ROOTS OF POLYNOMIALS AND QUADRATIC FORMS

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Introduction

- In 1829 Sturm proved a theorem calculating the number of real roots of a non-zero real polynomial P(X) ∈ ℝ[X] in an interval [a, b] ⊂ ℝ, using the Euclidean algorithm in ℝ[X] and counting sign changes.
- In 1853 Sylvester interpreted Sturm's theorem using continued fractions and the signature of a tridiagonal quadratic form.
- The survey paper of Étienne Ghys and A.R. http://arxiv.org/abs/1512.09258 Signatures in algebra, topology and dynamics includes a modern interpretation of the results of Sturm and Sylvester in terms of the "Witt group" of stable isomorphism classes of invertible symmetric matrices.

Jacques Charles François Sturm (1803-1855)



Sturm's problem

- Problem How many real roots of P(X) ∈ ℝ[X] are there in an interval [a, b] ⊂ ℝ? At the time, this was a major problem in analysis, algebra and numerical mathematics.
- Sturm's formula The Euclidean algorithm in ℝ[X] for finding the greatest common divisor of P₀(X) = P(X) and P₁(X) = P'(X) gives the Sturm sequences of polynomials

 $(P_*(X), Q_*(X)) = ((P_0(X), \dots, P_n(X)), (Q_1(X), \dots, Q_n(X)))$

with remainders $P_j(X)$ and quotients $Q_j(X)$, such that

$$\begin{split} &\deg(P_{j+1}(X)) < \deg(P_j(X)) \leqslant n-j \ (0 \leqslant j \leqslant n) \ , \\ &P_{j-1}(X) + P_{j+1}(X) \ = \ P_j(X)Q_j(X) \ (1 \leqslant j \leqslant n) \ . \end{split}$$

Sturm's formula expressed the number of real roots of P(X) in [a, b] in terms of the variation (= number of sign changes) in P_{*}(a) and P_{*}(b), assuming regularity.

The Euclidean algorithm

The Euclidean algorithm for the greatest common divisor of integers π₀ ≥ π₁ ≥ 1 is the sequence pair

 $\pi_0 \geqslant \pi_1 > \cdots > \pi_n > \pi_{n+1} = 0$, $\rho_0, \rho_1, \dots, \rho_n > 0$ with

$$\pi_{j-1} = \pi_j \rho_j + \pi_{j+1} (1 \le j \le n) ,$$

$$\rho_j = \lfloor \pi_{j-1}/\pi_j \rfloor = \text{quotient when dividing } \pi_{j-1} \text{ by } \pi_j ,$$

$$\pi_{j+1} = \text{remainder} , \pi_n = \text{g.c.d.}(\pi_0, \pi_1) .$$

the sequences $(\pi_0/\pi_1, \pi_1/\pi_2, \dots, \pi_n, 1/\pi_n) (\rho_1, \rho_2, \dots, \rho_n)$

► The sequences $(\pi_0/\pi_1, \pi_1/\pi_2, \dots, \pi_{n-1}/\pi_n)$, $(\rho_1, \rho_2, \dots, \rho_n)$ determine each other by

$$\frac{\pi_{j-1}}{\pi_j} = \rho_j + \frac{1}{\rho_{j+1} + \frac{1}{\frac{1}{\rho_{j+2} + \cdots + \frac{1}{\rho_n}}}}, \ \rho_j = \frac{\pi_{j-1}}{\pi_j} - \frac{\pi_{j+1}}{\pi_j}$$

Euclidean pairs

- ▶ **Definition** A sequence $p_* = (p_0, p_1, ..., p_n)$ of $p_j \in \mathbb{R}$ is regular if $p_j \neq 0 \in \mathbb{R}$ for $0 \leq j \leq n$.
- ▶ Definition A Euclidean pair (p_{*}, q_{*}) consists of two regular sequences p_{*} = (p₀, p₁,..., p_n), q_{*} = (q₁, q₂,..., q_n) in ℝ satisfying the identities

$$p_{j-1} + p_{j+1} = p_j q_j \in \mathbb{R} \ (1 \leq j \leq n, \ p_{n+1} = 0) \ .$$

• **Example** For integers $\pi_0 \ge \pi_1 \ge 1$ the Euclidean algorithm sequences $(\pi_0, \pi_1, \dots, \pi_n)$, $(\rho_1, \rho_2, \dots, \rho_n)$ determine a Euclidean pair (p_*, q_*) by

$$p_j = (-1)^{j(j-1)/2} \pi_j , q_j = \rho_j .$$

Variation and regularity

▶ **Definition** The **variation** of a regular sequence $p_* = (p_0, p_1, ..., p_n)$ in \mathbb{R} is

$$\operatorname{var}(p_*) = \operatorname{number} \operatorname{of} \operatorname{changes} \operatorname{of} \operatorname{sign} \operatorname{in} p_*$$

= $\left(n - \sum_{j=1}^n \operatorname{sign}(p_{j-1}/p_j)\right)/2 \in \{0, 1, \dots, n\}$.

- ▶ Definition A polynomial P(X) ∈ ℝ[X] is regular if it has no repeated roots.
- **Definition** A point $t \in \mathbb{R}$ is **regular** for $P(X) \in \mathbb{R}[X]$ if

$$P_*(t) = (P_0(t), P_1(t), \dots, P_n(t)),$$

is a regular sequence in \mathbb{R} .

Sturm's Theorem (1829)

Theorem The number of real roots of a regular P(X) ∈ ℝ[X] in [a, b] ⊂ ℝ for regular a < b is</p>

 $|\{x \in [a,b] | P(x) = 0 \in \mathbb{R}\}| = \operatorname{var}(P_*(a)) - \operatorname{var}(P_*(b))$.

▶ Idea of proof Let $a = t_0 < t_1 < t_2 < \cdots < t_{N-1} < t_N = b$ be the partition of [a, b] at the points $t_1 < t_2 < \cdots < t_{N-1}$ which are not regular. For each $i \in \{1, 2, \dots, N-1\}$ there is a unique $j_i \in \{0, 1, \dots, n-1\}$ such that

$$P_{j_i}(t_i) \;=\; 0 \;,\; P_k(t_i)
eq 0 \; ext{for} \; k
eq j_i \;.$$

The function

$$[a,b] \rightarrow \{0,1,\ldots,n\}$$
; $t \mapsto \operatorname{var}(P_*(a)) - \operatorname{var}(P_*(t))$

is constant for $t \in (t_i, t_{i+1})$. The jump is 1 at t_i with $j_i = 0$, i.e. at the real roots of P(X). The jump is 0 at t_i with $j_i \ge 1$, since $p_{j_i-1}(t_i) + p_{j_i+1}(t_i) = p_{j_i}(t_i)q_{j_i}(t_i) = 0$ with the first two terms $\ne 0$.

James Joseph Sylvester (1814-1897)



Sylvester's papers related to Sturm's theorem

- On the relation of Sturm's auxiliary functions to the roots of an algebraic equation. (1841)
- A demonstration of the theorem that every homogeneous quadratic polynomial is reducible by real orthogonal substitutions to the form of a sum of positive and negative squares. (1852)
- On a remarkable modification of Sturm's Theorem (1853)
- On a theory of the syzygetic relations of two rational integral functions, comprising an application to the theory of Sturm's functions, and that of the greatest algebraical common measure. (1853)
- Sylvester used continued fractions to express Sturm's formula in terms of the signatures of tridiagonal symmetric forms. In fact, the signature was developed for just this purpose!

Cauchy's Spectral Theorem (1829)

• **Definition** The **transpose** of an $n \times n$ matrix $A = (a_{ij})$ is

$$A^* = (a_{ji})$$
 .

▶ Definition The symmetric n × n matrices S, T in ℝ are orthogonally congruent if

$$T = A^*SA$$

for an $n \times n$ matrix A which is orthogonal, $A^*A = I_n$.

Spectral Theorem

(i) The eigenvalues of symmetric S are real.

(ii) Symmetric S, T are orthogonally congruent if and only if they have the same eigenvalues.

Sylvester's Law of Inertia

- Definition Let S be a symmetric n × n matrix in ℝ.
 (i) The positive index τ₊(S) ≥ 0 of S is the dimension of a maximal subspace V₊ ⊆ ℝⁿ such that S(x,x) > 0 for all x ∈ V₊ \{0}.
 (ii) The negative index τ₋(S) ≥ 0 of S is the dimension of a maximal subspace V₋ ⊆ ℝⁿ such that S(x,x) < 0 for all x ∈ V₋ \{0}.
- Definition Symmetric n × n matrices S, T are linearly congruent if

$$T = A^*SA$$

for an invertible $n \times n$ matrix A.

► Law of Inertia (1852) *S*, *T* are linearly congruent if and only if

$$(\tau_+(S), \tau_-(S)) = (\tau_+(T), \tau_-(T)).$$

The signature

▶ Definition The signature of a symmetric n × n matrix S in ℝ is

$$au(S) = au_+(S) - au_-(S) \in \{-n, -n+1, \dots, n-1, n\}$$

- ▶ The following conditions on *S* are equivalent:
 - S is invertible,

$$\tau_+(S) + \tau_-(S) = n$$

- the eigenvalues constitute a regular sequence $\lambda_* = (\lambda_1, \lambda_2, \dots, \lambda_n)$, i.e. each $\lambda_j \neq 0$.
- Proposition For invertible S

$$au(S) = \sum_{j=1}^{n} \operatorname{sign}(\lambda_j) = n - 2\operatorname{var}(\mu_*)$$

with $\mu_j = \lambda_1 \lambda_2 \dots \lambda_j$ $(1 \leq j \leq n)$ and $\mu_0 = 1$.

The principal minors and the Sylvester-Jacobi-Gundelfinger-Frobenius Theorem

▶ Definition The principal minors of an n × n matrix S = (s_{ij})_{1≤i,j≤n} in ℝ are the determinants of the principal submatrices S(k) = (s_{ij})_{1≤i,j≤k}

$$\mu_k(S) = \det(S(k)) \in \mathbb{R} \ (1 \leqslant k \leqslant n) \ .$$

For k = 0 set $\mu_0(S) = 1$.

Theorem (Sylvester (1853), Jacobi (1857), Gundelfinger (1881), Frobenius (1895))
 The signature of a symmetric n × n matrix S in R with the principal minors μ_k = μ_k(S) constituting a regular sequence μ_{*} = (μ₀, μ₁, ..., μ_n) is

$$\tau(S) = \sum_{k=1}^{n} \operatorname{sign}(\mu_k/\mu_{k-1}) = n - 2\operatorname{var}(\mu_*)$$

There is a proof in the survey, using "plumbing" of matrices.

The tridiagonal symmetric matrix

• **Definition** The tridiagonal symmetric matrix of a sequence $q_* = (q_1, q_2, ..., q_n)$ in \mathbb{R} is

$$\mathsf{Tri}(q_*) = egin{pmatrix} q_1 & 1 & 0 & \dots & 0 \ 1 & q_2 & 1 & \dots & 0 \ 0 & 1 & q_3 & \dots & 0 \ dots & dots & dots & dots & dots & dots \ dots & dots & dots & dots & dots \ dots \ dots & dots \ dots$$

Sylvester observed that every continued fraction is the ratio of successive principal minors µ_k = µ_k(Tri(q_∗))

$$\mu_k/\mu_{k-1} = q_k - \frac{1}{q_{k-1} - \frac{1}{q_{k-2} - \cdots - \frac{1}{q_1}}}$$

and $\tau(\operatorname{Tri}(q_*)) = \sum_{k=1}^n \operatorname{sign}(\mu_k/\mu_{k-1}) = n - 2\operatorname{var}(\mu_*).$

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Sylvester's mathematical inspiration

▶ For a Euclidean pair (p_*, q_*) the regular sequences $(p_0/p_1, p_1/p_2, ..., p_{n-1}/p_n)$ and q_* determine each other by

$$rac{p_{j-1}}{p_j} = q_j - rac{1}{q_{j+1} - rac{1}{q_{j+2} - \ddots}}, \ q_j = rac{p_{j-1}}{p_j} + rac{p_{j+1}}{p_j}$$

For his modification of Sturm's theorem Sylvester needed an expression for $\tau(\text{Tri}(q_*))$ in terms of p_* . He could not obtain it directly, so he reversed $q_* = (q_1, q_2, \ldots, q_n)$ to define

$$\begin{aligned} q'_* &= (q_n, q_{n-1}, \dots, q_1) \\ \text{with } \frac{p_{j-1}}{p_j} &= \frac{\mu_{n-j+1}(\operatorname{Tri}(q'_*))}{\mu_{n-j}(\operatorname{Tri}(q'_*))} \text{ and } \tau(\operatorname{Tri}(q'_*)) = n - 2\operatorname{var}(p_*). \\ \text{He then observed that } \operatorname{Tri}(q_*), \operatorname{Tri}(q'_*) \text{ are linearly congruent,} \\ \text{so that } \tau(\operatorname{Tri}(q_*)) &= \tau(\operatorname{Tri}(q'_*)) = n - 2\operatorname{var}(p_*). \end{aligned}$$

Sylvester's modification of Sturm

► Theorem (1853) For a Euclidean pair (p_{*}, q_{*}) = ((p₀, p₁,..., p_n), (q₁, q₂,..., q_n))

$$\tau(\text{Tri}(q_*)) = \sum_{k=1}^n \text{sign}(p_k/p_{k-1}) = n - 2 \operatorname{var}(p_*).$$

For regular $P(X) \in \mathbb{R}[X]$ and regular a < b with Sturm sequences $(P_*(X), Q_*(X))$ the number of real roots in [a, b] is

$$egin{aligned} &|\{x\in [a,b]\,|\, P(x)=0\in \mathbb{R}\}|\ &= ext{var}(P_*(a)) - ext{var}(P_*(b))\ &= ig(au(ext{Tri}(Q_*(b))) - au(ext{Tri}(Q_*(a)))ig)/2 \ . \end{aligned}$$

Proof of Sylvester's Theorem I.

► (i) The principal minors µ'_k = µ_k(Tri(q'_{*})) of the tridiagonal symmetric n × n matrix

$$\operatorname{Tri}(q'_{*}) = \begin{pmatrix} q_{n} & 1 & 0 & \dots & 0 \\ 1 & q_{n-1} & 1 & \dots & 0 \\ 0 & 1 & q_{n-2} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & q_{1} \end{pmatrix}$$

constitute a regular sequence $(\mu_1',\mu_2',\ldots,\mu_n')$ such that

$$\frac{\mu'_{j-1}}{\mu'_j} = \frac{p_{n-j+1}}{p_{n-j}} (1 \leq j \leq n) .$$

(ii) The signature of $Tri(q'_*)$ is

$$au({\sf Tri}(q'_*)) \;=\; n-2\,{\sf var}(\mu'_*) \;=\; n-2\,{\sf var}(p_*)\;.$$

Proof of Sylvester's Theorem II.

• (iii) The invertible $n \times n$ matrix

$$A = \begin{pmatrix} 0 & 0 & \dots & 1 \\ \vdots & \vdots & \ddots & 0 \\ 0 & 1 & \dots & 0 \\ 1 & 0 & \dots & 0 \end{pmatrix}$$

is such that

$$\operatorname{Tri}(q_*) = A^*\operatorname{Tri}(q'_*)A$$

so that by the Law of Inertia

$$au(\operatorname{Tri}(q_*)) = au(\operatorname{Tri}(q'_*)) = n - 2\operatorname{var}(p_*)$$
 .

Sylvester's musical inspiration

As an artist delights in recalling the particular time and atmospheric effects under which he has composed a favourite sketch, so I hope to be excused putting upon record that it was in listening to one of the magnificent choruses in the 'Israel in Egypt' that, unsought and unsolicited, like a ray of light, silently stole into my mind the idea (simple, but previously unperceived) of the equivalence of the Sturmian residues to the denominator series formed by the reverse convergents. The idea was just what was wanting,—the key-note to the due and perfect evolution of the theory.

A magnificent chorus from Israel in Egypt