\omega = (1/2)\{(1-\bar{\omega})\Gamma + (1-\omega)\Gamma^*\}$ . Since  $\tau_\xi = \text{sign}(1 - \text{Re } \xi) \tau_\omega$  with  $\omega = -(1-\xi)/(1-\bar{\xi})$ , the only interesting case is when  $\omega$  is on the unit circle, where  $\Gamma_\omega$  reduces to  $\Gamma_\omega = (1/2)(1-\bar{\omega})\Gamma(\omega)$ .

A hermitian form  $l_+ = x^* A y$  where  $A = (1/2)(\Gamma + \Gamma^*)$  and a skew-hermitian form  $l_- = x^* (-Q) y$  where  $Q = (1/2)(\Gamma^* - \Gamma)$  are considered; then  $\Gamma = A - Q$  and of course  $2A = \Gamma_{-1}$ . If the form  $l$  is non-singular, then the matrix  $P = (\Gamma^*)^{-1} \Gamma$  gives an automorphism  $t$  of  $l$ , i. e.,  $P^* \Gamma P = \Gamma$ , and hence of  $l_\omega$ ,  $l_+$  and  $l_-$ . The eigen-values  $\alpha$  of the automorphism  $t$  associate another series of signatures  $\sigma_{(\alpha)}$  which are defined by the hermitian form  $l_+$ ; where  $l_+$  is restricted to the  $\alpha$ -root subspaces  $V_\alpha = \{x \in V; (t - \alpha)^k x = 0 \text{ for some } k\}$ . Note that  $\dim V_\alpha > 0$  if and only if  $\alpha$  is a root of the Alexander polynomial and we have a generalized Cayley transformation  $Q(I+P) = A(I-P)$ . Moreover, we can remark that, if  $\alpha \neq \pm 1$ ,  $\sigma_{(\alpha)} = \text{sign}(V_\alpha; l_+)$  is equal to  $\text{sign}(\text{Im } \alpha) \text{sign}(V_\alpha; il_-)$ . (Cf. § 1, case (b).) We define  $\sigma_{(-1 \pm 0i)}$  by  $\pm \text{sign}(V_{-1}; il_-)$ .

**THEOREM 1 (Complex case).** For  $\omega = \exp(i\varphi)$  and  $\alpha = \exp(i\theta)$  with  $-\pi < \varphi < \pi$  and  $-\pi < \theta < \pi$ ,

$$(*) \quad \tau_\omega = \text{sign}(\text{Im } \omega) \left\{ \sum_{|\alpha|=1, \alpha \neq -1} \text{sign}(\varphi - \theta) \sigma_{(\alpha)} + \sigma_{(-1+0i)} \right\}$$

holds, provided either the automorphism  $t$  is semi-simple, or  $\omega$  is not a root of the Alexander polynomial.

**REMARK.** If  $\omega = -1$ ,  $(*)$  is replaced by  $(*)'$   $\text{sign}(l_+) = \sum \sigma_{(\alpha)} (|\alpha|=1, \alpha \neq -1)$ . The formula,  $(*)$  or  $(*)'$ , does not always hold. The excluded cases will be

studied in the § 3.

If  $l$  is a real non-singular bilinear form, then we shall deduce the following theorem with the more appropriate notation:  $\sigma_0 = \sigma_{(1)}$  and for  $0 < \theta < \pi$ ,  $\sigma_\theta = \sigma_{(\alpha)} + \sigma_{(\bar{\alpha})}$  where  $\alpha = \exp(i\theta)$ .

THEOREM 2 (Real case). For  $\omega = \exp(\pm i\varphi)$  with  $0 < \varphi \leq \pi$ ,

$$(**) \quad \tau_\omega = \sum_{0 \leq \theta < \varphi} \sigma_\theta + \frac{1}{2} \sigma_\varphi$$

holds, provided either the automorphism  $t$  is semi-simple, or  $\omega$  is not a root of the Alexander polynomial.

The study on the classification of sesqui-linear forms is summarized in [4]. And the reader can find a definition of  $\sigma_\theta$  for a knot in [2], which can be seen to be equal to  $\sigma_\theta$  for the non-singular Seifert matrix. The hermitian form  $l_\omega$  is defined and used by Levine [1] and Tristram [3] in the algebraic topology of knots and links. In the last section we are concerned with the calculation of  $\sigma_\theta$  for some algebraic links and we generalize the Brieskorn criterion [5]. Finally we mention a totally elementary proof of the result of Rokhlin [8] in an interesting special case.

### § 1. Proof of Theorem 1.

Since  $l_\omega(f(t)x, y) = l_\omega(x, \overline{f(t^{-1})}y)$  for any complex polynomial  $f(t)$ ,  $V_\alpha$  is orthogonal to  $V_\beta$  with respect to the hermitian form  $l_\omega$  unless  $\bar{\alpha}\beta = 1$ . It follows that the only contributions to the signature arise from  $V_\alpha$  with  $|\alpha| = 1$ .

On the other hand by the generalized Cayley transformation  $Q(I+P) = A(I-P)$ , we know that if  $\det(I+P) \neq 0$  then  $\Gamma_\omega = A(1-\bar{\omega})(P-\omega)(I+P)^{-1}$  and if  $\det(I-P) \neq 0$  then  $\Gamma_\omega = Q(1-\bar{\omega})(P-\omega)(I-P)^{-1}$ .

(a) *The case when  $t$  is semi-simple, that is,  $V_\alpha = \{x \in V; (t-\alpha)x = 0\}$ :* If  $x, y \in V_{-1}$ , then  $l_\omega(x, y) = (\omega - \bar{\omega})l_-(x, y)$ . Hence  $\text{sign}(V_{-1}; l_\omega) = \text{sign}(\text{Im } \omega) \text{sign}(V_{-1}; il_-)$ .

If  $|\alpha| = 1$  and  $\alpha \neq -1$ , we have  $l_\omega(x, y) = (1-\bar{\omega})(1-\bar{\alpha}\omega)(1+\bar{\alpha})^{-1}l_+(x, y)$ , provided  $x, y \in V_\alpha$ . Noting that  $(1+\bar{\alpha})(1+\alpha) = 2+(\alpha+\bar{\alpha}) > 0$ , we have only to study the sign of the following function  $f$ .

$$f = (1-\bar{\omega})(1-\bar{\alpha}\omega)(1+\alpha) = -8 \sin(-\varphi/2) \sin((\varphi-\theta)/2) \cos(\theta/2).$$

We get  $\text{sign } f = \text{sign}(\text{Im } \omega) \text{sign}(\varphi-\theta)$ , provided  $-\pi < \theta, \varphi < \pi$ .

(b) *The case when  $l(x, y)$  is a general non-singular sesqui-linear form:* We restrict  $\Gamma$  to  $V_\alpha$  with  $|\alpha| = 1$ , and then perturb it. Assuming  $\alpha \neq -1$ , we have  $Q = A(I-P)(I+P)^{-1}$  and another skew-hermitian matrix  ${}_0Q = A(1-\alpha)(1+\alpha)^{-1}$ . A family of skew-hermitian matrices  ${}_sQ = sQ + (1-s){}_0Q$ ,  $0 \leq s \leq 1$ , is considered and we get a family of sesqui-linear forms  ${}_s! = x {}_s! \Gamma y$ ,  $0 \leq s \leq 1$  by defining

${}_s\Gamma = A - {}_sQ$ . It follows that  ${}_s\Gamma = 2A((1-s)\alpha + (s+\alpha)P)(I+P)^{-1}(1+\alpha)^{-1}$  is non-singular and  ${}_sP - \alpha = (I + s\alpha + (1-s)P)^{-1}s(1+\alpha)(P - \alpha)$  is nilpotent for the automorphism  ${}_sP = (A + {}_sQ)^{-1}(A - {}_sQ)$ . Hence, for any  $s$  with  $0 \leq s \leq 1$ , the Alexander polynomial  ${}_s\Gamma(t)$  associated to  ${}_s\Gamma$  does not vanish except  $t = \alpha$ , that is, the hermitian form  ${}_s l_\omega = x^* {}_s\Gamma_\omega y$  is non-degenerate unless  $\omega = \alpha$ . Therefore, if  $|\alpha| = 1$ ,  $\alpha \neq -1$  and  $\omega \neq \alpha$ , then  $\text{sign}(V_\alpha; {}_0 l_\omega) = \text{sign}(V_\alpha; l_\omega)$ . This follows from the perturbation invariance of the signature of non-degenerate hermitian forms. Note also that  ${}_0 l_+ = l_+$ . As a consequence, if  $\omega = \exp(i\varphi)$  and  $\alpha = \exp(i\theta)$  with  $-\pi < \varphi \neq \theta < \pi$ , then  $\text{sign}(V_\alpha; l_\omega) - \text{sign}(\text{Im } \omega) \text{sign}(\varphi - \theta) \text{sign}(V_\alpha; l_+) = \text{sign}(V_\alpha; {}_0 l_\omega) - \text{sign}(\text{Im } \omega) \text{sign}(\varphi - \theta) \text{sign}(V_\alpha; {}_0 l_+)$ ; the latter vanishes, because  ${}_0 P = \alpha I$ . If  $\omega$  is not a root of the Alexander polynomial, then  $V_\alpha = 0$  and this completes the proof for  $\alpha \neq -1$ . Remark also that  ${}_sQ$  are non-degenerate for  $0 \leq s \leq 1$ , then we get  $\text{sign}(V_\alpha; l_+) = \text{sign}(\text{Im } \alpha) \text{sign}(V_\alpha; i(-{}_0Q)) = \text{sign}(\text{Im } \alpha) \text{sign}(V_\alpha; -iQ)$ .

If  $\alpha = -1$ , we use the inverse Cayley transformation  $A = Q(I+P)(I-P)^{-1}$  and put  ${}_sA = sA$ . Then,  ${}_s\Gamma = {}_sA - Q$ ,  $0 \leq s \leq 1$ , are non-singular and so are  ${}_s l_\omega(x, y)$ . Note that  ${}_0 l_\omega(x, y) = \text{sign}(\text{Im } \omega) i l_-(x, y)$ . Therefore, we get  $\text{sign}(V_{-1}, l_\omega) = \text{sign}(\text{Im } \omega) \text{sign}(V_{-1}, i l_-)$ .

## § 2. Proof of Theorem 2.

In view of the theorem 1 and the remark, it is sufficient to prove  $\sigma_{(\alpha)} = \sigma_{(\bar{\alpha})}$  for any real bilinear form with  $\alpha = \exp(i\theta)$ ,  $0 < \theta < \pi$  and  $\sigma_{(-1+0i)} = 0$ . But this is also deduced from the theorem 1 as follows. Because  $\Gamma$  is a real matrix, the transpose of  $\Gamma_\omega$  is equal to  $\Gamma_{\bar{\omega}}$  and hence  $\tau_\omega = \text{sign}(\text{transpose of } \Gamma_\omega) = \tau_{\bar{\omega}}$ . Let  $\alpha_\pm$  denote  $\exp(i(\theta \pm \varepsilon))$  for a small positive number  $\varepsilon$ . Then, from the theorem 1, we get

$$\sigma_{(\alpha)} = \tau_{\alpha+} - \tau_{\alpha-} = \tau_{\beta+} - \tau_{\beta-} = \sigma_{(\bar{\alpha})}, \quad \text{where } \beta_\pm = \bar{\alpha}_\pm.$$

Therefore,  $\tau_\omega = \sum \sigma_\theta + (1/2)\sigma_\varphi + \text{sign}(\text{Im } \omega)\sigma_{(-1+0i)}$ . But  $\tau_\omega = \tau_{\bar{\omega}}$  implies  $\sigma_{(-1+0i)} = 0$  from that.

## § 3. Excluded cases.

We use the notation of the § 1. By decomposing  $V_\alpha$  into  $t$ -invariant subspaces, we may assume  $P$  is the triangular matrix of rank  $r$ :  $P_{i,i} = \alpha$ ,  $P_{i,i+1} = 1$  and otherwise  $P_{i,j} = 0$ . Then, the fact that  $P^*AP = A$  and  $\alpha\bar{\alpha} = 1$  implies that  $A$  is the triangular matrix:  $A_{i,j} = 0$  if  $i+j \leq r$ . We investigate the case  $\omega = \alpha$  and  $\alpha \neq -1$ . (The case  $\alpha = -1$  is treated in the same way by using  $Q$  instead of  $A$ ). Remember the matrix  $\Gamma_\alpha$  is  $AX$  with  $X = (1-\alpha)(I - \bar{\alpha}P)(I+P)^{-1}$ . The matrices  $X$  and hence  $AX$  are the strongly triangular matrices:  $X_{i,j} = 0$  if  $i \geq j$  and  $(AX)_{i,j} = 0$  if  $i+j \leq r+1$ . The non-degeneracy of  $\Gamma = A - Q = 2AP(I+P)^{-1}$

implies that  $\text{rank } A=r$  and  $\text{rank } AX=r-1$ . If  $r=\text{odd}$ , we have  $\text{sign}(AX)=0$  and (\*). (Note:  $|\text{sign } A|=1$  in the case  $r \geq 3$ ). If  $r=\text{even}$ , we have  $|\text{sign}(AX)|=1$ . So in this case (\*) does not hold.

If we note that  $\Gamma \oplus \Gamma^*$  may be transformed to a real matrix, we understand that (\*\*) has also counterexamples.

#### § 4. Signatures of algebraic links.

We shall give a criterion to calculate  $\sigma_\theta$  for the algebraic links of Fermat-Pham-Brieskorn type:

$$\{z_1^{a_1} + \dots + z_n^{a_n} = 0\} \cap S^{2n-1}.$$

The Seifert matrix with integral coefficients is described as  $\Gamma = (-1)^{n(n+1)/2} \Gamma(a_1) \oplus \dots \oplus \Gamma(a_n)$ , where  $\Gamma(a_\nu)$  denotes a triangular matrix of rank  $a_\nu - 1$  with  $\Gamma(a_\nu)_{i,j} = \delta_{i,j} - \delta_{i+1,j}$ ,  $1 \leq i, j \leq a_\nu - 1$  (cf. [7]). The intersection matrix and the monodromy matrix of the Milnor fiber are

$$-(\Gamma + (-1)^{n-1} \Gamma^*) \quad \text{and} \quad (-1)^n (\Gamma^*)^{-1} \Gamma$$

respectively. They have the same real bases (cf. [6]). It is enough to know the case when  $n=\text{odd}$ , because  $\Gamma$  becomes either  $\Gamma$  or  $-\Gamma$  after we add the term  $z_{n+1}^2$ . Now, for  $0 \leq \theta \leq \pi$ ,  $A_\theta$  denotes the finite set of integers,

$$A_\theta = \{(j_1, \dots, j_n); 1 \leq j_\nu \leq a_\nu - 1 \text{ and } \pi + 2\pi \sum (j_\nu / a_\nu) \equiv \theta \text{ or } -\theta \pmod{2\pi}\}.$$

PROPOSITION 3. Suppose  $n$  is odd. The partial signatures  $\sigma_\theta = \sigma_\theta^+ - \sigma_\theta^-$  and the nullity  $n$  of  $\Gamma + \Gamma^*$  are given as follows: If  $0 \leq \theta < \pi$ , then

$$\sigma_\theta^- = \text{number of } (A_\theta \cap \{0 < \sum (j_\nu / a_\nu) < 1 \pmod{2}\}),$$

$$\sigma_\theta^+ = \text{number of } (A_\theta \cap \{1 < \sum (j_\nu / a_\nu) < 2 \pmod{2}\})$$

and

$$n = \text{rank of } V_{-1} = \text{number of } A_\pi.$$

The signatures  $\tau_\omega$  are given by the sum formula in the theorem 2, because the monodromy is semi-simple. We shall give an outline of the proof of the proposition 3.

Let  $T(a)$  be the transformation matrix with  $T(a)_{i,j} = 1 - \xi^{ij}$  and  $\xi = \exp(2\pi \sqrt{-1}/a)$ . (The bases must be written as  $x_s = (1 - \xi^s) \sum \xi^{si} \omega^i$  ( $0 \leq i \leq a-1$ ) in the notation of [7] and changes to  $x_s = -\xi^s \sum \xi^{si} \omega^i$  in that of [5].) Then,  $T^*(a) \Gamma(a) T(a)$  is a diagonal matrix  $(a(1 - \xi^{-i}) \delta_{i,j})$ . Therefore, the transformed matrix  $T^* \Gamma T$  and the transformed automorphism  $T^{-1}(\Gamma^*)^{-1} \Gamma T$  by  $T = T(a_1) \oplus \dots \oplus T(a_n)$  are

$$((-1)^{n(n+1)/2} \prod a_\nu \prod (1 - \xi_\nu^{-i_\nu}) \prod \delta_{i_\nu, j_\nu}) \quad \text{and} \quad ((-1)^n \prod \xi_\nu^{i_\nu} \prod \delta_{i_\nu, j_\nu})$$

respectively. Since these are diagonal matrices, it is easy to deduce the

proposition by the same technique of the calculation of sign of the function  $f$  in the proof of the theorem 1 (cf. p. 12 of [5]).

As a final remark it is noticed that the result of Rokhlin [8] in the case  $M=CP^2$  has an elementary proof: Apply the direct calculation in this note for the algebraic link  $\{z_1^d+z_2^d=0\}\cap S^3$  to the inequality of Tristram [3] with respect to  $\tau_\omega$ ;  $\omega=-1$  if  $d=\text{even}$  and  $\omega=\exp(m\pi\sqrt{-1}/2m+1)$  if  $2m+1$  is an odd prime power which divides  $d$ .

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