WHITEHEAD TORSION

BY J. MILNOR

In 1935, Reidemeister, Franz and de Rham introduced the concept of "torsion" for certain finite simplicial complexes. For example let Xbe a finite complex whose fundamental group $\pi_1 X$ is cyclic of order m. We can identify $\pi_1 X$ with the group of covering transformations of the universal covering complex \hat{X} . If $\pi_1 X$ operates trivially on the rational homology $H_*(\hat{X}; \mathbf{Q})$, then the *torsion* of X is defined as a certain collection of elements in the algebraic number field $\mathbf{Q}[\exp(2\pi i/m)]$. This torsion is a kind of determinant which describes the way in which the simplexes of \hat{X} are fitted together with respect to the action of $\pi_1 X$. The actual definition will be given in §8. (See Franz [1935], de Rham [1950], Milnor [1961].)

In 1950, J. H. C. Whitehead defined the "torsion" of a homotopy equivalence between finite complexes. This is a direct generalization of the Reidemeister, Franz, and de Rham concept; but is a more delicate invariant. (See §7.) It has gradually been realized that the Whitehead torsion provides a key tool for the study of combinatorial or differentiable manifolds with nontrivial fundamental group. Closely related is the concept of "simple homotopy type" (Whitehead [1939], [1950]).

The Whitehead torsion is not defined as an algebraic number, but rather as an element of a certain commutative group $Wh(\pi_1 X)$ which depends on the fundamental group. For many years these "Whitehead groups" were completely impossible to compute, except in a very few special cases (Higman [1940]). But recent work by H. Bass and others has made these groups moderately accessible.

The first six chapters of this presentation will be concerned with the algebraic part of the theory, and the remaining six chapters with the geometric applications. There are two appendices: one to show the relationship of Whitehead groups to the work of Bass and Mennicke on congruence subgroups, and one to help motivate the notation K_1A which is used for the Whitehead group of a ring.

1. The Whitehead group K_1A of a ring. Let A be an associative ring with unit. The group of all nonsingular $n \times n$ matrices over A will be denoted by GL(n, A). Identifying each $M \in GL(n, A)$ with the matrix

$$\begin{pmatrix} M & 0 \\ 0 & 1 \end{pmatrix} \in \operatorname{GL}(n+1, A)$$

we obtain inclusions

$$\operatorname{GL}(1, A) \subset \operatorname{GL}(2, A) \subset \operatorname{GL}(3, A) \subset \cdots$$

The union is called the infinite general linear group GL(A).

A matrix is called *elementary* if it coincides with the identity matrix except for one off-diagonal element.

LEMMA 1.1 (J. H. C. WHITEHEAD). The subgroup $E(A) \subset GL(A)$ generated by all elementary matrices is precisely equal to the commutator subgroup of GL(A).

PROOF. Let aE_{ij} denote the matrix with entry a in the (i, j)th place and zeros elsewhere. The identity

$$(I + aE_{ij})(I + E_{jk})(I - aE_{ij})(I - E_{jk}) = (I + aE_{ik}),$$

for $i \neq j \neq k \neq i$, shows that each elementary matrix in GL(n, A) is a commutator, providing that $n \ge 3$.

Conversely the following three identities show that each commutator $XYX^{-1}Y^{-1}$ in GL(n, A) can be expressed as a product of elementary matrices within the larger group GL(2n, A).

(1)
$$\begin{pmatrix} XYX^{-1}Y^{-1} & 0\\ 0 & I \end{pmatrix} = \begin{pmatrix} X & 0\\ 0 & X^{-1} \end{pmatrix} \begin{pmatrix} Y & 0\\ 0 & Y^{-1} \end{pmatrix} \begin{pmatrix} (YX)^{-1} & 0\\ 0 & YX \end{pmatrix},$$

(2)
$$\binom{X \ 0}{0 \ X^{-1}} = \binom{I \ X}{0 \ I} \binom{I \ 0}{I - X^{-1} \ I} \binom{I \ -I}{0 \ I} \binom{I \ 0}{I - X \ I},$$

(3)
$$\begin{pmatrix} I & X \\ 0 & I \end{pmatrix} = \prod_{i=1}^{n} \prod_{j=n+1}^{2n} (I + x_{ij}E_{ij}).$$

This completes the proof.

It follows that E(A) is a normal subgroup of GL(A) with commutative quotient group. The quotient will be called the Whitehead group

$$K_1A = \operatorname{GL}(A)/E(A).$$

We will usually think of K_1A as an additive group.

Clearly K_1 is a covariant functor: that is, any ring homomorphism $A \rightarrow A'$ gives rise to a group homomorphism $K_1A \rightarrow K_1A'$.

If the ring A happens to be commutative then we can also consider the special linear group SL(A), consisting of all matrices in GL(A)with determinant 1. The quotient SL(A)/E(A) will be denoted by $SK_1(A)$, and called the *special Whitehead group*. Note the direct sum decomposition

$$K_1A \cong U(A) \oplus SK_1(A),$$

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where U(A) denotes the group of units in A. This follows immediately from the existence of the determinant homomorphism

det:
$$GL(A)/E(A) \rightarrow U(A)$$
,

together with the inclusion

$$U(A) = \operatorname{GL}(1, A) \subset \operatorname{GL}(A).$$

For many important rings the second summand $SK_1(A)$ is zero. In other words every matrix in GL(A) with determinant 1 can be reduced to the identity matrix by elementary row operations.¹

EXAMPLE 1.2. If F is a field, then $SK_1(F) = 0$. So the Whitehead group K_1F can be identified with the group

$$U(F) = F - \{0\}$$

of units.

EXAMPLE 1.3. For the ring Z of rational integers, $SK_1(Z) = 0$, so K_1Z is equal to the group

$$U(\mathbf{Z}) = \{\pm 1\}$$

with two elements. More generally, if A is any commutative ring which possesses a euclidean algorithm, then $SK_1A = 0$.

The proofs of these statements are well known.

EXAMPLE 1.4. If A has only finitely many maximal ideals, then $SK_1A = 0$. (See Appendix 1; as well as Bass, Lazard and Serre [1964, Lemme 1].)

EXAMPLE 1.5. If 0 is the ring of integers in a finite extension field of the rational numbers, then $SK_10=0$. (Bass and Milnor [to appear].)

More important for the applications is the following.

EXAMPLE 1.6. If $Z\Pi$ is the integral group ring of a finite abelian group, then $SK_1(Z\Pi) = 0$. This will be proved in a forthcoming paper by H. Bass. (Compare Appendix 1.)

Added in proof. Unfortunately, there seems to be serious difficulties with the proof of 1.6. If Π is cyclic of prime order, the statement is certainly correct, but the general case remains in doubt. Care should be taken with §§6.4, 6.7, 8.1, 12.8, and other places in which 1.6 is used.

To break the monotony, here are some examples with $SK_1 \neq 0$.

EXAMPLE 1.7. Let R[x, y] denote the Dedekind ring which is obtained from the real numbers R by adjoining two indeterminates, subject to the single relation

¹ An elementary row operation on a matrix means the operation of left multiplying by an elementary matrix.

$$x^2 + y^2 = 1.$$

Then the matrix

$$\begin{pmatrix} x & y \\ -y & x \end{pmatrix} \in SL(2, \mathbf{R}[x, y])$$

represents a nontrivial element of $SK_1R[x, y]$.

(See Appendix 2. More precisely it is possible to show that the group $SK_1R[x, y]$ is cyclic of order 2.)

EXAMPLE 1.8. Let $A = \mathbf{Z}(T \times T_{23})$ be the integral group ring of the cartesian product of an infinite cyclic group T and a cyclic group of order 23. Then $SK_1A \neq 0$.

This follows from Bass, Heller and Swan [1964], and will be discussed in Appendix 2. (In fact SK_1A is the direct sum of a cyclic group of order 3 and an unknown 23-primary group.)

Finally, here are some examples in which the ring A is noncommutative.

EXAMPLE 1.9. If F is a skew-field, and $U = F^*$ the group of units, then K_1F can be identified with the abelianized group U/[U, U]. The natural homomorphism

$$\operatorname{GL}(n, F) \to K_1 F$$

is just the "noncommutative determinant" of Dieudonné [1943]. (See also Artin [1957].)

LEMMA 1.10. Let $M_n(A)$ denote the ring of all $n \times n$ matrices over the ring A. Then

$$K_1M_n(A)\cong K_1A.$$

PROOF. Any $k \times k$ matrix with entries in $M_n(A)$ can be thought of as a $kn \times kn$ matrix with entries in A. In other words

$$\operatorname{GL}(k, M_n(A)) \cong \operatorname{GL}(kn, A).$$

Passing to the limit as $k \rightarrow \infty$, and then abelianizing, we obtain the required isomorphism

$$K_1M_n(A)\cong K_1A.$$

For one important class of rings the group K_1A has been studied by Bass [1964]. We will say that A is an order in a semisimple *Q*-algebra if the additive group of A is a free abelian group of finite rank; and if the associated algebra $Q \otimes A$ over the rational numbers is semisimple. For example the integral group ring ZII of any finite group II is an order in the semisimple algebra QII.

THEOREM 1.11 (BASS [1964]). If A is an order in a semisimple Q-algebra then K_1A is a finitely generated group of rank r-q, where q denotes the number of simple factors of the algebra $Q \otimes A$, and r denotes the number of simple factors in the corresponding real algebra $R \otimes A$.

As an example, let $A = \mathbf{Z}T_p$ be the integral group ring of a cyclic group T_p of prime order $p \ge 3$. Then it is easy to verify that

$$q = 2$$
, $r = \frac{1}{2}(p+1);$

so the Whitehead group

$$K_1(\mathbf{Z}T_p) = U(\mathbf{Z}T_p)$$

is a finitely generated abelian group of rank (p-3)/2. (Compare Higman [1940].) In particular, this group has positive rank, providing that $p \ge 5$.

We will pursue these ideas further in §6, and in the two appendices. The reader may prefer to skip immediately to §6.

2. Elementary constructions with free modules. The word "module" will always mean "finitely generated left *A*-module."

Following Whitehead, we impose the following mild restriction on the ring A: The free module of rank r over A should not be isomorphic to the free module of rank s if $r \neq s$. This restriction will always be satisfied, for example, if A can be mapped homomorphically into a commutative ring.

Before proceeding it will be important to make a slight modification of the Whitehead groups studied in §1. Let $[-1] \in K_1A$ denote the element of order 2 corresponding to the unit

$$(-1) \in \operatorname{GL}(1, A) \subset \operatorname{GL}(A).$$

DEFINITION. The quotient $K_1A/\{0, [-1]\}$ will be denoted by \overline{K}_1A , and called the *reduced*² Whitehead group of A.

Here are two important examples. For the integers Z the group $\overline{K}_1 Z$ is zero. For the real numbers R, $\overline{K}_1 R$ is isomorphic to the multiplicative group R^+ of positive reals. A specific isomorphism is given by the correspondence $(a_{ij}) \rightarrow |\det(a_{ij})|$.

The advantage of passing to this quotient is that two matrices which differ only by a permutation of the rows represent the same element of \overline{K}_1A . This follows, for example, from the fact that every permutation matrix represents the zero element of $\overline{K}_1Z \subset \overline{K}_1A$.

Let F be a free A-module and let $b = (b_1, \dots, b_k)$ and $c = (c_1, \dots, c_k)$ be two different bases for F. Setting $c_i = \sum a_{ij}b_j$ we obtain a nonsingular matrix (a_{ij}) with entries in A. The corresponding element of

² In some noncommutative cases it may happen that [-1]=0, so that $K_1A = \overline{K}_1A$.

the reduced Whitehead group \overline{K}_1A will be denoted by [c/b]. If [c/b]=0 then we will say that b is equivalent to c (briefly $b\sim c$). The identities

$$[d/c] + [c/d] = [d/b],$$

 $[b/b] = 0$

show that this is an equivalence relation.

EXAMPLES. For a free module of rank 2, the bases (b_1+ab_2, b_2) , (b_1, ab_1+b_2) , and (b_2, b_1) are all equivalent to (b_1, b_2) .

Next consider a short exact sequence

$$0 \to E \to F \to G \to 0$$

of free modules. Given bases $e = (e_1, \dots, e_k)$ for E and $g = (g_1, \dots, g_l)$ for G we can construct a basis e_g for F as follows. Lift each $g_i \in G$ to an element g'_i of F. Then

$$eg = (e_1, \cdots, e_k, g'_i, \cdots, g'_i)$$

is the required basis. Of course this basis eg depends on the choice of the g'_i . However the equivalence class of eg depends only on e and g.

(Throughout §2, the proofs are easy, and will be omitted.)

Note also the following identity. If \bar{e} and \bar{g} are alternative bases for the modules E and G respectively, then

(2.1)
$$[\bar{e}\bar{g}/eg] = [\bar{e}/e] + [\bar{g}/g].$$

The following reformulation will often be convenient. Suppose that we are given free modules

$$F_0 \subset F_1 \subset F_2$$

together with bases b_1 for the free quotient module F_1/F_0 and b_2 for the quotient module F_2/F_1 . Then we obtain a basis b_1b_2 for F_2/F_0 , using the exact sequence

$$0 \to F_1/F_0 \to F_2/F_0 \to F_2/F_1 \to 0.$$

(2.2) This construction is associative: Given modules

$$F_0 \subset F_1 \subset F_2 \subset F_3$$

and bases b_i for the (free) quotient modules F_i/F_{i-1} , the basis $(b_1b_2)b_3$ for F_3/F_0 is equivalent to the basis $b_1(b_2b_3)$.

More generally, given modules

$$F_0 \subset F_1 \subset \cdots \subset F_k$$

and given bases b_i for the quotients F_i/F_{i-1} , we obtain a basis $b_1b_2 \cdots b_k$ for F_k/F_0 which is well defined up to equivalence.

It will be convenient to represent situations such as this by lattice diagrams such as the following.



Each arrow represents an inclusion map. The letter associated with each arrow denotes a basis (or equivalence class of bases) for the corresponding quotient module.

Our construction is also commutative, in the following sense. Let E and F be submodules of G, and let E+F denote the smallest submodule containing both. Thus we obtain a lattice:



Suppose that $E/E \cap F \cong (E+F)/F$ is free with basis b and that $F/E \cap F \cong (E+F)/E$ is free with basis c. Using the left hand inclusions we form the basis bc for $(E+F)/E \cap F$, and using the right hand inclusions we form the basis cb. Then clearly

$$(2.3) bc \sim cb.$$

It is essential at this point that we are working in \overline{K}_1A rather than K_1A .

3. The torsion of a chain complex. Let $C_n \rightarrow C_{n-1} \rightarrow \cdots \rightarrow C_1 \rightarrow C_0$ be a chain complex of modules over the ring A such that each C_i is free with a preferred basis c_i , and each homology group $H_i(C)$ is free with a preferred basis h_i . (The case $H_i(C) = 0$ is of course not excluded. By definition, the zero module has a unique basis.) We wish to define the *torsion* $\tau(C) \in \overline{K_1}A$. Let B_i denote the image of the boundary homomorphism $\partial: C_{i+1} \rightarrow C_i$ and let Z_{i+1} denote its kernel. In order to simplify the discussion we will assume the following.

HYPOTHESIS. Each B_i is also a free module.

The more general situation in which this hypothesis is not satisfied will be put off until §4.

Choose a basis b_i for each B_i . Using the inclusions $0 \subseteq B_i \subseteq Z_i \subseteq C_i$ where $Z_i/B_i \cong H_i$, $C_i/Z_i \cong B_{i-1}$ we see that the bases b_i , h_i , b_{i-1} combine to yield a new basis $b_i h_i b_{i-1}$ for C_i . Now define $\tau(C)$ $= \sum (-1)^i [b_i h_i b_{i-1}/c_i]$. This does not depend on the choice of the b_i since, choosing different bases b_i , we have

$$\sum (-1)^{i} [\bar{b}_{i} h_{i} \bar{b}_{i-1} / c_{i}] = \sum (-1)^{i} ([\bar{b}_{i} h_{i} \bar{b}_{i-1} / c_{i}] + [\bar{b}_{i} / b_{i}] + [\bar{b}_{i-1} / b_{i-1}]),$$

where the last two terms sum up to zero.

Of course $\tau(C)$ does depend on the c_i and h_i .

Now consider a short exact sequence $0 \rightarrow C' \rightarrow C \rightarrow C'' \rightarrow 0$, in the category of chain complexes and chain mappings over A. We will assume that the modules C'_i , C_i , C''_i are free with preferred bases c'_i , c_i , c''_i which are *compatible*, in the sense that $c_i \sim c'_i c''_i$.

We wish to prove that $\tau(C)$ is equal to $\tau(C') + \tau(C'')$ plus a correction term which depends on the homology groups of the three chain complexes. First consider the special case where all three complexes are acyclic.

THEOREM 3.1. If the homology modules H_*C' , H_*C and H_*C'' are all zero, then $\tau(C) = \tau(C') + \tau(C'')$.

The proof will be based on the following lattice of submodules of C_i .



Each capital letter in the diagram represents a submodule of C_i . Note that $C'_i \cap B_i = B'_i$. The natural isomorphisms

$$C_i/(C_i' + B_i) \cong C_i''/B_i'' \cong B_{i-1}'',$$
$$C_i'/B_i' \cong B_{i-1}'$$

and

$$B_i/B'_i \cong (C'_i + B_i)/C'_i \cong B''_i$$

are easily verified.

Each lower case letter in the diagram represents a basis for the corresponding quotient module. We are assuming that the modules B'_i , B_i , B''_i are free. Let b'_i , b_i , b''_i be bases for these modules. Since we can choose any bases we like, we may as well choose b_i to be equal to $b'_i b''_i$. Hence, pushing to the left across the diagram, we have

$$b_{i}b_{i-1} = b'_{i}(b''_{i}b'_{i-1})b''_{i-1} \sim (b'_{i}b'_{i-1})(b''_{i}b'_{i-1}),$$

using §2.3. Therefore

$$\begin{aligned} \tau(C) &= \sum (-1)^{i} [b_{i}b_{i-1}/c_{i}] \\ &= \sum (-1)^{i} [(b_{i}^{\prime}b_{i-1}^{\prime})(b_{i}^{\prime\prime}b_{i-1}^{\prime\prime})/c_{i}^{\prime}c_{i}^{\prime\prime}] \\ &= \sum (-1)^{i} [(b_{i}^{\prime}b_{i-1}^{\prime}/c_{i}^{\prime}] + [b_{i}^{\prime\prime}b_{i-1}^{\prime}/c_{i}^{\prime\prime}]) \\ &= \tau(C^{\prime}) + \tau(C^{\prime\prime}); \end{aligned}$$

using §2.1. This completes the proof of Theorem 3.1.

More generally suppose that the homology groups of C', C, and C'' are not zero; but are free with preferred bases. Then the exact homology sequence

 $H'_n \to H_n \to H''_n \to H'_{n-1} \to \cdots \to H'_0 \to H_0 \to H''_0$

can be thought of as a free acyclic chain complex³ \mathcal{K} of dimension 3n+2. Hence the torsion $\tau \mathcal{K}$ is defined.

THEOREM 3.2. With these assumptions the torsion $\tau(C)$ is equal to $\tau(C') + \tau(C'') + \tau(\mathfrak{K})$.

PROOF. Let $X'_i \subset H'_i$ and $X_i \subset H_i$ be the kernels of the homomorphisms $H'_i \to H_i$ and $H_i \to H'_i$ respectively. Similarly let X'_i be the kernel of $H''_i \to H'_{i-1}$. Thus the sequences

$$0 \to X'_{i} \to H'_{i} \to X_{i} \longrightarrow 0$$
$$0 \to X_{i} \to H_{i} \to X''_{i} \to 0$$
$$0 \to X''_{i} \to H''_{i} \to X'_{i-1} \to 0$$

are exact. We are assuming that the modules X'_i , X_i and X''_i are free. Choose bases x'_i , x_i and x''_i respectively.

Consider the following lattice of submodules of C_i .



^{*} To be more precise, we define \mathcal{K} by setting $\mathcal{K}_{3i} = H_i''$, $\mathcal{K}_{3i+1} = H_i$, $\mathcal{K}_{3i+2} = H_i'$.

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The notation is mostly self explanatory. For example $\partial^{-1}(C'_{i-1})$ denotes the set of all $\gamma \in C_i$ such that $\partial(\gamma)$ belongs to C'_{i-1} (and hence to $C'_{i-1} \cap B_{i-1} = Z'_{i-1} \cap B_{i-1}$). The verification that this diagram exists as advertised will be left to the reader.

Again we have $c_i \sim c'_i c''_i$ by hypothesis. We are free to choose the bases b'_i , b_i , b''_i , so we may choose b_i equal to $b'_i x'_i b''_i$. By definition

$$\begin{aligned} \tau(5\mathcal{C}) &= \sum (-1)^{3i+2} [x_i' x_i/h_i'] \\ &+ \sum (-1)^{3i+1} [x_i x_i''/h_i] \\ &+ \sum (-1)^{3i} [x_i'' x_{i-1}'/h_i'']. \end{aligned}$$

Hence

$$\begin{aligned} \tau(C') & -\tau(C) & +\tau(C'') & +\tau(3C) \\ &= \sum (-1)^i ([b'_i h'_i b'_{i-1}/c'_i] - [b_i h_i b_{i-1}/c_i] + [b''_i h'_i b''_{i-1}/c''_i] \\ &+ [x'_i x_i/h'_i] - [x_i x''_i /h_i] + [x''_i x'_{i-1}/h''_i]). \end{aligned}$$

We must prove that this expression is zero. But, upon inspecting the expression, we see that it does not depend on the choice of h'_i , h_i and h'_i . Hence we may as well assume that

$$h'_i = x'_i x_i, \quad h_i = x_i x''_i, \quad h''_i = x''_i x'_{i-1}$$

so that $\tau(\mathcal{H}) = 0$.

Similarly, after substituting $c'_i c''_i$ for c_i , the expression does not depend on the choice of c'_i and c''_i . Hence we may as well assume that

$$c'_{i} = b'_{i} h'_{i} b'_{i-1}, \qquad c''_{i} = b''_{i} h''_{i} b''_{i-1}$$

so that $\tau(C') = \tau(C'') = 0$.

Making these assumptions, it only remains to verify that $\tau(C) = 0$. Pushing to the left across our diagram, we have the following equivalences.

$$b_{i}h_{i}b_{i-1} = b'_{i}x'_{i}(b''_{i}x_{i})(x''_{i}b'_{i-1})x'_{i-1}b'_{i-1}$$

$$\sim b'_{i}x'_{i}x_{i}(b''_{i}b'_{i-1})x''_{i}x'_{i-1}b'_{i-1} \qquad \text{by 2.3}$$

$$\sim b'_{i}(x'_{i}x_{i})b'_{i-1}b''_{i}(x''_{i}x'_{i-1})b''_{i-1} \qquad \text{by 2.3}$$

$$= (b'_{i}h'_{i}b'_{i-1})(b''_{i}h''_{i}b''_{i-1})$$

$$= c_i' c_i'' \sim c_i.$$

Therefore

$$\tau(C) = \sum (-1)^{i} [b_{i}h_{i}b_{i-1}/c_{i}]$$

is equal to zero. This completes the proof.

4. Stably free modules. A module M over A will be called *stably* free if the direct sum of M with some free module is free. (Recall that all modules are to be finitely generated.) If $M \oplus F \cong F'$ then the difference between the rank of F' and the rank of F will be called the rank r of M.

LEMMA 4.1. Consider a short exact sequence $0 \rightarrow X \rightarrow Y \rightarrow Z \rightarrow 0$ of A-modules. If Y and Z are stably free, then X is also stably free.

PROOF. Since Z is projective the sequence splits; so that Y is isomorphic to $X \oplus Z$. Thus if $Z \oplus F \cong F'$ and $Y \oplus F \cong F''$, where F, F', F'' are free, it follows that $X \oplus F' \cong F''$.

Now consider a free chain complex

 $C_n \to C_{n-1} \to \cdots \to C_0$

over A, and assume that the homology modules $H_i = H_i(C)$ are also free. Using the exact sequences

$$0 \to Z_i \to C_i \to B_{i-1} \to 0$$
$$0 \to B_i \to Z_i \to H_i \to 0$$

it follows by induction that all of the modules Z_i and B_i are stably free.

We will show that the constructions of §2 can be carried out using stably free modules in place of free modules. It will then follow easily that all of the constructions and proofs of §3 can be carried out without the extra hypothesis that the B_i (and X_i) are free.

Let F_i denote a standard free module of rank i, with standard basis f_1, \dots, f_i . We may think of F_i as the submodule of F_{i+1} generated by the first i basis elements.

DEFINITION. An s-basis b for a stably free module M is a basis (b_1, \dots, b_{r+t}) for some direct sum $M \oplus F_t$. Here t can be any non-negative integer.

Given two s-bases $b = (b_1, \dots, b_{r+t})$ and $c = (c_1, \dots, c_{r+u})$ for M, the symbol

$$[c/b] \in \overline{K}_1 A$$

is defined as follows. Choose an integer $v \ge Max(t,u)$. Extend (b_1, \dots, b_{r+i}) to a basis for $M \oplus F_v$ by setting

$$b_{r+i} = 0 \oplus f_i, \qquad i \ge t+1.$$

Similarly extend (c_1, \dots, c_{r+u}) to a basis for $M \oplus F_v$ by setting

$$c_{r+i} = 0 \oplus f_i, \quad i \ge u+1.$$

Now $c_i = \sum a_{ij}b_j$ where the matrix $(a_{ij}) \in GL(r+v, A)$ represents the

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required element $[c/b] \in \overline{K}_1 A$. Clearly this construction does not depend on the choice of v. As in §2, we write $b \sim c$ if [c/b] = 0. The identities

$$\begin{bmatrix} d/b \end{bmatrix} = \begin{bmatrix} d/c \end{bmatrix} + \begin{bmatrix} c/b \end{bmatrix}$$
$$\begin{bmatrix} b/b \end{bmatrix} = 0$$

are again satisfied.

Next consider a short exact sequence

$$0 \to X \to Y \to Z \to 0.$$

Given s-bases x for X and z for Z we can construct an s-basis xz for Y as follows. Suppose that x is a basis for $X \oplus F_t$ and that z is a basis for $Z \oplus F_u$. Consider the exact sequence

$$0 \to F_t \xrightarrow{\alpha} F_{t+u} \xrightarrow{\beta} F_u \to 0$$

where α denotes the inclusion homomorphism, and

$$\beta(f_i) = \begin{cases} 0 & \text{for } i \leq t, \\ f_{i-t} & \text{for } i > t. \end{cases}$$

Forming the direct sum

$$0 \oplus 0 \to X \oplus F_t \to Y \oplus F_{t+u} \to Z \oplus F_u \to 0 \oplus 0,$$

the bases x and z combine to yield a basis xz for $Y \oplus F_{t+u}$, which is well defined up to equivalence. This is the required construction.

LEMMA 4.2. This composition operation for s-basis is "associative" and "commutative" in the sense of §2. Furthermore, if \bar{x} and \bar{z} are alternative s-bases for X and Z respectively, then

$$[\bar{x}\bar{z}/xz] = [\bar{x}/x] + [\bar{z}/z],$$

just as in §2.

The proof, which is rather dull, will be omitted.

It is now possible to revise §3 by substituting "stably free" and "s-basis" wherever the words "free" and "basis" occur. With these changes, all of the arguments still go through; but no extra hypothesis is needed to guarantee that the modules B_i and X_i are stably free.

5. An algebraic "subdivision" theorem. This section will prove an algebraic theorem which will enable us later to handle the geometric operations of subdividing a complex, or triangulating a smooth manifold.

The following situation is frequently encountered in homology theory. Let C be a chain complex and let

$$C^{(0)} \subset C^{(1)} \subset \cdots \subset C^{(n)} = C$$

be a "filtration" of C by subcomplexes such that the following is satisfied. We set $C^{(-1)} = 0$.

HYPOTHESIS. The homology group $H_i(C^{(\lambda)}/C^{(\lambda-1)})$ is zero for $i \neq \lambda$. Then we can define a new chain complex \overline{C} by setting

$$\overline{C}_{\lambda} = H_{\lambda}(C^{(\lambda)}/C^{(\lambda-1)}).$$

The boundary homomorphism $\partial: \overline{C}_{\lambda} \to \overline{C}_{\lambda-1}$ is to be obtained from the exact sequence of the triple $C^{(\lambda)}$, $C^{(\lambda-1)}$, $C^{(\lambda-2)}$. The following is well known.

LEMMA 5.1. The homology groups $H_i\overline{C}$ are canonically isomorphic to the groups H_iC .

For completeness, here is a proof. The fact that

 $H_i C^{(\lambda)} / C^{(\mu)} = 0 \text{ for } i > \lambda \text{ or } i \leq \mu$

is proved by an easy induction on $\lambda - \mu$. Hence

$$H_i C \cong H_i C^{(i+1)} \cong H_i (C^{(i+1)} / C^{(i-2)}).$$

Now consider the diagram



where the vertical line comes from the homology exact sequence of the triple $C^{(\lambda)}$, $C^{(\lambda-1)}$, $C^{(\lambda-2)}$; and the horizontal line from the triple $C^{(\lambda+1)}$, $C^{(\lambda)}$, $C^{(\lambda-2)}$. Inspection shows that the cycle group \overline{Z}_{λ} of \overline{C} can be identified with $H_{\lambda}C^{(\lambda)}/C^{(\lambda-2)}$. Hence

$$H_{\lambda}\overline{C} = \overline{Z}_{\lambda}/\overline{B}_{\lambda} \cong H_{\lambda}C^{(\lambda+1)}/C^{(\lambda-2)} = H_{\lambda}C,$$

which completes the proof.

We wish to examine the behavior of the torsion in a filtered chain complex of this type.

FURTHER HYPOTHESES. Each $C_i^{(\lambda)}/C_i^{(\lambda-1)}$ should be free with preferred basis c_i^{λ} ; so that C_i is free with basis

$$c_i = c_i c_i c_i^{0 \ 1 \ 2} \cdots c_i^n.$$

Also each $\overline{C}_{\lambda} = H_{\lambda}C^{(\lambda)}/C^{(\lambda-1)}$ should be free with preferred basis \overline{c}_{λ} ; and the modules

$$H_i C \cong H_i \overline{C}$$

should be free with preferred basis h_i . Finally C should be finitely generated so that the torsions τC and $\tau \overline{C}$ are defined.

With these hypotheses we will prove:

ALGEBRAIC SUBDIVISION THEOREM 5.2. If each quotient complex $C^{(k)}/C^{(k-1)}$ has torsion $\tau(C^{(k)}/C^{(k-1)})$ equal to zero, then $\tau(C) = \tau(\overline{C})$.

PROOF. Let $\overline{C}^{(k)}$ denote the truncated chain complex

$$\cdots 0 \to \overline{C}_k \to \overline{C}_{k-1} \to \cdots \to \overline{C}_0 \to 0$$

which is obtained from \overline{C} by chopping off the chain modules of degree >k. We wish to look at the torsion $\tau(\overline{C}^{(k)})$. It follows from 5.1 that $H_i\overline{C}^{(k)}\cong H_iC^{(k)}$. Note that $H_i\overline{C}^{(k)}\cong H_iC^{(k)}$ is zero for i > k; and is isomorphic to H_iC , with preferred basis h_i , for i < k. In order for the torsion to be defined we must also choose a preferred basis (or at least s-basis) for $H_k\overline{C}^{(k)}\cong H_kC^{(k)}$. But clearly $H_k\overline{C}^{(k)}$ can be identified with the cycle group \overline{Z}_k of \overline{C} , which is known to be stably free. Hence *some* preferred s-basis \overline{z}_k can be chosen. It then follows that $\tau(\overline{C}^{(k)})$ and $\tau(C^{(k)})$ are defined.

We will prove by induction on k that

$$\tau(C^{(k)}) = \tau(\overline{C}^{(k)}).$$

Taking k = n, this will complete the proof.

Let \mathcal{K} denote the homology exact sequence of the pair $(\overline{C}^{(k)}, \overline{C}^{(k-1)})$; or equivalently of the pair $(C^{(k)}, C^{(k-1)})$. Then according to §3 we have

$$\begin{aligned} \tau \overline{C}^{(k)} &= \tau \overline{C}^{(k-1)} + \tau \overline{C}^{(k)} / \overline{C}^{(k-1)} + \tau 3\mathfrak{C}, \\ \tau C^{(k)} &= \tau C^{(k-1)} + \tau C^{(k)} / C^{(k-1)} + \tau 3\mathfrak{C}. \end{aligned}$$

But $\tau \overline{C}^{(k-1)} = \tau C^{(k-1)}$ by induction, and $\tau C^{(k)}/C^{(k-1)} = 0$ by hypothesis. Since $\tau \overline{C}^{(k)}/\overline{C}^{(k-1)}$ is trivially zero, it follows that $\tau \overline{C}^{(k)} = \tau C^{(k)}$. This completes the proof.

6. The Whitehead group $Wh(\Pi)$ of a group. Let Π denote a multiplicative group and $Z\Pi$ the corresponding integral group ring. Then clearly Π itself is contained in the group of units

$$U(\mathbf{Z}\Pi) = \operatorname{GL}(1, \mathbf{Z}\Pi) \subset \operatorname{GL}(\mathbf{Z}\Pi).$$

Hence there are natural homomorphisms⁴

 $\Pi \to K_1(\mathbb{Z}\Pi) \to \overline{K}_1(\mathbb{Z}\Pi).$

DEFINITION. The cokernel

 $\overline{K}_1(\mathbf{Z}\Pi)/\text{image}(\Pi)$

is called the *Whitehead group* $Wh(\Pi)$. This construction can be described by the exact sequence

 $0 \to \Pi / [\Pi, \Pi] \to \overline{K}_1(\mathbf{Z}\Pi) \to \mathrm{Wh}(\Pi) \to 0.$

Clearly Wh(II) is a covariant functor of II. In other words, any homomorphism $f: \Pi_1 \rightarrow \Pi_2$ induces a homomorphism $f_*: Wh(\Pi_1) \rightarrow Wh(\Pi_2)$.

LEMMA 6.1. If $f: \Pi \rightarrow \Pi$ is an inner automorphism, then $f_*: Wh(\Pi) \rightarrow Wh(\Pi)$ is the identity.

PROOF. Let $f(\sigma) = \phi \sigma \phi^{-1}$ for each $\sigma \in \Pi$. The corresponding automorphism of $GL(n, \mathbb{Z}\Pi)$ is clearly given by

	(φ)	ſΦ)	1
$(a_{ij}) \mapsto$		•	(a_{ij})	•		•
	l	φ			ϕ	

Passing to the abelian group $K_1 \mathbb{Z}\Pi$, or to Wh(II), we therefore obtain the identity automorphism.

DEFINITIONS. If $a = \sum n_i \sigma_i$ is an element of **Z**II (with $n_i \in \mathbf{Z}$, $\sigma_i \in \Pi$) then the element $\sum n_i \sigma_i^{-1}$ is called the *conjugate* of a, and will be denoted briefly by \bar{a} . This conjugation operation is an *anti-automorphism* of the group ring. That is the conjugate of a+b is $\bar{a}+\bar{b}$ and

$$\overline{ab} = \overline{b}\overline{a}.$$

A corresponding anti-automorphism of the general linear group $GL(\mathbb{Z}\Pi)$ is obtained by sending each matrix (a_{ij}) into its conjugate transpose (\bar{a}_{ji}) . Passing to the abelianized group $K_1\mathbb{Z}\Pi$ this gives rise to an automorphism. Hence one obtains an automorphism of Wh(U). The image of an element $\omega \in Wh(\Pi)$ will be denoted by the symbol $\bar{\omega}$, and called the *conjugate* of ω .

Miscellaneous quoted theorems. If Π is infinite cyclic, or is finite of order 2, 3 or 4 then Higman [1940] proved that Wh(Π) is zero. Bass' Heller and Swan [1964] have shown that the Whitehead group of any free abelian group is zero. Stallings [1965₁] and Gersten [1965₁] have

⁴ Here $\overline{K}_1 A = K_1 A / \{0, [-1]\}$, as in §2.

shown that the Whitehead group of any free group is zero. In fact the Whitehead group of a free product is given by

$$Wh(\Pi * \Pi') = Wh(\Pi) \oplus Wh(\Pi').$$

(There is no corresponding formula for the Whitehead group of a cartesian product. For example $Wh(T_3)=0$ and $Wh(T_4)=0$, but $Wh(T_3 \times T_4) \cong \mathbb{Z}$; where T_m denotes the cyclic group of order m.)

If II is finite then Bass [1964] has shown that Wh(II) is finitely generated. In fact, more precisely:

THEOREM 6.2 (BASS). If Π is finite then Wh(Π) is a finitely generated abelian group of rank r-q, where r is the number of irreducible real representations of Π , and q is the number of irreducible rational representations.

(This is a special case of §1.11.) These numbers can be described quite explicitly as follows: q is the number of conjugate classes of cyclic subgroups⁵ of Π , and r is the number of conjugate classes of unordered pairs $\{\sigma, \sigma^{-1}\}$. Hence for Π finite we have:

COROLLARY 6.3. The Whitehead group Wh(II) of a finite group is itself finite if and only if, for every two elements σ , $\tau \in \Pi$ which generate the same cyclic subgroup, either σ is conjugate to τ or σ^{-1} is conjugate to τ .

As an example, the symmetric group S_n consisting of all permutations of *n* elements satisfies this condition. (In fact it is true that every complex representation of S_n is actually rational.) Hence $Wh(S_n)$ is finite. I do not know whether or not $Wh(S_n)$ is zero.

Now suppose that Π is finite abelian. Then, according to §1.6 the group $K_1Z\Pi$ is isomorphic to the group $U \subset Z\Pi$ of units in $Z\Pi$. (See also Appendix 1.) But according to Higman the only elements of finite order in U are the group elements and their negatives. Hence:

THEOREM 6.4 (BASS). If II is finite abelian then Wh(II) is a free abelian group of rank r-q.

COROLLARY 6.5. The Whitehead group $Wh(\Pi)$ of a finite abelian group Π is zero if and only if the group Π has exponent 1, 2, 3, 4, or 6.

For the cyclic groups of order 1, 2, 3, 4 and 6 are the only ones which have the property that any two generators are equal up to sign.

Here is a simple example worked out in more detail.

EXAMPLE 6.6. Let T_5 be cyclic of order 5 with generator t. Then Wh(T_5) is infinite cyclic; and the unit

⁵ In the abelian case $q = \sum \operatorname{order}(\Pi \otimes Z_m)/m$, summed over all *m* dividing order(Π).

$$u=t+t^{-1}-1\in ZT_5$$

represents a generator.6

(In fact the identity

$$(t + t^{-1} - 1)(t^2 + t^{-2} - 1) = 1$$

shows that u is a unit; and the homomorphism

$$t \mapsto \exp(2\pi i/5) = \xi,$$

 $u \mapsto \xi + \xi^{-1} - 1 = 2\cos 72^\circ - 1$

from ZT_5 to the complex numbers can be used to show that no power of u is equal to 1. The rest of the argument is much more difficult.)

REMARK. This unit $u \in \mathbb{Z}T_5$ is clearly self-conjugate. It is interesting to note that the automorphism $t \to t^2$ of T_5 carries u to u^{-1} . If we embed T_5 in the group G of order 20 in which t is conjugate to t^2 , this implies that the unit u represents an element of order ≤ 2 in the finite group Wh(G). I do not know whether or not Wh(G) is zero.

Here is a more general statement.

LEMMA 6.7. If Π is finite abelian, then every element of Wh(Π) is self-conjugate.

PROOF. If u is a unit of $\mathbb{Z}\Pi$, it is sufficient to show that \overline{u}/u is an element of finite order in the group of units. The rational group ring $\mathbb{Q}\Pi$ is isomorphic to a cartesian product $F_1 \times \cdots \times F_r$ of cyclotomic number fields. Note that the conjugation operation in $\mathbb{Q}\Pi$ corresponds to the usual complex conjugation operation in each F_i . Let E_i be the maximal real subfield of F_i . It follows easily from the Dirichlet unit theorem that for every unit v in the ring of integers of F_i , there exists a power v^k , k > 0, which belongs to the subfield E_i . Therefore some power u^k of

$$u \in \mathbf{Z} \Pi \subset F_1 \times \cdots \times F_r$$

must belong to the invariant subring $E_1 \times \cdots \times E_r$. This implies that u^k is self-conjugate, and hence that $(\bar{u}/u)^k = 1$; as was to be proved.

Bass has also proved a functorial version of Theorem 6.2. [To appear]. Two consequences are striking:

THEOREM 6.8. Let Γ range over all cyclic subgroups of the finite group II. Then the images

⁶ This was proved by Kaplansky (unpublished), before Bass's more general results were obtained.

$$i_*Wh(\Gamma) \subset Wh(\Pi)$$

together generate a subgroup of finite index in $Wh(\Pi)$.

Consider next an orthogonal representation $\Pi \rightarrow O(n)$ of our finite group Π . This representation gives rise to a ring homomorphism

$$h\colon \mathbf{Z}\Pi\to M_n(\mathbf{R})$$

and hence to an induced group homomorphism

$$h_*: \overline{K}_1(\mathbb{Z}\Pi) \to \overline{K}_1M_n(\mathbb{R}) \cong \mathbb{R}^+.$$

(Compare §1.10.) Since the group R^+ has no elements of finite order, there is clearly a corresponding homomorphism

$$\mathrm{Wh}(\Pi) \rightarrow \mathbb{R}^+$$

which will also be denoted by h_* .

THEOREM 6.9. An element $\omega \in Wh(\Pi)$ has finite order if and only if $h_*(\omega) = 1$ for every irreducible orthogonal representation h of the finite group Π .

This follows easily from Bass [to appear].

COROLLARY 6.10. For any finite Π and any $\omega \in Wh(\Pi)$, the difference $\bar{\omega} - \omega$ is an element of finite order in Wh(Π).

PROOF. This follows immediately from 6.7 and 6.8. Alternatively it follows easily from 6.9, making use of the fact that the determinant of a real matrix is equal to the determinant of its transpose.

7. Torsion for CW-complexes. First consider the following situation. Let (K, L) be a pair consisting of a finite, connected CWcomplex⁷ K, and a subcomplex L which is a deformation retract of K. The fundamental group $\pi_1(K)$ will be denoted briefly by II. (Of course $\pi_1 L \cong \pi_1 K$.) The Whitehead torsion

$$\tau(K, L) \in \mathrm{Wh}(\mathrm{II})$$

can then be defined as follows.

For any pair (X, Y) of CW-complexes the associated chain complex C(X, Y) is defined by setting

$$C_p(X, Y) = H_p(|X^p \cup Y|, |X^{p-1} \cup Y|),$$

where H denotes singular homology with integer coefficients, and where $|X^{p}|$ denotes the underlying topological space of the *p*-skele-

[May

⁷ See Whitehead [1949]. The reader may substitute "simplicial complex" for "CW-complex" and "simplex" for "cell" if he prefers.

ton of X; i.e., the union of all cells of dimension $\leq p$. This pth chain group is free abelian with one generator for each p-cell of X - Y. Note that the homology group $H_pC(X, Y)$ of this chain complex is canonically isomorphic to the singular group $H_p(|X|, |Y|)$. (Compare §5.1.) These mutually isomorphic groups will be denoted briefly by $H_p(X, Y)$.

Now consider the universal covering complexes $\hat{K} \supset \hat{L}$ of K and L. The fundamental group II will be identified with the group of covering transformations, so that each $\sigma \in \Pi$ determines a mapping

$$\sigma\colon (\hat{K},\,\hat{L})\to(\hat{K},\,\hat{L}).$$

Note that σ is *cellular*. (That is it carries the *p*-skeleton into the *p*-skeleton for each *p*.) Hence each $\sigma \in \Pi$ determines a chain map

$$\sigma_{\#}: C(\hat{K}, \hat{L}) \to C(\hat{K}, \hat{L}).$$

This action makes each chain group $C_p(\hat{K}, \hat{L})$ into a module over the integral group ring ZII. Clearly the resulting chain module is ZII-free with one generator for each *p*-cell of K-L. Since K is finite it follows that $C(\hat{K}, \hat{L})$ is finitely generated over ZII.

Thus we obtain a free chain complex

$$C_n(\hat{K}, \hat{L}) \to C_{n-1}(\hat{K}, \hat{L}) \to \cdots \to C_0(\hat{K}, L)$$

over **ZII**. The homology groups $H_i(\hat{K}, \hat{L})$ of this complex are zero since $|\hat{L}|$ is a deformation retract of $|\hat{K}|$.

If we were given a preferred basis c_p for each module $C_p(\hat{K}, \hat{L})$ then the torsion

$$\tau C(\widehat{K}, \widehat{L}) \in \overline{K}_1(\mathbb{Z}\Pi)$$

would be defined, as in §3. But the geometry of the situation determines a class of preferred bases, as follows. Let e_1, \dots, e_{α} denote the p-cells of K-L. For each e_i choose a representative cell \hat{e}_i of \hat{K} lying over e_i . Furthermore choose an orientation, so that \hat{e}_i determines a basis element of $C_p(\hat{K}, \hat{L})$, which we may also denote by \hat{e}_i . Then $c_p = (\hat{e}_1, \dots, \hat{e}_{\alpha})$ is the required basis for $C_p(\hat{K}, \hat{L})$.

Using these bases, the torsion $\tau C(\hat{K}, \hat{L})$ is apparently defined as an element of $\overline{K}_1(\mathbb{Z}\Pi)$. However we have made an arbitrary choice of the representative cells \hat{e}_i ; which leads to a certain arbitrariness in the resulting torsion. To eliminate the indeterminacy it is necessary to pass to the quotient group

$$\mathrm{Wh}(\Pi) = \overline{K}_1(\boldsymbol{Z}\Pi)/\mathrm{image}(\Pi)$$

which was studied in §6.

DEFINITION. The image of $\tau C(\hat{K}, \hat{L})$ in the quotient group Wh(II) is called the *Whitehead torsion* $\tau(K, L)$.

To justify this definition we must prove that $\tau(K, L)$ does not de-

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pend on the choice of \hat{e}_i . But if \hat{e}_i is replaced by a different representative cell $\pm \sigma_{\#}\hat{e}_i$ then a straightforward verification shows that $\tau C(\hat{K}, \hat{L})$ is replaced by

$$\tau C(\hat{K}, \hat{L}) - (-1)^p[\sigma] \in \overline{K}_1(\mathbb{Z}\Pi).$$

Thus the difference $\pm [\sigma]$ belongs to image (II), and is annihilated when we pass to the quotient group Wh(II). This completes the proof.

REMARK 1. In making use of the group $Wh(\Pi) = Wh(\pi_1 K)$ we never need to worry about base points, since any inner automorphism of Π will induce the identity automorphism of $Wh(\Pi)$.

REMARK 2. Of course we can generalize the definition. Instead of assuming that L is a deformation retract of K it is sufficient to assume that $H_*(\hat{K}, \hat{L})$ is free over ZII with a preferred basis. Here \hat{K} denotes the universal covering of K; and \hat{L} denotes the appropriate subcomplex. As group II we must take $\pi_1 K$, rather than $\pi_1 L$. More generally II might be the group of covering transformations for any regular covering of K. With a little more effort one could even define a sharper invariant using the group $\pi_1(K-L)$ in place of $\pi_1(K)$. (Compare 7.2.)

FUNDAMENTAL UNSOLVED PROBLEM. We would like to assert that the torsion $\tau(K, L)$ is a topological invariant of the pair (|K|, |L|), i.e., that it does not depend on the cell structure. However no one has been able to prove this, or to produce a counterexample. (Compare Milnor [1961].) The best result that one has is Whitehead's theorem that τ is invariant under subdivision:

DEFINITION. A second CW-complex X is a subdivision of K if the underlying space |X| is equal to |K|, and if each open cell of X is contained in a (possibly higher dimensional) open cell of K, so that the identity map $K \rightarrow X$ is cellular. (Compare Figure 1.) Similarly the pair (X, Y) is a subdivision of the pair (K, L) if X is a subdivision of K and Y is a subdivision of L.

COMBINATORIAL INVARIANCE THEOREM 7.1. The torsion $\tau(K, L)$ is invariant under subdivision of the pair (K, L).



FIGURE 1. Subdivision of a CW-complex.

Our proof will depend on the machinery set up in §5. (For a different proof see Whitehead [1950], Milnor [1961].) The geometrical kernel of the proof is contained in the following.

LEMMA 7.2. Suppose that each component of K-L is simply connected (where L is a deformation retract of K). Then $\tau(K, L) = 0$.

PROOF. First suppose that K-L has a single component Γ . Choose a representative component $\hat{\Gamma}$ of $\hat{K}-\hat{L}$. Clearly $\hat{\Gamma}$ projects homeomorphically onto Γ .



FIGURE 2. Judicious choice of representative cells in \hat{K} .

For each cell e of K-L choose the representative cell \hat{e} as the unique cell in $\hat{\Gamma}$ which lies over e. (Compare Figure 2.) Now notice that no representative cell \hat{e}^k of $\hat{K} - \hat{L}$ can be incident to a proper translate $\sigma \hat{e}^{k-1}$, $\sigma \neq 1$, of a representative cell. For $\sigma \hat{e}^{k-1}$ must be contained in a component $\sigma \hat{\Gamma}$ which is disjoint from $\hat{\Gamma}$. This means that the boundary $\partial \hat{e}^k$ can be expressed as a linear combination of representative k-1 cells with coefficients which are integers (rather than group ring elements). Thus in computing the torsion of the complex $C(\hat{K}, \hat{L})$ we need only work with the subring $Z \subset Z\Pi$. It follows that the torsion of $C(\hat{K}, \hat{L})$ belongs to the subgroup

$$\overline{K}_1 Z = 0 \subset \overline{K}_1 (Z \Pi).$$

Therefore $\tau(K, L) = 0$.

If K-L has several components the proof is essentially the same. It is only necessary to choose a representative component $\hat{\Gamma}_i$ lying over each component Γ_i of K-L, and to choose representative cells $\hat{e} \subset \hat{\Gamma}_i$ as before.

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More generally suppose that L is not a deformation retract of K.

LEMMA 7.3. Suppose that $H_*(\hat{K}, \hat{L})$ is not zero, but is ZII-free with preferred basis, where each basis element can be represented by a cycle lying in a single component of $\hat{K} - \hat{L}$. Assume as before that each component of K-L is simply connected. Then $\tau(K, L) = 0$.

PROOF. Choose representative components $\hat{\Gamma}$ and representative cells \hat{e} as before. Replace each preferred basis element $b \in H_i(\hat{K}, \hat{L})$ by the translate σb , chosen so that σb is represented by a cycle lying within one of the representative components $\hat{\Gamma}$. Clearly this change of basis will not alter the torsion.

Again we see that $\tau(K, L)$ can be computed within the subring $Z \subset Z\Pi$, and hence that $\tau(K, L) = 0$.

PROOF OF THEOREM 7.1. Let $C = C(\hat{X}, \hat{Y})$ be the chain complex associated with the subdivided pair; so that

 $\tau(C) \mapsto \tau(X, Y) \in \mathrm{Wh}(\mathrm{II}).$

We will define a sequence of subcomplexes

$$C^{(0)} \subset C^{(1)} \subset C^{(2)} \subset \cdots \subset C^{(n)} = C$$

so that the associated chain group

$$\overline{C}_{\lambda} = H_{\lambda}(C^{(\lambda)}/C^{(\lambda-1)})$$

can be identified with $C_{\lambda}(\hat{K}, \hat{L})$. In particular the torsion $\tau(\overline{C}) \in \overline{K}_1(\mathbb{Z}\Pi)$ will correspond to $\tau(K, L) \in Wh(\Pi)$. We will then show that the hypotheses of §5.2 are all satisfied. Thus Theorem 5.2 will imply that

$$\tau(C)=\tau(\overline{C});$$

and therefore that

$$\tau(X, Y) = \tau(K, L).$$

The construction follows. Let X(p) denote the subcomplex of X consisting of all cells of X which are contained in the subspace $|K^p \cup L| \subset |X|$. Let $\hat{X}(p)$ denote the corresponding subcomplex of \hat{X} . Finally, let

$$C^{(p)} = C(\hat{X}(p), \hat{Y}).$$

Then

$$H_i(C^{(p)}/C^{(p-1)}) = H_i(\hat{X}(p), \hat{X}(p-1))$$

$$\cong H_i(\left| \hat{K}^p \cup \hat{L} \right|, \left| \hat{K}^{p-1} \cup \hat{L} \right|).$$

Clearly this group is zero for $i \neq p$, and is equal to $C_p(\hat{K}, \hat{L})$ for i = p. Hence the associated complex \overline{C} can be identified with $C(\hat{K}, \hat{L})$.

In order to apply §5.2, we must verify that the torsion

$$\tau(C^{(p)}/C^{(p-1)}) = \tau C(\hat{X}(p), \, \hat{X}(p-1))$$

is zero. But this follows from 7.3 since:

(1) each component of |X(p)| - |X(p-1)| is a *p*-cell of the complex K, and therefore is simply connected; and

(2) each preferred generator for $H_p(\hat{X}(p), \hat{X}(p-1)) \cong C_p(\hat{K}, \hat{L})$ is represented by a cycle which lies in a single component of $|\hat{X}(p)| - |\hat{X}(p-1)|$.

Hence we can apply 5.2, and conclude that $\tau(X, Y) = \tau(K, L)$. This completes the proof of the Combinatorial Invariance Theorem.

To conclude this section we will discuss the torsion of a mapping cylinder, and the concept of "simple homotopy equivalence." First let us state an obvious consequence of §3.1.

LEMMA 7.4. If $K \supset L \supset M$ where both L and M are deformation retracts of K, then

$$\tau(K, M) = \tau(K, L) + i_*\tau(L, M),$$

where $i: \pi_1 L \cong \pi_1 K$.

Next a familiar definition:

The mapping cylinder of a cellular mapping $f: X \to Y$ is defined to be the complex M_f whose underlying space $|M_f|$ is obtained from $(|X| \times [0, 1]) \cup |Y|$ by identifying each $(x, 1) \in |X| \times [1]$ with $f(x) \in |Y|$. (Compare Figure 3.) The cell structure is chosen in the



FIGURE 3. A mapping cylinder.

obvious way so that $X(=X \times [0])$ and Y are disjoint⁸ subcomplexes of M_f . Clearly Y is a deformation retract of M_f .

LEMMA 7.5. The torsion $\tau(M_f, Y)$ is zero.

PROOF. Let $f(p): X^p \to Y$ denote the restriction of f to the p-skeleton of X, so that

$$Y = M_{f(-1)} \subset M_{f(0)} \subset M_{f(1)} \subset \cdots \subset M_{f(n)} = M_f.$$

Then

$$\tau(M_f, Y) = \sum_p \tau(M_{f(p)}, M_{f(p-1)})$$

by repeated application of 7.4. But each term on the right is zero by 7.2.

If f happens to be a homotopy equivalence then clearly X too is a deformation retract of M_f . However the torsion

$$\tau(M_f, X) \in \mathrm{Wh}(\pi_1 M_f)$$

is not always zero.

DEFINITION. For any cellular homotopy equivalence

 $f: X \to Y$

the torsion $\tau(f)$ is defined to be that element of $Wh(\pi_1 Y)$ which corresponds to $\tau(M_f, X)$ under the natural isomorphism

$$\operatorname{Wh}(\pi_1 M_f) \cong \operatorname{Wh}(\pi_1 Y).$$

If $\tau(f) = 0$, then f is called a *simple homotopy equivalence*. Here are some of the basic properties of this concept.

LEMMA 7.6. If $i: L \rightarrow K$ is an inclusion map, then $\tau(i) = \tau(K, L)$.

The proof is straightforward.

LEMMA 7.7. If f_0 and f_1 are homotopic then $\tau(f_0) = \tau(f_1)$.

LEMMA 7.8. If $f: X \rightarrow Y$ and $g: Y \rightarrow Z$ are cellular homotopy equivalences, then

$$\tau(g \circ f) = \tau(g) + g_*\tau(f).$$

It will be convenient to prove a more general statement which implies both 7.7 and 7.8. Let $h: X \rightarrow Z$ be any cellular mapping which is homotopic to $g \circ f$.

⁸ This language is convenient; but can be unfortunate if (for example) X is equal to Y. More precisely one *should* say that M_f contains a "copy" of X and a disjoint "copy" of Y.

PROOF THAT
$$\tau(h) = \tau(g) + g_*\tau(f)$$
. Choose a cellular homotopy

 $X \times [0, 1] \rightarrow Z$

between h and $g \circ f$. (This is possible by Whitehead [1949, (K)].) This homotopy can be pieced together with the mapping $g: Y \to Z$ to yield a cellular mapping

 $H: M_f \to Z$

where

$$H \mid X \times [0] = h, \qquad H \mid Y = g$$

Note that the mapping cylinder M_H contains the mapping cylinders



FIGURE 4. Schematic drawing of M_{H} .

of f, g and h as subcomplexes. (Compare Figure 4.) In fact we have the following diagram of inclusion maps.



According to 7.5:

$$\tau(M_f, Y) = 0, \quad \tau(M_g, Z) = 0,$$

 $\tau(M_H, Z) = 0 \text{ and } \tau(M_h, Z) = 0.$

These facts have been indicated on the diagram by inserting the symbol \simeq (for simple homotopy equivalence) on the appropriate arrows. Applying 7.4 to the second and third of these equations, we see that

$$\tau(M_H,\,M_g)\,=\,0.$$

Similarly

$$\tau(M_H, M_h) = 0.$$

In other words j and k are simple homotopy equivalences. Now applying 7.4 to the right hand square we see that

$$\tau(M_H, M_f) + i_* 0 = 0 + j_* \tau(M_g, Y).$$

Similarly from the left hand square:

$$0 + k_* \tau(M_h, X) = \tau(M_H, M_f) + i_* \tau(M_f, X).$$

Hence

$$k_*\tau(M_h, X) = j_*\tau(M_g, Y) + i_*\tau(M_f, X).$$

Now applying the isomorphism

$$\operatorname{Wh}(\pi_1 M_H) \xrightarrow{\cong} \operatorname{Wh}(\pi_1 Z)$$

to each of these three terms, we obtain the required equation

$$\tau(h) = \tau(g) + g_*\tau(f).$$

This completes the proof of 7.7 and 7.8.

REMARK. It follows from 7.7 that the torsion can be defined even for a homotopy equivalence $X \rightarrow Y$ which is not cellular. For Whitehead showed that any map between CW-complexes is homotopic to a cellular map.

It is not however possible to dispense with the hypothesis that X and Y are finite complexes.

8. Change of rings: the *R*-torsion. This section will study an alternative form of torsion, to be called the "Reidemeister, Franz, de Rham real representation torsion," or briefly "*R*-torsion." This *R*-torsion has two advantages over the Whitehead torsion: It is more likely to be defined; and its value is an honest real number, instead of an element of an esoteric group. On the other hand the Whitehead

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torsion, when defined, is a sharper invariant.

First consider the general problem of changing rings. Let C be a free complex of left A-modules, where each C_k has preferred basis c_k . Let

$$h: A \to A'$$

be a ring homomorphism. Then a free complex C' over A' is obtained by setting

$$C_k' = A' \bigotimes_A C_k$$

(using the homomorphism h to make A' into a right A-module). Furthermore the basis

$$c_k = (c_{k1}, \cdots, c_{k\alpha})$$

for C_k determines a basis

$$c_k' = (1 \otimes c_{k1}, \cdots, 1 \otimes c_{k\alpha})$$

for C'_k .

HYPOTHESIS. Suppose that C' is acyclic (that is $H_kC' = 0$ for all k).

Then using the preferred bases c_k' the torsion $\tau(C') \in \overline{K}_1 A'$ is defined. This element will be denoted by $\tau_h(C)$ and called the torsion of C associated with the representation h of A.

For example if the original complex C is acyclic then the new complex C' will certainly also be acyclic. Hence in this case both $\tau(C)$ and $\tau_h(C)$ are defined. However the relation

$$\tau_h(C) = h_*\tau(C)$$

shows that we have not really produced anything new in this case. The real interest lies rather in the fact that τ_h may be defined even when τ is not. Examples will be given presently.

The simplest choice for the ring A' is a field: say the field of complex numbers. However, if we are interested in noncommutative situations, then it is necessary to look at more general possibilities. This section will emphasize the possibility of using a real matrix ring for A'.

Now for the geometry. As in §7 consider pairs (K, L) of finite CW-complexes. We again assume that K is connected, with fundamental group II; but we no longer require that L be a deformation retract of K. As before the chain complex $C(\hat{K}, \hat{L})$ is free over ZII with preferred bases. We will discuss two different procedures for changing the ring, so as to obtain a more manageable torsion. A third procedure will be discussed in §12.

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First procedure. Consider a homomorphism

 $h: \Pi \to F^*$

from II to the multiplicative group of a field F, say the field of complex numbers. Then h gives rise to a ring homomorphism

$$Z\Pi \rightarrow F$$

which will also be denoted by h. Using h we can form the chain complex

$$C' = F \underset{\mathbf{Z}\Pi}{\otimes} C(\hat{K}, \hat{L})$$

over F. If $H_*(C') = 0$ then the torsion

$$\tau(C') \in \overline{K}_1 F = F^* / \{\pm 1\}$$

is more or less well defined. To be more precise, this torsion is well defined providing that we pass to the quotient group

$$\overline{K}_{1}F/\text{image}(\Pi) = F^{*}/\{\pm 1\}h(\Pi).$$

As in §7, torsion is invariant under subdivision. We will use the notation

$$\Delta_h(K, L) \in F^*/\pm h(\Pi)$$

or

$$\pm h(\Pi)\Delta_h(K, L) \subset F^*$$

for this torsion.⁹ The use of this new symbol Δ will help to distinguish $\Delta_{\lambda}(K, L)$ from the Whitehead torsion $\tau(K, L)$. Also the new notation will emphasize that Δ belongs to a multiplicative rather than an additive group.

This is the original construction as used by Reidemeister and Franz. It is particularly effective if Π is a finite cyclic group, and F is the field of complex numbers. But it can also be used in other cases:

EXAMPLE 1. Let K be the circle S^1 and let L be vacuous. The Whitehead torsion $\tau(S^1, \phi)$ cannot be defined, since the module $H_0(\hat{S}^1)$ is not zero, and is not ZII-free. However if the homomorphism

$$h: \pi_1 S^1 \to F^*$$

maps a generator into the field element $f \neq 1$, then computation shows

⁹ Caution. Due to a difference in sign conventions, this Δ corresponds to Δ^{-1} in de Rham [1950] and Milnor [1961], [1962].

that the associated torsion

$$\Delta_h(S^1) \in F^*/\pm h(\Pi)$$

is well defined, and is equal to 1-f (up to multiplication by plus or minus a power of f).

EXAMPLE 2. Let X be obtained from the 3-sphere by boring out the interior of a knotted tube. Let

$$h: \pi_1(X) \longrightarrow F^*$$

map each loop with linking number +1 into the field element $f \neq 1$. Then $\Delta_h(X)$ is well defined, and is equal to (1-f)/A(f) (up to multiplication by $\pm f^i$), where A(t) denotes the Alexander polynomial of the knot. (Compare Milnor [1962].)

In general, if we want to work with a noncommutative group II, it is better to allow representations of II by $n \times n$ matrices, with n > 1. Once we have made this step, the complex numbers no longer seem to have any advantage over the real numbers.

Second Procedure. Let $h: \Pi \rightarrow O(n)$ be an orthogonal representation of the group II. Then h extends to a unique ring homomorphism from $\mathbb{Z}\Pi$ to the ring $M_n(\mathbb{R})$ of all real $n \times n$ matrices. Using h we can form the complex

$$C' = M_n(\mathbf{R}) \bigotimes_{\Pi} C(\hat{K}, \hat{L}).$$

If this complex happens to be acyclic, then the torsion

$$\tau(C') \in \overline{K}_1 M_n(R) = \overline{K}_1 R$$

is defined.

The group $\overline{K}_1 R$ can be identified either with the multiplicative group R^+ or with the additive group R, using the correspondence

$$(a_{ij}) \rightarrow |\det(a_{ij})|$$
 or $\log |\det(a_{ij})|$

respectively. It doesn't really matter which identification is used; but the multiplicative notation is customary in this context. We will again use the notation Δ instead of τ to emphasize the switch to a multiplicative notation.

DEFINITION. The positive real number corresponding to $\tau(C') \in \overline{K}_1 \mathbb{R}$ will be denoted by $\Delta_h(K, L)$, and called the *R*-torsion of (K, L) with respect to *h*. The *R*-torsion also is invariant under subdivision.

This *R*-torsion is completely well defined. In particular, there is no ambiguity coming from the lack of uniqueness of representative cells in the universal covering space. For if the *p*-cell \hat{e} of \hat{K} is replaced by

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a translate $\sigma \hat{e}$, then $\Delta_h(K, L)$ will be multiplied or divided by $|\det h(\sigma)|$ according as p is odd or even. But this determinant is ± 1 , since $h(\sigma)$ is orthogonal.

Let us compare *R*-torsions with Whitehead torsions. Recall from §6 that any orthogonal representation

$$h: \Pi \to O(n)$$

determines a homomorphism

$$h_* \colon \mathrm{Wh}(\Pi) \to \overline{K}_1 R \cong R^+.$$

THEOREM 8.1. Suppose that the Whitehead torsion invariant

$$\tau(K, L) \in \mathrm{Wh}(\Pi)$$

is defined; and suppose that Π is a finite group. Then $\tau(K, L)$ is an element of finite order in Wh(Π) if and only if $\Delta_h(K, L) = 1$ for all possible orthogonal representations h of Π . If Π is finite abelian, then $\tau = 0$ if and only if $\Delta_h = 1$ for all possible h.

PROOF. This follows immediately from 6.9 and 6.4 together with the identity

$$\Delta_h(K, L) = h_*\tau(K, L).$$

REMARK. Of course one need only consider representations h which are irreducible. Furthermore one need consider only "irrational" representations. For if h is equivalent to a representation by rational matrices, then it is equivalent to a representation by integer matrices; and hence h_* is trivial.

As a final illustration of *R*-torsions, consider the following.

By a spherical *Clifford-Klein manifold* M^n will be meant a manifold of the form S^n/Π where Π is a finite fixed-point free group of orthogonal motions of the *n*-sphere. (If Π is cyclic then S^n/Π is called a *lens space.*) It will be shown in §9 that torsion can be defined for such smooth manifolds.

THEOREM 8.2 (DE RHAM). A spherical Clifford-Klein manifold is determined up to isometry by its fundamental group II together with the collection $\{\Delta_h(M^n)\}$ of R-torsion invariants.

Hence two such manifolds which are diffeomorphic must actually be isometric.

For the proof the reader is referred to de Rham [1950]. In the case of a lens space this result is due to Franz [1935], and will be studied further in §12. 9. Torsion for smooth manifolds. Let W be a smooth $(=C^{\infty})$ manifold whose boundary is the disjoint union $M \cup M'$ of two closed submanifolds. If W is compact, connected, and both M and M' are deformation retracts of W, then the triad (W; M, M') is called an *h*-cobordism.

If the fundamental group

$$\Pi = \pi_1 M \cong \pi_1 W \cong \pi_1 M'$$

is trivial, and the dimension n of W is ≥ 6 , then a theorem of Smale [1962] asserts that W is necessarily a product:

$$W \approx M \times [0, 1].$$

We will be interested in the case when II is nontrivial. According to a theorem of Stallings [1965₂], the *h*-cobordism is then completely determined by M, together with the torsion invariant $\tau(W, M) \in Wh(II)$. (See §11.)

To define this torsion, one must somehow construct an algebraic chain complex out of the geometric situation. Three ways of doing this are known to me:

(1) The construction can be based on Whitehead's theory of C^1 -triangulations.

(2) It can be based on the Smale-Morse theory of handlebodies (or of nondegenerate functions).

(3) It can be based on the nerve of a covering by geodesically convex open sets (de Rham [1950]).

We will study only the first two possibilities. The first is the easiest. Let

$$t: \left(\left| \begin{array}{c} K \right|, \left| \begin{array}{c} L \right| \right) \rightarrow (W, M) \end{array} \right)$$

be a C^1 -triangulation. (See Munkres [1963]. Here |K| denotes the underlying topological space of the simplicial complex K.) Now define $\tau(W, M)$ to be $t_*\tau(K, L)$, where

$$t_*: \operatorname{Wh}(\pi_1 \mid K \mid) \to \operatorname{Wh}(\pi_1 W)$$

denotes the isomorphism induced by t.

LEMMA 9.1. This element $\tau(W, M)$ does not depend on the choice of the C¹-triangulation t.

PROOF. Let $u: (|X|, |Y|) \rightarrow (W, M)$ be a second C^1 -triangulation. By a fundamental theorem of Whitehead, there exist rectilinear subdivisions (K', L') of (K, L) and (X', Y') of (X, Y) which are isomorphic to each other under an isomorphism

$$\phi \colon (K', L') \to (X', Y')$$

of simplicial complexes. Furthermore, given $\epsilon > 0$, these subdivisions can be chosen so that the composition

$$u \mid \phi \mid t^{-1} \colon (W, M) \to (W, M)$$

is an ϵ -approximation to the identity. (See Munkres §10.5.)

If ϵ is sufficiently small, then clearly $u_* |\phi| * t_*^{-1}$ must be the identity automorphism of Wh(II). Hence

$$t_*\tau(K, L) = t_*\tau(K', L') = u_* |\phi|_*\tau(K', L')$$

= $u_*\tau(X', Y') = u_*\tau(X, Y);$

which completes the proof.

Next we will discuss the definition based on Smale-Morse theory. Let W be a smooth manifold with boundaries M and M'. A smooth function

$$f\colon W\to [a,\,b]$$

is called a Morse function if $f^{-1}(a) = M$, $f^{-1}(b) = M'$; and if the critical points of f are interior and nondegenerate. Now suppose that $a = -\frac{1}{2}$, $b = n + \frac{1}{2}$. Definition. f is a nice function (or self-indexing function) if all critical points of index λ lie in the subset $f^{-1}(\lambda) \subset W$. A theorem of Smale asserts that such functions always exist.

Defining $W^{(\lambda)} = f^{-1}[a, \lambda + \frac{1}{2}]$ it then follows that

$$M = W^{(-1)} \subset W^{(0)} \subset W^{(1)} \subset \cdots \subset W^{(n)} = W_{n}$$

where each $W^{(\lambda)}$ is a smooth manifold which contains precisely the critical points of index $\leq \lambda$.

Given such a nice function f we will define the torsion $\tau(W, M, f)$ relative to f. It will then be established that this coincides with our earlier definition of $\tau(W, M)$, and hence does not actually depend on f.

Let \hat{W} denote the universal covering manifold of W, and $\hat{f}: \hat{W} \to [a, b]$ the map corresponding to f. Then $\hat{W}^{(\lambda)} = \hat{f}^{-1}[a, \lambda + \frac{1}{2}]$ is the portion of \hat{W} which lies over $W^{(\lambda)}$.

LEMMA 9.2. The singular homology group $H_i(\hat{W}^{(\lambda)}, \hat{W}^{(\lambda-1)})$ is zero for $i \neq \lambda$ and is free abelian for $i = \lambda$, with one generator for each critical point of index λ in \hat{W} .

PROOF. It is well known that $W^{(\lambda)}$ contains as deformation retract a subset $W^{(\lambda-1)} \cup e_1 \cup \cdots \cup e_{\alpha}$ where e_1, \cdots, e_{α} are disjoint λ -cells which pass through the critical points x_1, \cdots, x_{α} of index λ in W,

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and which are attached to $W^{(\lambda-1)}$ only along their boundaries. (See Milnor [1963, §3.3].) Hence the covering space $\hat{W}^{(\lambda)}$ has a similar description. However each λ -cell e_i is covered by a collection of disjoint λ -cells $\sigma \hat{e}_i$ where σ ranges over the group II of covering transformations, and where \hat{e}_i denotes a single representative cell. Precisely one cell $\sigma \hat{e}_i$ passes through each of the points $\sigma \hat{x}_i$ lying over x_i in \hat{W} . This completes the proof.

If we take account of the action of Π then it is evident that $H_{\lambda}(\hat{W}^{(\lambda)}, \hat{W}^{(\lambda-1)})$, becomes a free module over the group ring $Z\Pi$, with α generators. Setting $H_{\lambda}(\hat{W}^{(\lambda)}, \hat{W}^{(\lambda-1)})$ equal to \overline{C}_{λ} we have thus constructed a free chain complex

$$\overline{C}_n \to \overline{C}_{n-1} \to \cdots \to \overline{C}_0$$

over **ZII**. The homology of this chain complex is isomorphic to $H_*(\hat{W}, \hat{M})$ (compare §5) and hence is zero; since \hat{M} is a deformation retract of \hat{W} .

The above construction also yields a preferred basis for \overline{C}_{λ} . [The procedure can be described more invariantly as follows. For each critical point x_i in $f^{-1}(\lambda)$ choose a covering critical point \hat{x}_i . Now if U is a small neighborhood of \hat{x}_i note that the group

$$H_{\lambda}(U \cap \hat{f}^{-1}[a, \lambda], U \cap \hat{f}^{-1}[a, \lambda])$$

is infinite cyclic, and maps monomorphically into

$$H_{\lambda}(\hat{f}^{-1}[a,\lambda],\hat{f}^{-1}[a,\lambda]) \cong H_{\lambda}(\hat{W}^{(\lambda)},\hat{W}^{(\lambda-1)}) = \overline{C}_{\lambda}.$$

Thus the choice of \hat{x}_i determines a basis element for \overline{C}_{λ} up to sign.]

Just as in §7 the torsion $\tau \overline{C}$ is defined, apparently as an element of $\overline{K}_1 \mathbb{Z} \Pi$. But if we alter the choice of representatives \hat{x}_i , then, as in §7, this torsion will be altered by an element of the subgroup

image(II)
$$\subset \overline{K}_1 \mathbb{Z} \Pi$$
.

Hence the image of $\tau \overline{C}$ in the quotient group Wh(II) = $\overline{K}_1 \mathbb{Z} \Pi$ /image(II) is independent of the choice of representatives. This image will be denoted by $\tau(W, M; f) \in Wh(\Pi)$.

THEOREM 9.3. If $t: (|K|, |L|) \rightarrow (W, M)$ is a C¹-triangulation then

$$\tau(W, M; f) = t_*\tau(K, L).$$

Hence $\tau(W, M; f) = \tau(W, M)$ does not depend on the choice of nice function f.

REMARK. A corresponding theorem holds for *R*-torsions.

PROOF OF 9.3. We are at liberty to choose whatever C^1 -triangula-

tion we please. In particular we can choose the triangulation so that each $W^{(\lambda)}$ corresponds to a subcomplex $K^{(\lambda)} \subset K$. (Munkres §10.6.) It will be convenient to suppress the map t by identifying |K| with its image t|K| = W.

Thus the chain complexes $C^{(\lambda)} = C(\hat{K}^{(\lambda)}, \hat{L})$ yield a filtration

$$C^{(0)} \subset C^{(1)} \subset \cdots \subset C^{(n)} = C(\hat{K}, \hat{L}).$$

The relative homology groups $H_i C^{(\lambda)} / C^{(\lambda-1)}$ can be identified with $H_i(\hat{W}^{(\lambda)}, \hat{W}^{(\lambda-1)})$, and hence satisfy the hypotheses of §5. Furthermore we have used the geometry to choose bases for the free modules

$$\overline{C}_{\lambda} = H_{\lambda} C^{(\lambda)} / C^{(\lambda-1)} = H_{\lambda}(\widehat{W}^{(\lambda)}, \widehat{W}^{(\lambda-1)}).$$

We will prove:

LEMMA 9.4. For each quotient complex $C^{(\lambda)}/C^{(\lambda-1)}$ the torsion $\tau C^{(\lambda)}/C^{(\lambda-1)} \in Wh(\Pi)$ is zero.

Using the Algebraic Subdivision Theorem of §5, this will prove that $\tau \overline{C} = \tau(W, M; f)$ is equal to $\tau C = t_* \tau(K, L)$; which will prove the theorem.

PROOF OF LEMMA. Let us recall something of the geometry of the region $f^{-1}[\lambda - \frac{1}{2}, \lambda + \frac{1}{2}]$ which contains the critical points of index λ . (Compare Milnor [1963, §3] and [1965].) It will be convenient to set

$$X = f^{-1}[\lambda - \frac{1}{2}, \lambda + \frac{1}{2}], \quad B = f^{-1}[\lambda - \frac{1}{2}], \quad B' = f^{-1}[\lambda + \frac{1}{2}]$$

We must prove that $\tau(X, B) = 0$.

Through each critical point x_i one can construct a "left hand cell" e_i^{λ} which meets B in the sphere ∂e_i^{λ} , and a corresponding "right hand cell," which we will denote by $e_i^{n-\lambda}$, and which meets B' in a corre-



FIGURE 5. The "left and right-hand cells" for a critical point of index $\lambda = 1$ on a surface.

sponding sphere $\partial \epsilon_i^{n-\lambda}$. These cells are all disjoint except that $e_i^{\lambda} \cap \epsilon_i^{n-\lambda} = x_i$. Using the trajectories of a suitable vector field one can show that the two boundary manifolds

$$B - \partial e_1^{\lambda} - \cdots - \partial e_{\alpha}^{\lambda}, \qquad B' - \partial \epsilon_1^{n-\lambda} - \cdots - \partial \epsilon_{\alpha}^{n-\lambda}$$

are diffeomorphic. In fact the entire region

$$X - (e_1^{\lambda} \cup \epsilon_1^{n-\lambda}) - \cdots - (e_{\alpha}^{\lambda} \cup \epsilon_{\alpha}^{n-\lambda})$$

is diffeomorphic with the product

$$(B - \partial e_1^{\lambda} - \cdots - \partial e_{\alpha}^{\lambda}) \times [\lambda - \frac{1}{2}, \lambda + \frac{1}{2}].$$

Let B_0 denote the manifold obtained from B by removing an open tubular neighborhood of each ∂e_i^{λ} ; and let

$$X_0 \approx B_0 \times \left[\lambda - \frac{1}{2}, \lambda + \frac{1}{2}\right]$$

denote the corresponding subset of X. (Compare Figure 5, in which X_0 is shaded and B_0 is emphasized.) We may assume that X_0 is triangulated as a product. (Compare the proof in Munkres [1963, \$10.6].)

Now we will apply two lemmas from §7. We have

$$\tau(X, B) = \tau(X_0 \cup B, B) + \tau(X, X_0 \cup B)$$

by Theorem 3.2. (To be accurate here, each of the symbols X, X_0, B should be replaced by the symbol for the corresponding simplicial complex.) But the last term is zero by Lemma 7.3 since each component of $X - X_0 - B$ is clearly contractible. The first term on the right is zero by Lemma 7.5 since X_0 is a product: $X_0 \approx B_0 \times [\lambda - \frac{1}{2}, \lambda + \frac{1}{2}]$. (Such a product is clearly an example of a mapping cylinder. Furthermore the product triangulation of X_0 can be regarded as a subdivision of the product cell structure which was used in the discussion of mapping cylinders.)

Thus $\tau(X, B) = \tau C^{(\lambda)} / C^{(\lambda-1)}$ is zero; which completes the proof.

10. The duality theorem. The following basic theorem has been proved by Mazur [1963], Barden [1963] and Stallings. We will not try to give a proof.

s-COBORDISM THEOREM. Let (W; M, M') be an h-cobordism of dimension $n \ge 6$. Then the torsion $\tau(W, M)$ vanishes if and only if W is diffeomorphic to the product $M \times [0, 1]$.

Suppose that we interchange the roles of M and M'. Clearly we can also say that $\tau(W, M')$ is zero if and only if W is a product. This

suggests that there should be a formula relating $\tau(W, M)$ and $\tau(W, M')$.

DUALITY THEOREM. For any orientable h-cobordism (W; M, M') of dimension n we have

$$\tau(W, M') = (-1)^{n-1} \bar{\tau}(W, M),$$

where $\bar{\tau}$ denotes the conjugate of τ .

(For the definition of "conjugate" see §6.)

The proof will depend on a comparison between the nice function f on W and the "dual" nice function n-f.

As in §9, through each critical point x_i of index λ we can construct a "left-hand cell"

$$e_i^{\lambda} \subset f^{-1}[\lambda - \frac{1}{2}, \lambda]$$

and a right hand cell

$$\epsilon_i^{n-\lambda} \subset f^{-1}[\lambda, \lambda + \frac{1}{2}].$$

These are to be oriented so that the intersection number $e_i^{\lambda} \cdot e_i^{n-\lambda}$ is +1. Furthermore we can cover e_i^{λ} and $e_i^{n-\lambda}$ by representative cells in the universal covering space so that $\hat{e}_i^{\lambda} \cdot \hat{e}_i^{n-\lambda} = 1$.

If we think of \hat{e}_i^{λ} as a basis element for the chain group

$$\overline{C}_{\lambda} = H_{\lambda}(\widehat{W}^{(\lambda)}, \widehat{W}^{(\lambda-1)})$$

then the boundary homomorphism $\partial: \overline{C}_{\lambda+1} \to \overline{C}_{\lambda}$ can be described by a matrix of "incidence numbers" $a_{ki} \in \mathbb{Z}\Pi$, where



FIGURE 6. A highly schematic drawing of left and right hand cells for critical points of index λ and λ +1.

Similarly, using the dual function n-f, we can define incidence numbers between the right hand cells.

DUALITY LEMMA. The incidence number between $\hat{\epsilon}_i^{n-\lambda}$ and $\hat{\epsilon}_k^{n-\lambda-1}$ is equal to the conjugate \bar{a}_{ki} of the incidence number between $\hat{e}_k^{\lambda+1}$ and \hat{e}_i^{λ} , multiplied by a sign $(-1)^{\lambda+1}$ which depends only on the dimensions.

The proof will depend on some identities involving intersection numbers. It will be convenient to set



FIGURE 7. A more realistic drawing. (With n=2. Note that B^+ is vacuous.) The boundary formulas $\partial \hat{e}^2 = (t^{-1}-1)\hat{e}^1$, $\partial \hat{e}^{n-1} = (t-1)\hat{e}^{n-2}$ illustrate the Duality Lemma.

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(Compare Figures 6 and 7.) We will show that the matrix (a_{kj}) can be described in terms of intersection numbers, either within X^- or within the middle manifold B.

Note that the homomorphism $\overline{\partial}: \overline{C}_{\lambda+1} \rightarrow \overline{C}_{\lambda}$ can be expressed as $\overline{\partial} = \iota_* \partial$ where

$$\partial \colon \overline{C}_{\lambda+1} = H_{\lambda+1}(X^+, B) \to H_{\lambda}B,$$

$$\iota_* \colon H_{\lambda}B \to H_{\lambda}(X^-, B^-) = \overline{C}_{\lambda}.$$

(Here ι denotes the inclusion map $(B, \phi) \rightarrow (X^-, B^-)$.)

Let us compute the coefficient of σ in the group ring element a_{kj} . In other words let us compute the coefficient of $\sigma \hat{e}_j^{\lambda}$ in $\partial \hat{e}_k^{\lambda+1}$. Clearly the element $\sigma \hat{e}_j^{n-\lambda}$ of $H_{n-\lambda}(X^-, B)$ has intersection number +1 with $\sigma \hat{e}_j^{\lambda}$, but has intersection number 0 with all of the other basis elements $\rho \hat{e}_i^{\lambda}$. This gives us the identity

coefficient of
$$\sigma$$
 in a_{kj}
= coefficient of $\sigma \hat{e}_j^{\lambda}$ in $\overline{\partial} \hat{e}_k^{\lambda+1}$
= $(\overline{\partial} \hat{e}_k^{\lambda+1}) \cdot (\sigma \hat{e}_j^{n-\lambda}).$

Now suppose that B is oriented as part of the boundary of X^- . Then for any elements

$$u \in H_{\lambda}B, \quad v \in H_{n-\lambda}(X^{-}, B)$$

the identity

$$\iota_* u \cdot v = (-1)^{\lambda} u \cdot \partial' v$$

is easily verified (where the first intersection number is evaluated within X^- and the second is evaluated within B). Setting

$$\iota_* u = \iota_* \partial \hat{e}_k^{\lambda+1} = \overline{\partial} \hat{e}_k^{\lambda+1}, \qquad v = \sigma \hat{e}_j^{n-\lambda}$$

this yields the formula

coefficient of
$$\sigma$$
 in a_{kj}
= $(-1)^{\lambda} (\partial \hat{\epsilon}_{k}^{\lambda+1}) \cdot (\sigma \partial' \hat{\epsilon}_{j}^{n-\lambda}).$

Now let us look at the corresponding matrix (a'_{jk}) for the dual homomorphism

$$\overline{\partial}' = \iota_*' \, \partial' \colon H_{n-\lambda}(X^-, B) \to H_{n-\lambda-1}(X^+, B^+).$$

Similar arguments show that

coefficient of
$$\sigma$$
 in a'_{jk}
= coefficient of $\sigma \hat{\epsilon}_k^{n-\lambda-1}$ in $\iota_k' \partial_k' \hat{\epsilon}_j^{n-\lambda}$
= $(\sigma \hat{\epsilon}_k^{\lambda+1}) \cdot (\iota_k' \partial' \hat{\epsilon}_j^{n-\lambda})$
= $- (\partial \sigma \hat{\epsilon}_k^{\lambda+1}) \cdot (\partial' \hat{\epsilon}_j^{n-\lambda})$
= $- (\partial \hat{\epsilon}_k^{\lambda+1}) \cdot (\sigma^{-1} \partial' \hat{\epsilon}_j^{n-\lambda}).$

Comparing these expressions, the coefficient of σ in a'_{jk} is equal to $(-1)^{\lambda+1}$ times the coefficient of σ^{-1} in a_{kj} . Therefore

$$a'_{jk} = (-1)^{\lambda+1} \bar{a}_{kj}$$

as asserted.

PROOF OF DUALITY THEOREM. First suppose that there exists a nice function f on W such that all critical points have index λ or $\lambda+1$. Then the complex \overline{C} associated with f is completely described by the matrix (a_{kj}) which corresponds to

$$\overline{\partial} \colon \overline{C}_{\lambda+1} \to \overline{C}_{\lambda}.$$

Since \overline{C} is acyclic it is clear that (a_{kj}) is nonsingular, and that the canonical homomorphism

$$\eta: \operatorname{GL}(\alpha, \mathbb{Z}\Pi) \to \operatorname{Wh}(\Pi)$$

carries (a_{kj}) to $(-1)^{\lambda}\tau(W, M)$.

Similarly the dual complex \overline{C}' is completely described by the matrix (a'_{jk}) which corresponds to

$$\partial' \colon \overline{C}_{n-\lambda}' \to \overline{C}_{n-\lambda-1}',$$

so that η carries (a'_{jk}) to $(-1)^{n-\lambda-1}\tau(W, M')$. But (a'_{jk}) is, up to sign, the conjugate transpose of (a_{kj}) . Therefore

$$(-1)^{\lambda}\tau(W, M) = (-1)^{n-\lambda-1}\overline{\tau}(W, M'),$$

which completes the proof in the special case.

If the dimension n is ≥ 6 this actually completes the proof, since such special nice functions are constructed as part of the proof of the *s*-Cobordism Theorem. (See also the proof of the Existence Theorem in §11.)

This simplification is not really necessary however. It is better simply to prove in general that two chain complexes \overline{C} and $\overline{C'}$ which are "dual," in the sense that they satisfy the Duality Lemma, will always have torsions satisfying the Duality Theorem. The argument is not too different from that given in Milnor [1962]; and will be left to the reader.

REMARK. If the manifolds are not orientable then it is necessary to change the Duality Theorem and Lemma as follows. The conjugation operation in $Z\Pi$ must be replaced by the anti-automorphism $a \rightarrow a^*$ which satisfies

$$\sigma^* = \sigma^{-1}$$
 if σ is orientation preserving,
 $\sigma^* = -\sigma^{-1}$ otherwise.

This induces an automorphism of Wh(II) which is definitely different from conjugation. Here is an example. If T_8 is cyclic of order 8 with generator t, and if $t^* = -t^{-1}$, then the fundamental unit

$$u = 2 + (t + t^7) - (t^3 + t^5) - t^4 \in ZT_8$$

satisfies $\bar{u} = u$, but $u^* = u^{-1}$. No power of u is equal to 1.

The Duality Theorem has an analogue for R-torsion which can be proved in essentially the same way. (Compare Milnor [1962].) The following application is particularly striking.

THEOREM. If M is a closed orientable manifold of even dimension then every R-torsion $\Delta_h(M)$ which is defined is equal to 1.

11. The classification of *h*-cobordisms. The following result is due to Stallings [1965₂]. Let M be a smooth, compact, connected manifold without boundary of dimension n-1.

EXISTENCE THEOREM 11.1. If the dimension of M is ≥ 5 , then for every $\tau_0 \in Wh(\pi_1 M)$ there exists an h-cobordism (W; M, M') with $\tau(W, M) = \tau_0$.

Here is an outline of the proof. It is convenient to use the language of "attaching handles" (Small [1961]).

Let (a_{ij}) be a $k \times k$ nonsingular matrix over **Z**II which represents τ_0 . Start with the product $M \times [0, 1]$ and attach k handles of index +2 to the right hand side. The attaching maps

$$S^1 \times D^{n-2} \to M \times [1]$$

should be "trivial" so that the resulting manifold W_1 can also be described as that obtained from $M \times [0, 1]$ by pasting k copies of $S^2 \times D^{n-2}$ along its right hand boundary. The left and right hand boundaries of W_1 will be denoted by M and M_1 respectively.

The group $\pi_2(W_1, M) \cong H_2(\hat{W}_1, \hat{M})$ is clearly free over $Z(\pi_1 M)$ with k preferred generators.

LEMMA 11.2. Each element of $\pi_2(W_1, M)$ can be represented by a 2-sphere $S \subset M_1$ which is embedded with trivial normal bundle.

PROOF. Since $\pi_1 W_1 \cong \pi_1 M$ we have

$$\pi_2 W_1 \to \pi_2(W_1, M) \to 0.$$

Furthermore

$$\pi_2 M_1 \to \pi_2 W_1 \to 0$$

since W_1 has a dual handlebody presentation in which it is obtained from $M_1 \times [0, 1]$ by attaching k handles of index n-2>2. Therefore the given homotopy class can be represented by an element of $\pi_2 M_1$. Each element of $\pi_2 M_1$ is represented by an imbedded sphere S since the dimension n-1 is ≥ 5 .

We must try to choose S so that its normal bundle is trivial. To verify that the normal bundle of S is trivial it is sufficient to check that the Stiefel-Whitney class w_2 of W_1 annihilates the homology class of S in W_1 . But this Stiefel-Whitney class determines a homomorphism

$$\pi_2 W_1 \to H_2 W_1 \to \boldsymbol{Z}_2.$$

By the construction of W_1 it is clear that we can choose elements $\mu_1, \dots, \mu_k \in \pi_2 W_1$ which represent a basis for $\pi_2(W_1, M)$; and so that w_2 annihilates the homology class of each of the μ_i . Hence, if the homotopy class of S in W_1 is chosen carefully, the normal bundle of S in W_1 , and in M_1 , will be trivial. This proves the Lemma.

Now the k rows of the matrix (a_{ij}) represent elements of $\pi_2(W_1, M)$ which are represented by spheres appropriately imbedded in M_1 . Using these k 2-spheres to attach handles of index 3 to W_1 , we obtain the required manifold W. Let M' be the right hand boundary.

Clearly $\pi_1 M \cong \pi_1 W_1 \cong \pi_1 W$; and $H_*(\hat{W}, \hat{M}) = 0$ since the matrix (a_{ij}) is nonsingular. Therefore M is a deformation retract of W. (Compare Whitehead [1949].) On the other hand $\pi_1 M' \cong \pi_1 W$ since W can be formed from $M' \times [0, 1]$ by attaching handles of index $n-3 \ge 3$ and $n-2 \ge 4$. Furthermore, using the Duality Lemma of §10, we see that $H_*(\hat{W}, \hat{M}')$ is also zero. Therefore (W; M, M') is an *h*-cobordism.

Since $\tau(W, M)$ is clearly equal to τ_0 , this completes the proof.

Combining the Existence Theorem with the s-Cobordism Theorem (\$10), we obtain the following.

UNIQUENESS THEOREM 11.3. Let $(W; M, M_1)$ and $(W_2; M, M_2)$ be two h-cobordisms of dimension ≥ 6 with the same torsion:

$$\tau(W_1, M) = \tau(W_2, M) = \tau_0.$$

Then W_1 is diffeomorphic to W_2 under a diffeomorphism which preserves M.

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PROOF. (Compare Figure 8.) Choose an *h*-cobordism $(W'; M_1, M')$ with $\tau(W', M_1) = -\tau_0$. (We are identifying the fundamental groups



$$\pi_1 M \cong \pi_1 W_k \cong \pi_1 M_k$$

FIGURE 8. The composite *h*-cobordism is diffeomorphic both to W_1 and to W_2 .

in the obvious way.) Let $W_1 \cup W'$ be a smooth manifold obtained by pasting W_1 and W' together along M_1 . Then

$$\tau(W_1 \cup W', M) = \tau(W_1, M) + \tau(W_1 \cup W', W_1) = \tau_0 - \tau_0 = 0$$

hence $W_1 \cup W' \approx M \times [0, 1]$. In particular we obtain a diffeomorphism $\phi: M' \rightarrow M$.

Similarly form $W_1 \cup W' \cup_{\phi} W_2$. Since $W_1 \cup W'$ is a product it follows that

$$W_1 \cup W' \cup_{\phi} W_2 \approx (M \times [0, 1]) \cup W_2 \approx W_2.$$

But a similar argument shows that $W' \cup_{\phi} W_2$ is a product, hence

 $W_1 \cup W \cup_{\phi} W_2 \approx W_1 \cup (M_1 \times [0, 1]) \approx W_1.$

This completes the proof.

Let us try to test the power of these theorems by trying to classify manifolds which are h-cobordant to a given manifold M_0 . We must first ask the following question. Given an h-cobordism (W; M_0 , M') can it happen that M' is diffeomorphic to M_0 even though W is not a product?

Here is a method for constructing examples. Given any *h*-cobordism $(W; M_0, M_1)$ let 2W denote the "double" of W which is obtained by pasting together two copies of W along the right hand boundary M_1 .

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Then clearly $(2W; M_0, M'_0)$ is an h-cobordism, where M_0 and M'_0 denote two copies of the same manifold.

LEMMA 11.4. The torsion $\tau(2W, M_0)$ is equal to $\tau(W, M_0) + (-1)^{n-1}$ $\overline{\tau}(W, M_0)$.

The proof is straightforward.

Thus, surprisingly enough, 2W is not always a product. For example if II is finite commutative and the dimension $n \ge 7$ is odd, then $\tau(2W, M_0) = 2\tau(W, M_0)$, so 2W is a product only if W is a product. An interesting consequence is the following.

THEOREM 11.5. If M has even dimension and $\pi_1 M$ is finite, then there are only finitely many distinct manifolds which are h-cobordant to M.

In contrast, if M has odd dimension, there may well be infinitely many such manifolds. (Compare \$12.9.)

PROOF. Let $G \subset Wh(\pi_1 M)$ denote the subgroup consisting of all elements of the form $\omega + \bar{\omega}$. Since $Wh(\pi_1 M)$ is finitely generated, and since

 $\tilde{\omega} \equiv \omega$ (modulo elements of finite order)

by 6.10, it follows easily that G is a subgroup of finite index.

Consider two *h*-cobordisms (W'; M, M') and (W''; M, M'') which satisfy

$$\tau(W', M) \equiv \tau(W'', M) \pmod{G}$$



FIGURE 9. The composite h-cobordism is diffeomorphic to W''.

Setting $\tau(W'', M) = \tau(W', M) + \tau_0 + \bar{\tau}_0$, construct an *h*-cobordism $(W; M, M_1)$ with torsion τ_0 . Paste the double of W onto W' so as to obtain an *h*-cobordism $(2W \subset W'; M, M')$ with torsion $\tau_0 + (-1)^{n-1}\bar{\tau}_0 + \tau(W', M')$ equal to $\tau(W'', M)$. Then $2W \cup W' \approx W''$ and hence $M' \approx M''$. Thus the number of distinct manifolds *h*-cobordant to M is at most equal to the order of the quotient group Wh(II)/G. This completes the proof.

12. Lens spaces. The lens spaces of Tietze and de Rham serve as marvellous examples for the study of torsion. First some notation. Let $m \ge 3$ be a fixed integer and let $\Pi = T_m$ be the cyclic group of order m with generator t. Let $S^{2n-1} \subset \mathbb{C}^n$ be the unit sphere in complex n-space, with a standard orientation.

Given primitive *m*th roots of unity $\alpha_1, \dots, \alpha_n \in \mathbf{C}$ define an action of Π on S^{2n-1} by the formula

$$t(z_1, \cdots, z_n) = (\alpha_1 z_1, \cdots, \alpha_n z_n).$$

The quotient manifold S^{2n-1}/Π is then called a *lens space*.

In order to index these manifolds conveniently we can introduce residue classes q_1, \dots, q_n modulo m by the formula

$$\alpha_j = \exp(2\pi i q_j/m).$$

Thus if $\alpha_0 = \exp(2\pi i/m)$ is the standard root of unity, then $\alpha_j = \alpha_0^{q_j}$. The "reciprocal" residue classes r_1, \dots, r_n are also important. That is, we define r_j by the congruence

$$q_j r_j \equiv 1 \pmod{m}$$

so that $\alpha_0 = \alpha_j^r$. Following Franz the notation $L_m(r_1, \dots, r_n)$ (or briefly $L(r_1, \dots, r_n)$) will be used for the corresponding lens space S^{2n-1}/Π .

Note that $L(r_1, \dots, r_n)$ is a Riemannian manifold with a preferred orientation, and that its fundamental group II has a preferred generator *t*. It will be convenient to say that two lens spaces are *isomorphic* if they are related by a diffeomorphism which preserves the Riemannian metric and the orientation and the preferred generator.

Some diffeomorphisms. Clearly the order of the numbers r_1, \dots, r_n is not important. Thus if (r'_1, \dots, r'_n) is a permutation of (r_1, \dots, r_n) then $L(r'_1, \dots, r'_n)$ is isomorphic to $L(r_1, \dots, r_n)$. If we change the sign of one of the r_k the only effect is to reverse the orientation. Hence every lens space is isomorphic to one of the form $\pm L(r_1, \dots, r_n)$ with

$$1 \leq r_1 \leq r_2 \leq \cdots \leq r_n < m/2.$$

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(Here -L denotes L with orientation reversed.) It will turn out later that every lens space is isomorphic to one and only one lens space of this form. As an example, if m is equal to 3, 4, or 6 then every lens space is isomorphic to $\pm L(1, \dots, 1)$.

If the preferred generator for Π is altered, the effect is to replace (r_1, \dots, r_n) by some constant multiple (kr_1, \dots, kr_n) . Hence if we do not wish to distinguish any particular generator for Π , the notation $L(r_1: r_2: \dots: r_n)$ is appropriate.

Metric properties. As Riemannian manifolds the lens spaces of a given dimension are all locally isometric. But they are clearly distinguished by global properties. For example the space $L(1: 1: \cdots : 1)$ of dimension 2n-1 possesses a transitive n^2 -dimensional group of isometries: namely the full unitary group U(n). In contrast, if the residue classes $\pm r_1, \cdots, \pm r_n$ are all distinct, then the group of isometries of $L(r_1, \cdots, r_n)$ is only the *n*-dimensional group $U(1) \times \cdots \times U(1)$.

12.1. Homotopy type. According to Rueff [1938] and Olum [1953]: there exists a homotopy equivalence

$$L(r'_1, \cdots, r'_n) \rightarrow L(r_1, \cdots, r_n)$$

which preserves the orientation and preferred generator if and only if

$$r'_1 \cdots r'_n \equiv r_1 \cdots r_n \pmod{m}.$$

Hence the necessary and sufficient condition for the existence of a homotopy equivalence which is *not* required to preserve orientation and generator is that

$$r'_1 \cdots r'_n \equiv \pm k^n r_1 \cdots r_n \pmod{m}$$

for some integer k.

12.2. Tangent bundle. The preferred generator t for Π determines a preferred generator x for the dual group

$$H^{2}(L; \mathbb{Z}) \cong \operatorname{Ext}(\Pi, \mathbb{Z}) \cong \operatorname{Hom}(\Pi, \mathbb{R}/\mathbb{Z}).$$

The total Pontrjagin class $p=1+p_1+p_2+\cdots$ of the lens space $L(r_1, \cdots, r_n)$ turns out to be given by the formula

$$p = (1 + q_1^2 x^2)(1 + q_2^2 x^2) \cdots (1 + q_n^2 x^2)$$

(where $q_i r_i \equiv 1$). Thus the individual Pontrjagin classes are the elementary functions of the $q_i^2 x^2$:

$$p_1 = (q_1^2 + \cdots + q_n^2)x^2,$$

$$p_2 = (q_1^2 q_2^2 + q_1^2 q_3^2 + \cdots + q_{n-1}^2 q_n^2)x^4,$$

and so on.

EXAMPLE. A lens space can be parallelizable only if its dimension is 3, or its dimension is 7 and

$$q_1^2 + q_2^2 + q_3^2 + q_4^2 \equiv 0 \pmod{m}.$$

(For some values of m, e.g., if m is a multiple of 3 or 8, this congruence cannot be satisfied.)

I will not try to give any details here. A complete determination of the stable tangent bundle of a lens space has been given by Szczarba [1964] and Folkman [1965]. In fact Folkman has proved the following remarkable result: If m is prime, then a high dimensional lens space L_m is determined up to isomorphism by its homotopy type and its stable tangent bundle.

12.3. Cell structure. Each lens space L can be given the structure of a CW-complex with one cell in each dimension. The boundary relations in $\hat{L} = S^{2n-1}$ then take the form

$$\begin{aligned} \partial \hat{e}^{2k-1} &= (t^{r_k} - 1)\hat{e}^{2k-2} & \text{for } 1 \leq k \leq n, \\ \partial \hat{e}^{2k} &= (1 + t + t^2 + \cdots + t^{m-1})\hat{e}^{2k-1} & \text{for } 1 \leq k < n. \end{aligned}$$

(Compare Franz [1935] and de Rham [1950].) This CW-complex has a subdivision which is a C^1 -triangulation of L. (See Milnor [1961], as well as Franz and de Rham.) Hence any torsion invariants which can be computed from the cell structure will be diffeomorphism invariants.

The *R*-torsion invariants can readily be computed, and can be used to classify lens spaces. Instead we will introduce an alternative form of torsion which is somewhat more convenient to work with.

DEFINITION. A finite complex or a compact smooth manifold will be called *special* if the fundamental group Π is finite abelian and operates trivially on the rational homology groups of the universal covering space.

For such special complexes we will define a torsion invariant in the rational group ring $Q\Pi$.

For any finite group II let $N \subset QII$ denote the kernel of the canonical homomorphism $QII \rightarrow Q$ which caries all group elements to +1. Let $\Sigma \in ZII$ denote the sum of all of the group elements. Then clearly the algebra splits as the direct sum

$$Q\Pi = N \oplus (\Sigma)$$

of two mutually annihilating two sided ideals (where $(\Sigma) = Q\Sigma$).

Note that N itself can be thought of as an algebra which is isomorphic to the $Q\Pi/(\Sigma)$. (The identity element of N is equal to $1-\Sigma/m$, where m is the order of Π .)

Let X be a finite complex with fundamental group II. The direct sum decomposition of $Q\Pi$ gives rise to corresponding decompositions of chain and homology modules

$$C(X; Q) = NC(X; Q) \oplus \Sigma C(X; Q),$$

$$H(\hat{X}; Q) = NH(\hat{X}; Q) \oplus \Sigma H(\hat{X}; Q).$$

Now if Π operates trivially on $H(\hat{X}; Q)$ then clearly $NH(\hat{X}; Q) = 0$, so that the complex $NC(\hat{X}; Q)$ is acyclic.

Clearly $NC(\hat{X}; Q)$ is N-free, with a preferred basis which corresponds to the preferred basis for $C(\hat{X}; Z)$ under the natural homomorphism

$$C(\hat{X}; \mathbf{Z}) \rightarrow C(\hat{X}; \mathbf{Q}) / \Sigma C(\hat{X}; \mathbf{Q}) = NC(\hat{X}; \mathbf{Q}).$$

Hence the torsion

$$au(NC(\hat{X}; \boldsymbol{Q})) \in \overline{K}_1 N / (ext{image II})$$

is well defined. As in §7, this torsion is invariant under subdivision.

Now suppose that II is abelian. Then N is isomorphic to a cartesian product of (cyclotomic) fields, hence K_1N can be identified with the group U(N) of units of N. We will switch to a multiplicative notation, and write $\Delta(X) \in U(N)$ for an element corresponding to the torsion $\tau(NC(\hat{X}; \mathbf{Q}))$. Thus we have proved:

LEMMA 12.4. To each special complex X there corresponds the torsion

$$\Delta(X) \in U(N) \subset N \subset \mathbf{Q}\Pi$$

which is well defined up to multiplication by plus or minus a group element. This torsion is invariant under subdivision of X.

It will be convenient to use the notation $\Delta \sim \Delta'$ to mean that

$$\Delta = \pm \sigma \Delta'$$
, for some $\sigma \in \Pi$.

The strength of this torsion invariant is shown by the following.

LEMMA 12.5. A homotopy equivalence $f: X \rightarrow Y$ between special complexes is a simple homotopy equivalence (that is $\tau(f) = 0$) if and only if $f_*\Delta(X) \sim \Delta(Y)$.

PROOF. This follows easily from §8.1.

Now let us look at a lens space $L = L(r_1, \dots, r_n)$. This is clearly a "special" manifold. Modulo the ideal (Σ) the boundary relations 12.3 take the form

$$\partial \hat{e}^{2k-1} = (t^{r_k} - 1)\hat{e}^{2k-2},$$
$$\partial \hat{e}^{2k} = 0.$$

Since we know that $NC(\hat{L}: Q)$ is acyclic it follows that each (t^r-1) must be a unit of N. (Alternatively the identity

$$(t-1)(1+2t+3t^2+\cdots+mt^{m-1})=m-\Sigma$$

shows directly that t-1 is a unit modulo (Σ).) Clearly the torsion is given by

$$\Delta(L) \sim (t^{r_1} - 1)(t^{r_2} - 1) \cdots (t^{r_n} - 1)$$

(This turns out to be an expression with integer coefficients, although a priori we could have expected rational coefficients.)

In order to classify lens spaces we must know what relations exist between the $\phi(m)$ elements $t^r - 1$ of U(N). The identity

$$(t^r - 1) = -t^r(t^{-r} - 1)$$

shows that $(t^{r}-1) \sim (t^{-r}-1)$.

12.6. FRANZ INDEPENDENCE LEMMA. The $\phi(m)/2$ units $t^r-1 \in U(N)$, where

 $1 \leq r < m/2, \quad (r, m) = 1,$

do not satisfy any multiplicative relations.

Since the proof is rather difficult, we will simply refer to Franz [1935] or de Rham [1964₂]. (Actually Franz shows only that there can be no relation of the form $\prod (t^r-1)^{a_r} \sim 1$ where the exponents a_r add up to zero. But the possibility of such a relation in which $\sum a_r \neq 0$ is easily ruled out. Compare Lemma 12.10 below.)

CLASSIFICATION THEOREM 12.7. If two lens spaces have the same torsion invariant $\Delta \in U(N)/\pm \Pi$ then they are isomorphic, up to orientation. Each lens space is isomorphic to a unique lens space of the form $\pm L(r_1, \dots, r_n)$ with $1 \leq r_1 \leq \dots \leq r_n < m/2$.

In particular it follows that two lens spaces which are diffeomorphic must actually be isometric as Riemannian manifolds. (Compare §8.2.)

PROOF. This follows immediately from the Franz lemma.

Now let us study an *h*-cobordism (W; M, M') between two "special" manifolds. All three fundamental groups will be denoted by Π .

THEOREM 12.8. Suppose that there exists an h-cobordism between the odd dimensional special manifolds M, M' which is compatible with a given identification of fundamental groups. Then

$$\Delta(M') \sim u^2 \Delta(M)$$

for some unit u of ZII, where $u^2 \sim 1$ if and only if $\tau(W, M) = 0$. Conversely, if the dimension is ≥ 5 , then given M and u one can construct a corresponding h-cobordism.

PROOF. Given the *h*-cobordism (W; M, M') we have

$$\Delta(W) \sim \Delta(W, M) \Delta(M)$$

 $\sim \Delta(W, M') \Delta(M').$

Since M and M' are deformation retracts, the Whitehead torsions $\tau(W, M)$ and $\tau(W, M')$ are defined. Furthermore

$$\tau(W, M) = - \bar{\tau}(W, M')$$

by §10. Switching to the multiplicative notation, let u and \bar{u}^{-1} denote the units of $Z\Pi$ which correspond to these two torsion invariants. Clearly the homomorphism

$$\mathbf{Z}\Pi \rightarrow \mathbf{Q}\Pi/(\Sigma) \cong N$$

carries u to $\Delta(W, M)$. Therefore

$$\Delta(W) \sim u \Delta(M) \sim \bar{u}^{-1} \Delta(M')$$

hence

$$\Delta(M') \sim u\bar{u}\Delta(M).$$

Since $u \sim \bar{u}$ by §6.7 this proves the first statement.

If $u^2 \sim 1$ then clearly $2\tau(W, M) = 0$. Since Wh(II) is torsion free, this implies that $\tau(W, M) = 0$. (In dimensions ≥ 5 it implies that $W \approx M \times [0, 1]$.)

Since the final statement of Theorem 12.8 follows immediately from §11, this completes the proof.

COROLLARY 12.9. Let M be a special manifold of dimension $2n-1 \ge 5$. If ZII has a nontrivial unit then there exist infinitely many distinct manifolds in the h-cobordism class of M. On the other hand if ZII has only trivial units then every h-cobordism (W; M, M') is a product.

The proof of 12.9 is immediate. (Compare Milnor [1964].)

REMARK. According to Higman the ring $Z\Pi$ has a nontrivial unit unless Π has exponent 2, 3, 4, or 6. (See §6.5.) If Π does have exponent 2, 3, 4, or 6 then of course Wh(Π) = 0.

To conclude the discussion of special manifolds, here are some further results whose proofs will be left as exercises for the reader.

ASSERTION 1. A homotopy equivalence between *even dimensional* special manifolds is always a simple homotopy equivalence.

(I do not know whether $\Delta(M) \sim 1$ for every even dimensional special manifold.)

ASSERTION 2. If X and Y are special complexes then $\Delta(X \times Y) \sim 1$. (Compare Kwun and Szczarba [1965].)

ASSERTION 3. If M is an odd dimensional closed orientable manifold and if the *R*-torsion $\Delta_h(M)$ is defined for some representation h such that

$$h_*: \mathrm{Wh}(\Pi) \to \mathbb{R}^+$$

is nontrivial, then there are infinitely many distinct manifolds in the h-cobordism class of M. ("Distinct" in the sense that no two are related by a diffeomorphism which is compatible with the given identification of fundamental groups.)

Theorem 12.8 suggests the importance of finding out precisely what units exist within the ring $\mathbb{Z}\Pi$. Here is a preliminary estimate when Π is cyclic of order m > 2. Let r_1, \dots, r_n and s_1, \dots, s_p be prime to m.

LEMMA 12.10. There exists a unit u of ZII satisfying the equation

 $(t^{r_1}-1)\cdots(t^{r_n}-1)=u(t^{s_1}-1)\cdots(t^{s_p}-1)$

if and only if n = p and

$$r_1 \cdots r_n \equiv \pm s_1 \cdots s_n \pmod{m}$$
.

This unit u is uniquely determined, if it exists. Furthermore the canonical homomorphism $Z\Pi \rightarrow Z$ carries u to $u(1) = \pm 1$; where

$$u(1) \equiv r_1 \cdots r_n/s_1 \cdots s_n \pmod{m}.$$

(Compare the homotopy classification theorem 12.1.)

PROOF. First suppose that u exists and that n = p. Let $r_i \equiv s_i x_i \pmod{m}$ with $x_i > 0$. Since each $(t^{*i} - 1)$ is a unit modulo Σ we can divide to obtain

$$u \equiv \prod_{i=1}^{n} (1 + t^{s_i} + t^{2s_i} + \cdots + t^{(x_i-1)s_i}) \pmod{\Sigma};$$

or, more precisely,

(1)
$$u \equiv \prod (1 + t^{\mathfrak{s}_i} + \cdots + t^{(x_i-1)\mathfrak{s}_i}) + k\Sigma$$

for some integer k. Mapping t into 1 this equality in $Z\Pi$ transforms into the equality

(2)
$$u(1) = x_1 \cdots x_n + km$$

in Z. This proves that

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$$u(1) \equiv x_1 \cdots x_n \equiv r_1 \cdots r_n/s_1 \cdots s_n \pmod{m}$$

where u(1) clearly must be ± 1 . Furthermore, since x_1, \dots, x_n are given, and m > 2, the equality (2) can be solved uniquely for k. Plugging this value of k into (1) we have shown that u is uniquely determined.

Conversely suppose that we are given r_1, \dots, r_n and s_1, \dots, s_n satisfying the required congruence. The above argument shows that there exist unique elements u and v of $Z\Pi$ satisfying the conditions

$$(t^{r_1}-1)\cdots(t^{r_n}-1) = u(t^{s_1}-1)\cdots(t^{s_n}-1),$$

 $(t^{s_1}-1)\cdots(t^{s_n}-1) = v(t^{r_1}-1)\cdots(t^{r_n}-1)$

and

$$u(1) = v(1) = \pm 1.$$

Multiplying the first equation by v this implies that

$$(t^{s_1}-1)\cdots(t^{s_n}-1)=uv(t^{s_1}-1)\cdots(t^{s_n}-1).$$

But, by the uniqueness statement, this is only possible if uv=1. Therefore u is a unit.

To complete the proof we need only exclude the case $n \neq p$. But if, say, n < p, then dividing as above we would obtain

$$\prod_{1}^{n} (1 + t^{s_{i}} + \cdots + t^{(x_{i}-1)s_{i}}) \equiv u \prod_{n+1}^{p} (t^{s_{i}} - 1) \pmod{\Sigma}$$

Mapping t into 1 this would imply

$$x_1 \cdots x_n \equiv \pm 0 \pmod{m},$$

which is impossible.

REMARK. Bass [to appear] has shown that the units described by Lemma 12.10 generate a subgroup of at most finite index in Wh(II).

Now let us look at the question of cobordism between lens spaces. Atiyah and Bott (unpublished) have obtained an extraordinary new fixed point formula which can be used to prove the following. Let Gbe a compact group which operates smoothly on a sphere or homology sphere Σ^n with two fixed points p and q, the action being free except at p and q.

THEOREM 12.11. If these hypotheses are satisfied, then the action of G on the tangent space of Σ^n at p is equivalent to the action at q.

In other words the group representation $G \rightarrow GL(n, R)$ obtained from the action at p is equivalent to that obtained from the action at q.

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Part of the proof of 12.11 is based on the Franz lemma 12.6. However the main part of the argument involves the Atiyah-Bott fixed point formula for elliptic operators. No details will be given (although we will give the proof of a substantially weaker result in §12.15).

COROLLARY 12.12. If two lens spaces are related by an h-cobordism which is compatible with the preferred generators and orientations, then they are actually isomorphic.

PROOF. Let $(W; L_1, L_2)$ be an *h*-cobordism between lens spaces of dimension 2n-1. Then the universal covering manifold \hat{W} provides an *h*-cobordism between the spheres \hat{L}_1 and \hat{L}_2 . The group $\pi_1 L_1 \cong \pi_1 W$ $\cong \pi_1 L_2 = \Pi$ of covering transformations operates orthogonally on these two spheres. Hence we can attach one 2n-disk to \hat{W} along \hat{L}_1 and another along \hat{L}_2 and extend the action of Π , by letting Π operate orthogonally on the disks D_1^{2n} and D_2^{2n} . The union $\hat{W} \cup D_1^{2n} \cup D_2^{2n}$ can be given a compatible smoothness structure; and is clearly a homology sphere. Applying the Atiyah-Bott theorem 12.11 we see that the orthogonal action of Π on D_1^{2n} is equivalent to the action on D_2^{2n} ; and hence that L_1 is equivalent to $\pm L_2$.

In fact the sign must be +. For otherwise there would exist a homotopy equivalence $L_1 \rightarrow -L_1$ preserving orientation and preferred generator. But this is impossible by 12.1.

COROLLARY 12.13. Any h-cobordism (W; L, L') between lens spaces must have trivial torsion. Hence (if the dimension is ≥ 5) the manifold W must be diffeomorphic to $L \times [0, 1]$.

PROOF. This follows from 12.12 and 12.8.

It is essential for these results that L and L' should be precisely lens spaces. Here is an example of an *h*-cobordism (W; L, M) with $\tau(W, L) \neq 0$, where M is a manifold which is indistinguishable from a certain lens space L' by all of the more obvious tests.

EXAMPLE 12.14. Let $L = L_{35}(1, 1, 1, 1, 1)$ and $L' = L_{35}(1, 6, 6, 6, 6)$. These nine dimensional lens spaces with $\pi_1 \cong T_{35}$ are not *h*-cobordant to each other. Nevertheless *L* is *h*-cobordant to a manifold *M* which has the same simple homotopy type and the same tangent bundle as L'.

PROOF. By 12.10, since $6^2 \equiv 1 \mod 35$, there exists a unit u of $\mathbb{Z}\Pi$ so that

$$(t^6-1)^2 = u(t-1)^2.$$

By 12.8 there is an *h*-cobordism (W; L, M) starting from L, and having

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$$\Delta(M) \sim u^2 \Delta(L) = u^2 (t-1)^5$$

= $(t^6 - 1)^4 (t-1) \sim \Delta(L').$

According to 12.1 there does exist a homotopy equivalence

 $f: M \to L'$.

Furthermore it follows from 12.5 that f is a simple homotopy equivalence. We will prove that the induced bundle

 $f^*(\text{tangent bundle of } L')$

is isomorphic to the tangent bundle of M. The obstructions to the existence of such an isomorphism lie in the cohomology groups

 $H^k(M; \pi_{k-1}(\mathrm{SO}_q)).$

Thus there are obstructions in dimensions 4, 8 (namely the differences of Pontrjagin classes) and in dimension 9. It follows from 12.2 that the Pontrjagin classes do not distinguish M from L'. But the 9-dimensional obstruction is an element of order 2, and hence is not destroyed if we pass to the 35-fold covering space. It follows easily that all of the obstructions are zero; which completes the proof of 12.14.

Thus 12.12 and 12.13 definitely cannot be proved, using only the methods of the present paper. Nevertheless we will persevere, and see how far it is possible to get making use only of torsions and tangent bundles.

Let (W; L, L') be an *h*-cobordism between two lens spaces with fundamental group of order m.

THEOREM 12.15. If m is prime and less than 163, then the torsion $\tau(W, L)$ is zero. More generally the same result will be true if L and L' are replaced by any manifolds having the simple homotopy types and the same Pontrjagin classes as suitable lens spaces.¹⁰

The proof of 12.15 will occupy the rest of §12.

REMARK. The present proof works for many larger primes, but it definitely breaks down for the case m = 163.

The following holds without restriction on m.

LEMMA 12.16. If the indices r_i are equal in pairs, say $L = L(r_1, r_1, r_2, r_2, \cdots, r_k, r_k)$ with n = 2k and correspondingly $L' = L(s_1, s_1, s_2, s_2, \cdots, s_k, s_k)$, then there cannot exist an orientation reversing h-cobordism from L to L'.

¹⁰ Similar generalizations apply throughout the remainder of §12.

COROLLARY. There cannot exist an orientation reversing h-cobordism from $L(r_1:r_1:r_2:r_2:\cdots:r_k:r_k)$ to itself.

(In contrast if *n* is odd then every lens space $L(r_1: \cdots : r_n)$ admits an orientation reversing diffeomorphism. Similarly, if $r^2 \equiv -1 \pmod{m}$, then the 3-dimensional lens space

$$L(1: r) \approx L(r: r^2) \approx L(-1: r)$$

admits an orientation reversing diffeomorphism.)

PROOF OF 12.16. For an orientation reversing h-cobordism, the homotopy type classification theorem implies that

$$r_1r_1\cdots r_kr_k\equiv -s_1s_1\cdots s_ks_k \pmod{m}.$$

In particular, -1 must be a quadratic residue modulo m.

On the other hand for an *h*-cobordism we must have

$$(t^{r_1}-1)^2\cdots(t^{r_k}-1)^2=\pm t^a u^2(t^{s_1}-1)^2\cdots(t^{s_k}-1)^2$$

by 12.8. And by 12.10 the sign which occurs here must also be a minus sign. We will show that this is impossible.

Note that m must have an odd prime factor. For otherwise m would be divisible by 4; and hence -1 would not be a quadratic residue. Map $Z\Pi$ into a cyclotomic number field by mapping t into an odd root of unity ξ . Then

$$(\xi^{r_1}-1)^2\cdots(\xi^{r_k}-1)^2=-\xi^au(\xi)^2(\xi^{s_1}-1)^2\cdots(\xi^{s_k}-1)^2.$$

Thus $-\xi^{a}$ can be expressed as a square within the field $Q[\xi]$; and hence -1 can be expressed as a square. But in an odd cyclotomic field this is impossible, q.e.d.

The proof of Theorem 12.15 will depend on some results from algebraic number theory. Let ξ denote a primitive *m*th root of unity, with m = 2d + 1 prime. Let *U* denote the group of units in the ring $\boldsymbol{Z}[\xi]$ of cyclotomic integers. Then it is known classically that

(1) U is a finitely generated group of rank d-1.

(2) The only elements of finite order in U are the roots of unity $\pm \xi^k$.

(3) The "cyclotomic units" $(\xi^r - 1)/(\xi - 1) \in U$, with $1 < r \le d$, satisfy no multiplicative relations. (Compare Kummer [1851], or the Independence Lemma 12.6.) Hence they generate a subgroup of finite index in U.

Let U_0 denote the subgroup generated by the cyclotomic units together with $\pm \xi$. The index of U_0 in U will be denoted by $h_2(m)$. In the customary terminology $h_2(m)$ is called the "second factor of the class number" for the cyclotomic field $\mathcal{Q}[\xi]$. LEMMA 12.17 (KUMMER.) For all primes m less than 163 the index $h_2(m)$ is an odd integer. However $h_2(163)$ is even.

PROOF. Kummer showed in [1851] that the number of ideal classes in the ring $\mathbf{Z}[\xi]$ can be expressed as a product h_1h_2 of integers, where h_2 is equal to the index $[U: U_0]$ as just described,¹¹ and where h_1 is given by an explicit numerical formula. He tabulated the values of $h_1(m)$ for m < 100. A more extensive tabulation, for $m \leq 257$, has been given by Schrutka v. Rechtenstamm [1964]. Within this range, and for m prime, only

$$h_1(29) = 8,$$

 $h_1(113) = 1,612,072,001,362,952,$
 $h_1(163) = 2,708,534,744,692,077,051,875,131,636$

and

 $h_1(197), h_1(239)$

are even.¹²

In [1870] Kummer proved that the second factor $h_2(m)$ can be even only if $h_1(m)$ is even. He made a particular study of the cases m=29, 113 and 163; showing that $h_2(29)$ and $h_2(113)$ are odd, but that $h_2(163)$ is even. (In fact, he gave an explicit example of an element of order 2 in U/U_0 for m=163.) This completes the proof of 12.17.

REMARK 12.18. The numbers $h_2(m)$ seem extraordinarily difficult to compute. However it is known that

$$h_2(m) = h_1(m) = 1$$

for $m \leq 19$. (See Minkowski [1891, p. 296] as well as Wolfskehl [1886] and Kummer [1851, p. 472].) It has been conjectured that $h_2(m) = 1$ for all m < 97. (See Schrutka v. Rechtenstamm [1964, p. 4].) For further information see Hasse [1952], and Vandiver and Wahlin [1928].

Now consider the group ring $Z\Pi$ where Π is cyclic of prime order m=2d+1.

LEMMA 12.19. Suppose that $h_2(m)$ is odd. If the equality

(1)
$$(t^{r_1}-1)\cdots(t^{r_n}-1)=\pm t^a u^2(t^{s_1}-1)\cdots(t^{s_n}-1)$$

¹¹ Alternatively h_2 is equal to the number of ideal classes in the real subring $Z[\xi+\bar{\xi}]$ of the cyclotomic field. For a modern account see Hasse [1952].

¹² The last two numbers are very roughly equal to 6×10^{80} and 2×10^{49} respectively. They are divisible by 2^3 and 2^6 respectively.

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holds for some unit u of $\mathbf{Z}\Pi$, where

(2)
$$1 \leq r_1 \leq \cdots \leq r_n \leq d, \quad 1 \leq s_1 \leq \cdots \leq s_n \leq d$$

then the 2n numbers $r_1, \dots, r_n, s_1, \dots, s_n$ must be equal in pairs. Furthermore the congruence

$$r_1 \cdots r_n \equiv s_1 \cdots s_n \pmod{m}$$

must be satisfied.

PROOF. Mapping t into ξ we obtain a corresponding equality involving a unit $u(\xi)$ of $Z[\xi]$. Clearly $u(\xi)^2$ belongs to the subgroup $U_0 \subset U$ generated by cyclotomic units. Since the order $h_2(m)$ of U/U_0 is odd, this implies that $u(\xi)$ itself belongs to U_0 . The statement that the numbers $r_1, \dots, r_n, s_1, \dots, s_n$ are equal in pairs now follows by inspection, making use of 12.6.

Now the proof of 12.16 can be used to show that the plus sign must hold in Equation (1). In other words the congruence $r_1 \cdots r_n \equiv +s_1 \cdots s_n$ must be satisfied. This proves Lemma 12.19.

EXAMPLE. If n=2 then the statement that the numbers r_1 , r_2 , s_1 , s_2 are "equal in pairs" means that either

$$r_1 = s_1, \qquad r_2 = s_2$$

or

 $r_1=r_2, \qquad s_1=s_2.$

(The third possibility: $r_1 = s_2$, $r_2 = s_1$ may be ignored because of our assumption that $r_1 \leq r_2$, $s_1 \leq s_2$.) But if $r_1 = r_2$, $s_1 = s_2$ then the congruence $r_1r_2 \equiv s_1s_2$ implies (since *m* is prime) that $r_1 \equiv \pm s_1$ and hence that $r_1 = s_1$. Thus in any case we must have

 $r_1 = s_1, \qquad r_2 = s_2$

so that $L(r_1, r_2) = L(s_1, s_2)$. This proves Theorem 12.15 for the case n=2.

PROOF OF 12.15 FOR n > 2. Setting the total Pontrjagin class of L equal to the total Pontrjagin class of L' we obtain

(3)
$$(1 + x^2 r_1^{-2}) \cdots (1 + x^2 r_n^{-2}) = (1 + x^2 s_1^{-2}) \cdots (1 + x^2 s_n^{-2})$$

where $x^k \in H^{2k}(L; \mathbb{Z})$ is an element of order *m* for k < n, and is zero for $k \ge n$.

The following result will be proved by induction on n.

LEMMA 12.20. If Equations (1), (2) and (3) hold, and if $h_2(m)$ is odd, then $r_1 = s_1, \dots, r_n = s_n$.

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The proof will be divided into two cases. It follows immediately from Lemma 12.19 that these two cases exhaust all of the possibilities.

Case 1. Suppose that some r_i is equal to some s_j . Then dividing Equation (1) by the equality $(t^{r_i}-1) = (t^{s_j}-1)$, and dividing Equation (3) by the equality $(1+x^2r_i^{-2}) = (1+x^2s_j^{-2})$ we obtain corresponding equalities with n replaced by n-1. (The reader should verify that both divisions are legitimate.) Hence the desired conclusion follows from the induction hypothesis.

Case 2. Suppose that $r_1 = r_2$, $r_3 = r_4$, \cdots , $r_{n-1} = r_n$ and that $s_1 = s_2$, \cdots , $s_{n-1} = s_n$, where n = 2k. It will be convenient to introduce the abbreviations

$$a_i \equiv r_{2i}^{-2}, \qquad b_j \equiv s_{2j}^{-2} \pmod{m},$$

so that

$$(3') \quad (1 + a_1 x^2)^2 \cdots (1 + a_k x^2)^2 = (1 + b_1 x^2)^2 \cdots (1 + b_k x^2)^2.$$

Since m is odd, note that every mixed cohomology class of the form

$$1 + c_1 x + c_2 x^2 + \cdots \in \sum H^{2i}(L; \mathbb{Z})$$

has a unique square root $1+d_1x+d_2x^2+\cdots$ of the same form. That is the congruences

$$c_1 \equiv 2d_1, \quad c_2 \equiv 2d_2 + d_1^2, \quad c_3 \equiv 2d_3 + 2d_1d_2, \cdots$$

have a unique solution. Therefore we can take the square root of Equation (3') to obtain

$$(1 + a_1x^2) \cdots (1 + a_kx^2) = (1 + b_1x^2) \cdots (1 + b_kx^2).$$

Since $x^{2i} \neq 0$ for i < k this proves that the *i*th elementary symmetric function of a_1, \dots, a_k is congruent to the *i*th elementary symmetric function of b_1, \dots, b_k for i < k. But the congruence

$$a_1 \cdot \cdot \cdot a_k \equiv b_1 \cdot \cdot \cdot b_k \pmod{m}$$

for the kth elementary symmetric function is also valid, by Lemma 12.19.

Consider the polynomials

$$(y - a_1)(y - a_2) \cdots (y - a_k)$$
 and $(y - b_1)(y - b_2) \cdots (y - b_k)$

in one variable over the field Z_m . Since the corresponding elementary symmetric functions are all equal, we have

$$(y - a_1)(y - a_2) \cdots (y - a_k) = (y - b_1)(y - b_2) \cdots (y - b_k).$$

According to the unique factorization theorem for polynomials over Z_m this is only possible if $\{a_1, \dots, a_k\}$ is a permutation of

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 $\{b_1, \cdots, b_k\}$. But if, say, $a_1 \equiv b_j \pmod{m}$ then $r_2^2 \equiv s_{2j}^2$, hence $r_2 \equiv \pm s_{2j}$, hence $r_2 \equiv s_{2j}$ (making use of (2)).

Thus Case 2 has been reduced to Case 1. This completes the proof of Lemma 12.20, and therefore completes the proof of the Theorem 12.15.

Appendix 1. The congruence subgroup theorem. Let A be a commutative ring, and $\mathfrak{a} \subset A$ an ideal such that the quotient ring A/\mathfrak{a} is finite. The kernel of the natural homomorphism

$$SL(n, A) \rightarrow SL(n, A/a)$$

will be denoted by $N_{\mathfrak{a}}$, and called the *congruence subgroup* corresponding to \mathfrak{a} . Clearly $N_{\mathfrak{a}}$ is a normal subgroup of finite index in SL(n, A).

DEFINITION. The group SL(n, A) satisfies the congruence subgroup theorem if every subgroup of finite index in SL(n, A) contains such a congruence subgroup.

This theorem is true for $SL(n, \mathbb{Z})$ providing that $n \ge 3$. (See Bass, Lazard and Serre [1964]; or Mennicke [1965].) It is not true however for $SL(2, \mathbb{Z})$. (See for example Reiner [1958].)

Now let 0 be the ring of integers in an algebraic number field.

ASSERTION. If n is sufficiently large, then SL(n, 0) satisfies the congruence subgroup theorem.*

This result has been claimed by Mennicke [1965, p. 37]; and by Bass (unpublished). Assuming that it is true, we will prove the following.

THEOREM 1.6. If Π is a finite abelian group, then $SK_1(\mathbb{Z}\Pi) = 0$.

The proof (due to Bass) will be based on five lemmas.

LEMMA 1. If $SL(n, A_1)$ and $SL(n, A_2)$ both satisfy the congruence subgroup theorem, then so does $SL(n, A_1 \times A_2)$.

PROOF. This follows easily from the natural isomorphism

 $SL(n, A_1 \times A_2) = SL(n, A_1) \times SL(n, A_2).$

Consider next a ring A and a subring $A_0 \subset A$. Suppose that the

^{*} Added in proof. At this date (April, 1966) it is not at all sure that this assertion is true for all number fields.

additive group of A is finitely generated, and that A_0 is (additively) a subgroup of finite index, say λ , in A.

LEMMA 2. If SL(n, A) satisfies the congruence subgroup theorem, then so does $SL(n, A_0)$.

PROOF. Note that $SL(n, A_0)$ is a subgroup of finite index in SL(n, A). In fact $SL(n, A_0)$ clearly contains the congruence subgroup which corresponds to the ideal $\lambda A \subset A$. The rest of the argument is now quite easy.

Let Π be a finite abelian group with k elements.

LEMMA 3. If n is sufficiently large, then $SL(n, \mathbb{Z}\Pi)$ satisfies the congruence subgroup theorem.

PROOF. The semisimple algebra $Q\Pi$ is isomorphic to a cartesian product of fields:

$$Q\Pi \cong F_1 \times \cdots \times F_q$$

Let \mathcal{O}_i be the ring of integers in the number field F_i . Then clearly $\mathbb{Z}\Pi$ is a subring of the product $\mathcal{O}_1 \times \cdots \times \mathcal{O}_q$. The additive group of this product ring is clearly \mathbb{Z} -free of rank k. Similarly the additive group of $\mathbb{Z}\Pi$ is free of rank k.

Choose *n* so large that each of the groups $SL(n, O_i)$ satisfies the congruence subgroup theorem. Then Lemmas 1 and 2 imply that $SL(n, \mathbb{Z}\Pi)$ must also satisfy the congruence subgroup theorem. This proves Lemma 3.

Finally we will need the following.

LEMMA 4. The group $SL(n, \mathbb{Z}\Pi)$ is finitely generated.

(Compare Siegel [1943], Borel and Harish-Chandra [1962, §6.12].) This is perhaps best proved by noting that $SL(n, \mathbb{Z}\Pi)$ is a subgroup of finite index in

$$\mathrm{SL}(n, \mathfrak{O}_1) \times \cdots \times \mathrm{SL}(n, \mathfrak{O}_q).$$

Since each $SL(n, O_i)$ is finitely generated by a theorem of Hurwitz [1895], the conclusion follows.

LEMMA 5. If n is sufficiently large, then the group $SL(n, \mathbb{Z}\Pi)$ is equal to its own commutator subgroup.

PROOF. Otherwise $SL(n, \mathbb{Z}\Pi)$ could be mapped homomorphically onto some finite, nontrivial abelian group G, making use of Lemma 4. The kernel of this homomorphism would contain a congruence subgroup $N_{\mathfrak{a}}$, by Lemma 3. Hence the quotient

 $SL(n, \mathbf{Z}\Pi)/N_{\mathfrak{a}}$

would also map homomorphically onto G.

Recall that $N_{\mathfrak{a}}$ is defined by the exact sequence

$$0 \to N_{\mathfrak{a}} \to \mathrm{SL}(n, \mathbb{Z}\Pi) \xrightarrow{j} \mathrm{SL}(n, \mathbb{Z}\Pi/\mathfrak{a}).$$

But $Z\Pi/\mathfrak{a}$ is a finite ring; and so has only finitely many maximal ideals. An easy argument then shows that the group $SL(n, Z\Pi/\mathfrak{a})$ is generated by elementary matrices. (Compare Bass, Lazard, Serre [1964, Lemme 1], as well as §1.4.) Hence the homomorphism j must be onto. Furthermore the group

$$\operatorname{SL}(n, \mathbb{Z}\Pi)/N_{\mathfrak{a}} \cong \operatorname{SL}(n, \mathbb{Z}\Pi/\mathfrak{a})$$

must be equal to its own commutator subgroup (assuming that $n \ge 3$). It follows that this group *cannot* map homomorphically onto the abelian group G. This contradiction completes the proof of Lemma 5.

Since Theorem 1.6 clearly follows from Lemma 5, this completes the argument.

Appendix 2. The group K_0A of virtual projective A-modules. Closely related to K_1 is the functor K_0 which is defined as follows. For each ring A let K_0A be the additive group having one generator (P) for each finitely generated projective module P over A, and one relation

$$(P \oplus Q) = (P) + (Q)$$

for each pair of finitely generated projectives.¹³ Note that any ring homomorphism $h: A \rightarrow A'$ gives rise to a group homomorphism

$$h_*\colon K_0A\to K_0A'$$

where

$$h_*(P) = (A' \bigotimes_A P).$$

Thus K_0 is a covariant functor from rings to additive groups.

(If A happens to be commutative then the product operation

$$(P)(Q) = (P \bigotimes_{A} Q)$$

makes K_0A into a ring. Thus K_0 can also be considered as a functor from commutative rings to commutative rings.)

The class of the free A-module of rank 1 generates a cyclic subgroup of K_0A . The quotient

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¹³ In other words K_0A is the "Grothendieck group" associated with the category of finitely generated projectives over A.

$$K_0A/($$
subgroup generated by free modules $)$

is called the *projective class group* \tilde{K}_0A . (Serre [1958], Rim [1961].) Clearly \tilde{K}_0 is also a covariant functor. Here are some examples.

EXAMPLE 1. If A is a simple algebra then K_0A is infinite cyclic, and \tilde{K}_0A is finite cyclic.

EXAMPLE 2. If A is a Dedekind ring then \tilde{K}_0A can be identified with the ideal class group of A. (See Kaplansky [1952], Rim [1959].) The ring K_0A splits additively as a direct sum

$$K_{0}A \cong \mathbf{Z} \oplus \widetilde{K}_{0}A,$$

where $\tilde{K}_0 A$ is an ideal, and where the product of any two elements in $\tilde{K}_0 A$ is zero. More generally:

EXAMPLE 3. If A is any ring which admits a homomorphism into a skew-field F then the homomorphisms

 $\mathbf{Z} \to A \to F$

give rise to a direct sum decomposition

$$K_0A \cong \mathbf{Z} \oplus \tilde{K}_0A.$$

EXAMPLE 4. Let T_p be the cyclic group of prime order p, and let $\xi = \exp(2\pi i/p)$. Then according to Rim [1959] the homomorphism

 $\mathbf{Z}T_p \to \mathbf{Z}[\xi]$

give rise to an isomorphism

$$\widetilde{K}_0 \mathbf{Z} T_p \to \widetilde{K}_0 \mathbf{Z}[\xi].$$

Thus $\tilde{K}_0 ZT_p$ is a finite group, with order equal to the class number of the cyclotomic field. These groups are trivial for p < 23; however¹⁴

$$\begin{split} \tilde{K}_0 ZT_{23} &\cong Z_3 \oplus (?), \\ \tilde{K}_0 ZT_{29} &\cong Z_2 \oplus Z_2 \oplus Z_2 \oplus (?), \\ \tilde{K}_0 ZT_{31} &\cong Z_9 \oplus (?), \\ \tilde{K}_0 ZT_{37} &\cong Z_{37} \oplus (?), \end{split}$$

and so on. These groups are surely nontrivial for all $p \ge 23$.

More generally consider the group ring $Z\Pi$ of an arbitrary multiplicative group.

EXAMPLE 5 (SWAN [1960]). If II is finite, then the projective class group $\tilde{K}_0(\mathbb{Z}\Pi)$ is also finite.

EXAMPLE 6 (BASS, HELLER AND SWAN [1964]). If II is free abelian, then $\tilde{K}_0(\mathbf{Z}\Pi) = 0$.

 $^{^{14}}$ See Kummer [1851] and [1860], as well as §12.18. Here (?) denotes a finite group which is probably zero.

In contrast, the following result has recently been obtained.

EXAMPLE 7 (M. P. MURTHY; UNPUBLISHED). If $\Pi = T \times T_p^2$ is the product of a free cyclic group and a cyclic group of order p^2 , then $\tilde{K}_0(\mathbb{Z}\Pi)$ contains infinitely many distinct elements of order p. In particular, this projective class group is not finitely generated.

To confuse matters, both K_0 and K_1 sometimes behave as covariant functors. Let

$$h: A \to A'$$

be a ring homomorphism with the special property that A' is finitely generated and projective when considered as a left A-module. Then every finitely generated projective module P over A' can be thought of as a finitely generated projective module h^*P over A. Thus one obtains a backwards homomorphism

$$h^* \colon K_0 A' \to K_0 A$$

which might be called the "transfer." Similarly a "transfer" homomorphism

$$h^* \colon K_1 A' \to K_1 A$$

can be defined.¹⁵

The precise affinity between K_0 and K_1 is a little difficult to explain. (See Bass [1964], as well as the thesis of Gersten [1965].) One relationship can be described as follows: Given rings $A \subset A'$ there exists an exact sequence of the form

$$K_1A \to K_1A' \to * \to K_0A \to K_0A'.$$

Here is a simple example. Let A be a Dedekind ring and F its quotient field. Then there is an exact sequence

$$K_1A \to K_1F \to G \to K_0A \to K_0F \to 0,$$

where G denotes the group of all fractional A-ideals in F.

For any commutative A it is possible to define¹⁶ a product operation

$$K_0A \otimes K_1A \to K_1A$$
,

making K_1A into a module over the ring K_0A .

¹⁵ Represent an arbitrary element of K_1A' by an automorphism α of the free module $A' \oplus \cdots \oplus A'$. Choose a projective A-module Q so that $h^*(A' \oplus \cdots \oplus A') \oplus Q$ is A-free. Now the automorphism $\alpha \otimes$ (identity) of this free module determines the required element of K_1A .

¹⁶ The product of an element $(P) \in K_0A$ and an element (α) of K_1A , where α denotes an automorphism of an A-free module M, is represented by the automorphism (identity_P) $\otimes \alpha$ of the projective module $P \otimes M$. (Compare the preceding footnote.)

Here is another example of a relation between K_0 and K_1 . Let T be an infinite cyclic group and Π an arbitrary group. Then according to Bass, Heller and Swan [1964, §5] there is a direct sum decomposition

$$K_1(\mathbf{Z}(T \times \Pi)) \cong K_1(\mathbf{Z}\Pi) \oplus K_0(\mathbf{Z}\Pi) \oplus (?),$$

where (?) denotes an unknown group. Hence

$$\operatorname{Wh}(T \times \Pi) \cong \operatorname{Wh}(\Pi) \oplus \widetilde{K}_0(\mathbb{Z}\Pi) \oplus (?).$$

If Π is finite abelian of order m, then Bass has recently shown that the unknown third summand is an m-primary group.

As an example suppose that II is the cyclic group T_{23} of order 23. Then Wh(II) is free abelian of rank 10. The projective class group $\tilde{K}_0(\mathbf{Z}T_{23})$ is isomorphic to the ideal class group of $\mathbf{Q}[\exp(2\pi i/23)]$ and hence (presumably) is cyclic of order 3. (Example 4 above.) Thus

$$\mathrm{Wh}(\mathbf{Z}(T \times T_{23})) \cong 10\mathbf{Z} \oplus \mathbf{Z}_3 \oplus (?).$$

The conjugation operation can be explicitly computed in this case. It turns out to be multiplication by -1 on the Z_3 summand, and multiplication by +1 on the $Z \oplus \cdots \oplus Z$ summand.

As a second example let $\Pi = T \times T_{p^2}$ where p is prime. Using Example 7 above (M. P. Murthy) we see that the Whitehead group

$$Wh(T \times \Pi) = Wh(T \times T \times T_p^2)$$

is not finitely generated.

The geometric applications of the functor K_1 are strikingly paralleled in Wall's theory of obstructions to finiteness for CW-complexes. Let X be a topological space which is dominated by a finite CWcomplex. Then Wall defines an obstruction

$$\sigma \in K_0(\mathbf{Z}\pi_1(X))$$

which vanishes if and only if X has the homotopy type of a finite CW-complex. (Wall [1965]. See also Siebenmann [1965].) This obstruction can be considered as a generalization of the familiar Euler characteristic.

Here is a quite different example from topology. Let C^x denote the ring of continuous complex valued functions on a compact space X. Then every finitely generated projective module over C^x is isomorphic to the module of sections of a unique complex vector bundle over X. (Swan [1962].) Hence $K_0 C^x$ can be identified with the

Atiyah-Hirzebruch group $K^{0}X$ of virtual complex vector bundles over X. (See Atiyah and Hirzebruch [1959], Adams [1962].)

Similarly the special Whitehead group $SK_1(\mathbf{C}^{\mathbf{x}})$ is isomorphic to the group of all homotopy classes of mappings from X to the infinite special linear group SL(C). This group of homotopy classes is intimately related to the Atiyah-Hirzebruch group $K^{-1}X$.

Similarly the functors K_0 and K_1 applied to the ring $\mathbb{R}^{\mathbb{X}}$ of continuous real valued functions on X closely related to the Atiyah-Hirzebruch groups $KO^0(X)$ and $KO^{-1}(X)$. Consider for example a space X and a matrix

$$(a_{ij}) \in \mathrm{SL}(n, \mathbf{R}^{\mathbf{X}}).$$

Then the correspondence

 $x \mapsto (a_{ij}(x))$

maps X into SL(n, R). Clearly any elementary row operation on the matrix induces a homotopy of the corresponding mapping.

EXAMPLE. Let X be the unit circle in the plane, and let

 $x, y \in R^{X}$

denote the two coordinate mappings. Then the matrix

$$\begin{pmatrix} x & y \\ -y & x \end{pmatrix} \in \mathrm{SL}(2, \mathbf{R}^{\mathbf{X}}) \subset \mathrm{SL}(\mathbf{R}^{\mathbf{X}})$$

determines a mapping

$$X \to \mathrm{SL}(2, \mathbb{R}) \subset \mathrm{SL}(\mathbb{R})$$

which clearly represents a generator for the group $\pi_1 SL(R)$. (Recall that $\pi_1 SL(R) \cong \pi_1 O$ is cyclic of order 2.) It follows that the matrix

$$\begin{pmatrix} x & y \\ -y & x \end{pmatrix}$$

over R^x can not be expressed as a product of elementary matrices. This conclusion follows a fortiori if we restrict attention to the subring

 $R[x, y] \subset R^{\mathbf{X}}$.

(Compare §1.7.)

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